Structure from Motion (SfM) - model referencing strategies

Entle (S9_5, S9_6)*

C1: GCPs, 2 level obl.
C2: weak GCPs, 2 level obl.
C3: GCPs, 1 level grid
C4: weak GCPs, 1 level grid
C5: no GCPs, 2 level obl.
C6: no GCPs, 1 level grid

Luetschine (L2), Kander (K1)

C1: GCPs, grid + 1 level obl.
C2: GCPs, grid only
C3: no GCPs, grid + 1 level obl.
C4: no GCPs, grid only

Camera orientation (oblique or nadir)
Camera position uncertainty (if used for referencing)
GCP with uncertainty (if used for referencing)
Surface
SfM model uncertainty
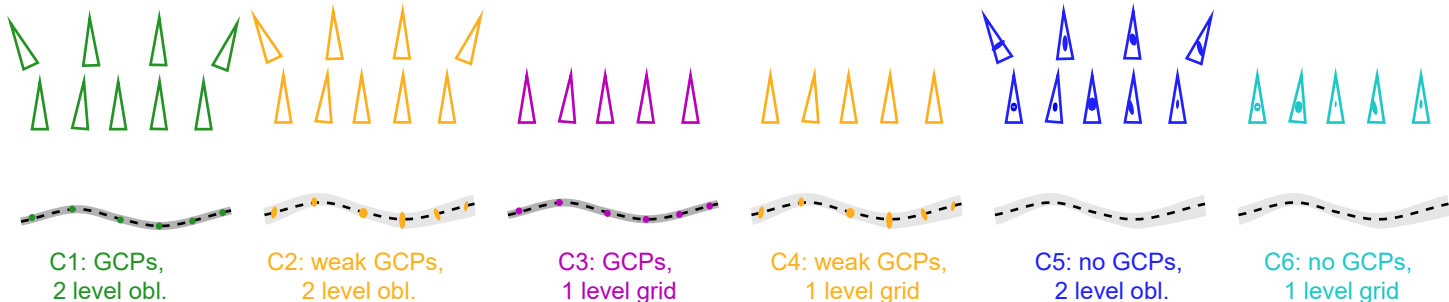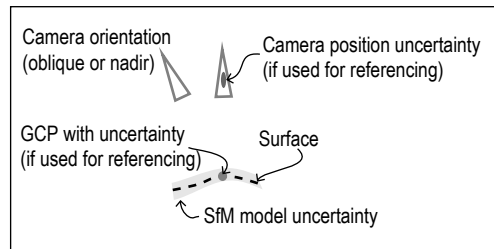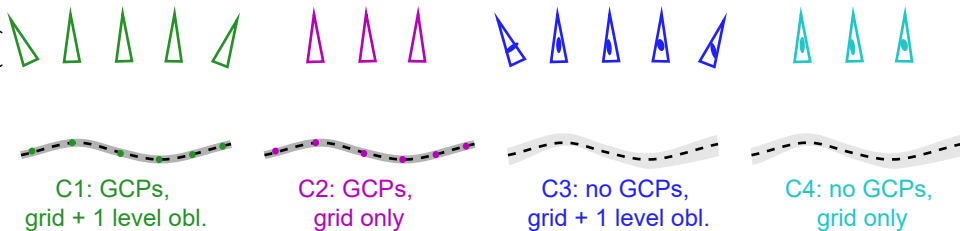
*two individual UAV surveys conducted with different image acquisition formats