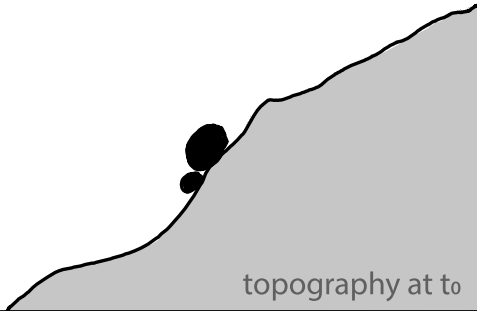


t_0 3D point cloud acquisition



t_0+x image acquisition

