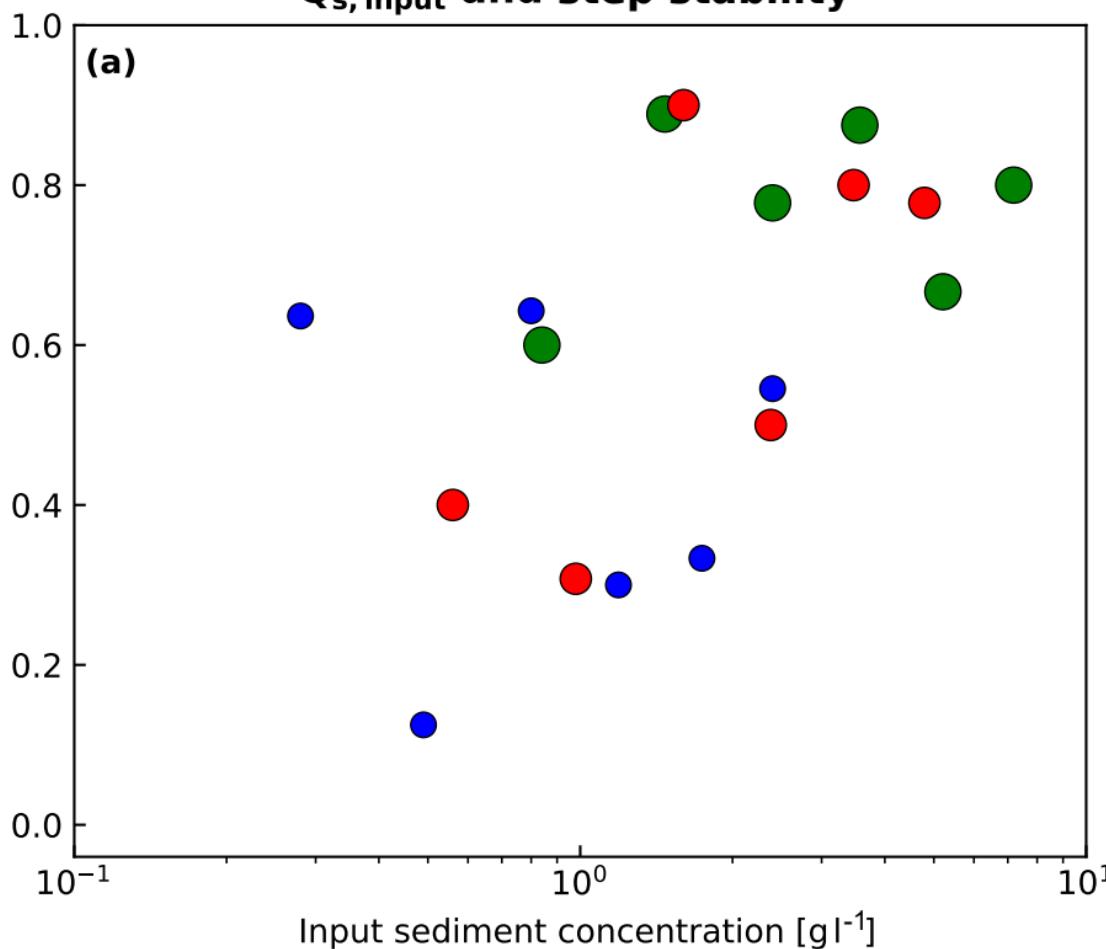


Q_s , input and step stability

Fraction of destroyed steps



Q_s , output and step stability

Fraction of destroyed steps

