Vertical movements of frost mounds in sub-Arctic

permafrost regions analyzed using geodetic survey and

3 satellite interferometry

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Abstract

- 17 Permafrost-affected soils cover about 450 45 % of Canada. The environment in such areas,
- 18 especially those located within the discontinuous permafrost zone, has been impacted more
- 19 than any other by recorded climatic changes. A number of changes, such as surface
- subsidence and the degradation of frost mounds due to permafrost thawing have already been
- 21 observed at many locations.
- We surveyed three frost mounds (lithalsas) in the sub-Arctic close to Umiujaq in, northern
- 23 Quebec, sub-Arctic, using a-high-precision differential Global Positioning System (d-GPS)
- technology during field visits in 2009, 2010 and 2011, thus obtaining detailed information on
- 25 their responses to the freezing and thawing that occurs during the course of the annual
- temperature cycle. Seasonal pulsations were detected in the frost mounds and these responses
- 27 were shown to vary with the state of degradation and the land cover. The most degraded
- 28 lithalsa showed a maximum amplitude of vertical movement (either up or down) between
- 29 winter (freezing) and summer (thawing) of 0.19±0.09 m over the study period, while for the
- least degraded lithalsa this figure was far greater (1.24±0.47 m). Records from patches areas

- with little or no vegetation showed far less average vertical movement over the study period
- 2 (0.17±0.03 m) than those with prostrate shrubs (0.56±0.02 m), suggesting an influence from
- 3 the land-cover.
- 4 A differential Interferometric Synthetic Aperature Radar (D-InSAR) analysis was also
- 5 completed over the lithalsas using selected TerraSAR-X images acquired from April to
- 6 October 2009 and from March to October 2010, with a repeat cycle of 11 days.
- 7 Interferograms with baselines shorter than 200 m were computed revealing a generally very
- 8 low interferometric coherence, restricting the quantification of vertical movements of the
- 9 lithalsas. Vertical surface movements of the order of a few centimeters in the centimeter range
- were recorded in the near vicinity of Umiujaq.

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1 Introduction

- Permafrost underlies 40 455% of Canada and is significantly affected by has a significant
- 14 effect on the global climate. Climate modelling suggests that increasing air temperatures are
- to be expected over the next 40 years, with a large increase expected in this area of up to 10°C
- during the winter months (Allard et al., 2007). Such elevated air temperatures will affect the
- soil temperature, which has been modelled to increase by about 4°C until by 2070 (Sushama
- et al., 2006). Such warming would increase thawing during the summer months leading to an
- increase in marshlands or wetlands and encouraging the formation of new lakes (Rowland et
- 20 al. 2010, Smith et al., 2004).
- 21 Characteristic landforms of the discontinuous permafrost zone, such as palsas and lithalsas
- 22 (Fig. 1 a), are also likely to suffer as a result of increasing soil temperatures, especially as the
- 23 ground temperature in these features is usually already >-2°C... Lithalsas are permafrost
- 24 mounds; they are typical of northern Quebec and Lapland and are formed by ice segregation
- in a similar manner to palsas. In contrast to palsas, however, lithalsas have no insulating cover
- of peat (Calmels, 2008; Zoltai and Tarnocai, 1975; Zuidhoff, 2002; Zuidhoff and Kolstrup,
- 27 2005), which makes them more sensitive to changes in temperature (Pissart, 2000; Seppälä,
- 28 1988). Lithalsas and palsas normally form low circular or oval features that are-about 5 m
- 29 high, 10-30 m wide, and up to 150 m long. The morphology of lithalsas and palsas are
- 30 normally low circular or oval features, around 5 m in height, 10-30 m in width and up to 150
- 31 m in length. The ice lenses of their permafrost cores are usually not thicker than 3 cm, but
- lenses up to 40 cm thick have been described (Gurney, 2001; Pissart, 2002). Their anticipated
- degradation with continued warming is likely to have severe direct and indirect consequences

- for the ecosystem, the hydrological regime, and the vegetation, and to ultimately also affect
- the human population (Nelson et al., 2003).
- 3 Changes in theto land surface within the area covered by this study (around Umiujaq in
- 4 northern Quebec) over recent years have been attributed to permafrost thawing. A number of
- 5 studies (e.g. Laberge and Payette, 1995; Fortier and Aubé-Maurice, 2008) have shown that
- 6 longer-and, warmer summer periods lead to result in degradation of these mounds, (and even
- 7 their disappearance) accompanied by a subsidence of the surrounding terrain.
- 8 Increasing temperature and pressure gradients in winter encourage the formation of
- 9 segregation ice and cause frost heave. During the thawing period the opposite occurs and
- 10 lithalsas subside (Skaven-Haug, 1959). Long-term climatic variations are expected to elicit
- 11 responses to changing air temperatures that are comparable to these annual changes. Calmels
- et al. (2008), for example, surveyed a lithalsa close to our own study area and recorded thaw
- settlement of 1 m over <u>a 5</u> year period.
- In this study we have investigated the seasonal dynamics of lithalsas on the eastern shore of
- Hudson Bay, in the Nunavik region of northern Quebec, Canada, using a differential system
- 16 (d-GPS) and satellite-based differential SAR interferometry (D-InSAR).
- 17 <u>DThe d-GPS technology</u> has been successfully used for a wide range of scientific
- applications, although its usehas only really been used for geocryological purposes only really
- started insince the mid-1990's. For example, Theakstone et al. (1999) generated used d-GPS
- 20 technology to generate maps and a DEM for a glacier in central Norway, stating claiming a
- vertical accuracy of 0.1 m, Kaufmann (1998) evaluated used d-GPS technology to evaluate
- 22 the stability of reference points on a rock glacier in the Austrian Alps, Tait and Moormann
- 23 (2003) found a-d-GPS technology to be the best approach for monitoring topographic
- movements in continuous permafrost regions, and Sheng Tait et al. (2004) and Tait et al.
- 25 (2005) used a-d-GPS technology to survey frost mounds within the continuous permafrost
- 26 zone. A number of research teams have also successfully used a-d-GPS technology to monitor
- 27 frost heave and thaw subsidence. For example, Little (2006), Little et al. (2003) and Nelson et
- al. (2001) collected d-GPS measurements in flat areas of northern Alaska, where they
- recorded heave and subsidence movements of up to 0.06 m. Shiklomanov et al. (2013) used a
- 30 d-GPS to quantify isotropic thaw subsidence in permafrost areas of northern Alaska, and Wirz
- et al. (2015) derived the temporal variability of mountain permafrost slopes using d-GPS
- 32 measurements.

In addition to field measurements, remotely-sensed radar data has also been used to detect 1 2 vertical movements in permafrost regions from space, by means of differential interferometry. Differential Interferometry Synthetic Aperture Radar (D-InSAR) uses the phase content of a 3 4 complex radar signal to detect land surface deformations by transforming the phase difference between two acquisitions into a displacement figure (e.g. Bamler and Hartl, 1998). Changes 5 of the order of centimetres, or even millimetres, can be observed depending on the sensor's 6 wavelength. Such an analysis requires at least two scenes of the area of interest, recorded by 7 the same sensor but at different times, and an appropriate digital elevation model (DEM). D-8 InSAR has mainly been used to detect large-scale deformations caused by earthquakes (e.g. 9 Yen et al., 2008) or by seismic and volcanic activities (e.g. Ge et al., 2008; Amelung et al., 10 11 2000), but it has also been used to monitor glacier velocity (e.g. Goldstein et al., 1993). The first extensive studies of permafrost thawing and freezing in the Arctic (North Slope of 12 13 Alaska) using D-InSAR were based on data from the ERS SAR sensor (C-band, 5.7 cm wavelength) (Liu et al., 2010; Liu et al., 2011). Data has also been available at a higher spatial 14 resolution since 2006 from COSMO-SkyMed (ASI, 2007), based on shorter wavelengths (X-15 band 3.6 cm), and since 2007 from the TerraSAR-X satellite (DLR, 2010). A number of 16 17 studies have since been initiated using TerraSAR-X data to investigate vertical movements caused by permafrost thawing within the Arctic region (Larsen et al., 2009; Larsen et al., 18 19 2011; Lauknes et al., 2010a; Lauknes et al., 2010b; Short et al., 2011; Short et al., 2014; 20 Strozzi et al., 2012). 21 Little is known about the surface movements of frost mounds (lithalsas), in particular about their responses to the freezing and thawing that occurs during the course of an annual 22 temperature cycle, or the relationship between these movements and the state of degradation 23 of the frost mounds or their vegetation cover. We therefore surveyed three lithalsas in the 24 Canadian sub-Arctic using d-GPS technology to obtain more detailed information. In order to 25 investigate the use and effectiveness of new and innovative technologies we also used D-26 InSAR data which, to the author's best knowledge, has not previously been used to investigate 27 this type of permafrost landform. We analyzed TerraSAR-X images acquired between April 28 29 2009 and October 2009 and between March and October 2010, with a repeat cycle of 11 days, from which we obtained valuable information concerning the possibility of using D-InSAR in 30 this kind of environment. 31

2 Study area description

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- 1 The study area covers about 60 km² and is located near the Inuit village of Umiujaq (56°33'
- 2 N, 76°33' W), close to the eastern shoreline of Hudson Bay in Nunavik, northern Quebec,
- 3 Canada (Fig. 2).
- 4 The study area is located in the transition zone between the sub-Arctic and the Arctic, where a
- 5 high sensitivity to climatic changes is expected making it an ideal region in which to conduct
- 6 a climate change impact study. The permafrost is mainly scattered sporadic (Fig. 2) and the
- 7 study area covers the northern timber line; the mean annual ground temperature (MAGT) at a
- 8 depth of 10 m is about -2.5°C (Smith et al., 2010).
- 9 There are currently only 60 to 80 frost-free days per year in the study area (Environment
- 10 Canada, 2004) and the annual average air temperature is about -5.5°C but, due to the
- 11 proximity of Hudson Bay, the region is characterized by high temperature variability
- throughout the year. From June until mid-December the climate has a maritime character with
- 13 little diurnal variation in temperature and moderate temperatures of about 8°C. In contrast,
- when Hudson Bay freezes over during the winter temperatures can reach to below -30°C due
- to continentality. In addition, the annual average wind speeds in this area are between 20 and
- 24 km/h (Gagnon and Ferland, 1967), resulting in wind-chill temperatures down to -60°C
- 17 (Environment Canada, 2004). The average annual precipitation is approximately 500 mm
- 18 (Phillips, 1984), of which 37% falls as snow (Environment Canada, 2004).
- 19 The study area can be divided into a coastal region with gently sloping topography and the
- 20 Lac-Guillaume-Delisle graben (Fig. 2). The two landscape units are separated by ridges of
- outcropping bedrock (consisting of volcanic sediments) known as 'Cuestas' (Kranck, 1951).
- 22 The entire study area is experiencing a heterogeneous post-glacial rebound that averages
- about 1.0 cm/year (Lajeunesse and Allard, 2003; Tait and Moorman 2003).
- Temperatures in the region around Umiujaq are expected to increase by up to 10°C over the
- 25 next 40 years, with the rate of increase expected to be highest during the winter months
- 26 (Allard et al., 2007). Such an increase in air temperature would have an impact on the soil
- 27 temperature, which would in turn be expected to increase by approximately 4°C by 2070.
- 28 These modelling results obtained by Sushama et al. (2006) suggest a significant future
- 29 deepening of the active layer, which would be likely to result in thaw-related settlement
- 30 (Calmels, 2008).

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3 Data and methods

- 1 The data used for this study consisted of information collected during field visits in 2009,
- 2 2010 and 2011, together with remotely sensed data acquired by the German TerraSAR-X
- 3 satellite. The *in-situ* measurements provided detailed information on the seasonal variations in
- 4 lithalsas at specific locations and were also used to validate the results obtained from analysis
- 5 of the remote sensing data. Table 1 shows the acquisition dates for the d-GPS and TerraSAR-
- 6 X data, as well as details the dates of the useable differential interferograms. Thaw depths
- 7 were also measured at the same time as the other field measurements were obtained, using a
- 8 <u>frost probe.</u>

3.1 Field data

- 10 The three lithalsas investigated (identified as I, R, and M) are located to the south-east of the
- community of Umiujaq (Fig. 3)
- They are each about 40 m in diameter and between 5 and 10 m high. They comprise a mixture
- of patches of bare ground and areas covered by lichens or prostrate shrubs, with their slopes
- being covered in small shrubs. A detailed soil map (1:10,000 scale) by Doyon et al. (2010)
- identifies the three features as ice-rich frost mounds ('Buttes cryogènes riche en glace').
- Lithalsas I and R lie within a zone of aeolian sediments dominated by sand, sandy silt, sandy
- 17 gravel and gravel ('Sable, silt sableux, sable graveleux et gravier'). Lithalsa M is further to
- 18 the south-east in an area of marine and littoral sediments consisting mainly of sand but
- including beds of heavy minerals and shell fragments ('Sable moven à grossier avec présence
- de lits de minéraux lourds et de fragments de coquillages'). Adjacent to the southern slope of
- 21 this lithalsa lies a poorly drained wetland area (Doyon et al., 2010).
- 22 The three lithalsas all exhibit clearly different states of degradation. A 220 m² pond on the
- eastern side of Lithalsa R provides evidence that this lithalsa is in the process of breaking up,
- 24 with additional evidence coming from the presence of numerous cracks and small-scale
- 25 | solifluction features (Fig. 1b). A pond has also formed on the <u>north-east-facing</u>_slope of
- Lithalsa M, but its dimensions are smaller (Fig. 3) and there are far fewer cracks than at
- 27 Lithalsa R. Degradation at Lithalsa M is therefore interpreted to be less advanced than at
- 28 Lithalsa R. There is, in contrast, no evidence of degradation at Lithalsa I, which has no pond
- and no visible cracks. Table 2 summarizes the characteristics of the three lithalsas.
- 30 Seven field visits were made between August 2009 and April 2011, covering the full range of
- seasons. The three lithalsas were surveyed using a ProMark 3 GPS from Magellan with a
- 32 NAP100-L1 antenna. <u>DThe d-GPS</u> technology allows accurate measurement of vertical
- 33 movements (at centimeter or even sub-centimeter scales) within a worldwide geodetic

coordinate system. This is achieved using normal code-based GPS technology, which acquires coordinate positions through triangulation by defining the interspace between at least four satellites and a receiver (UNVACO, 2006). This kind of GPS only has an accuracy of a few meters, but this is improved by using a differential system (d-GPS) equipped with at least two receivers. One of the two receivers serves as the base station: it has a known (fixed) position from which it tracks the satellites. The other receiver (the rover receiver) is placed at a particular point for only a limited period of time (usually between 15 and 60 seconds; http://www.trimble.com/gps_tutorial/). By comparing the signals from the two receivers at the same point in time, systematic errors, such as those due to atmospheric signal delays or the variations in the precision of the orbits, can be substantially reduced (Trimble, 2010). For this the "kinematic stop-and-go d-GPS method" (Berber et al., 2002) was used. Hofmann-Wellenhof et al. suggested that the best accuracy was achieved with this method if the phase ambiguities were resolved before starting the survey. This we achieved through the use of a static initialization process provided by Magellan in their initialization equipment. The numbers recorded by the d-GPS were stored in RINEX (Receiver Independent Exchange) format. The data were analysed using the GNSS Solution v3.10.07 post-processing software (Magellan), with the data being imported into the software and then processed by adjusting vectors in relation to a fixed control point received from the base station.

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> The records were analysed using GNSS Solution v3.10.07 post processing software, also from Magellan. Coordinates and elevations for the 39 measurement points (R1 - R12, M1 -M14, and I1 – I13) over the three lithalsas were determined in August 2009, March 2010, May 2010, August 2010, and April 2011. The base station was mounted, always mounded at the same location, about 500 m from the lithalsas, elose to at a marked trigonometric point on stable bedrock where changes in elevation caused by frost heave or thawing subsidence could be excluded. Unfortunately however, the original details of this trigonometric point could not be obtained, the trigonometric point could not be identified and, due to the remoteness of the study area no permanent reference station was available. Since this introduced the possibility of errors in the recorded position of the base station, the measured coordinates needed to be manually corrected for each record date before running the post-processing software. This correction was undertaken using the online service provided by the NRCan's Geodetic Survey Division (www.geod.nrcan.gc.ca/index_e.php) in which the recorded coordinates are submitted to the system, together with information concerning the processing mode and the reference system. The Precise Point Position (PPP) is then calculated based on the Canadian Spatial Reference System (CSRS) (Bisnath and Gao, 2009). The coordinates finally defined by the CSRS for the base station were 56.55° N and 76.54° E. These coordinates then served as a control point for the processing described above. Both horizontal and vertical uncertainties were calculated during post-processing. The horizontal error was found to be

- between 0.001 cm (Lithalsa M) and 0.098 cm (Lithalsa R), and the vertical error between
 0.001 cm (Lithalsa M) and 0.123 cm (Lithalsa I).-
- 3 The points on the three lithalsas at which measurements were to be recorded by the mobile
- 4 receiver were first selected in August 2009. It was important to ensure that they were located
- 5 within snow-free areas and in either non-vegetated patches or sparsely vegetated patches
- 6 (with lichens and/or prostrate shrubs). The selected points were marked with a metal-pin
- about 20 cm long, hammered into the ground and wrapped with pink tape.
- 8 The Magellan user's guide states that a vertical accuracy of "up to" 1.5 cm is attainable when
- 9 using a recording time of at least 15 seconds, and that this may be improved by using longer
- recording times. For this study a recording time of 60 seconds at each point was chosen and
- since there were no obstacles interrupting the signal this should ideally have resulted in an
- accuracy of several millimetres. However, because of the need to compute a correction for the
- coordinates of the base station (see details below), the vertical accuracy was reduced to within
- 14 a few centimetres (~ 5 cm).

3.2 Remote sensing data

- 16 In addition to the ground measurements, contemporaneous records from the TerraSAR-X
- satellite were also examined. Launched in June 2007, this satellite acquires high-quality X-
- band radar images with a spatial resolution of down to 1 m whilst circling the earth in a polar
- orbit at an altitude of 514 km. The frequency that the X-band sensor operates at is 9.65 GHz,
- 20 which corresponds to a wavelength of about 3 cm (DLR, 2010). Its repetition time is 11 days.
- 21 There are several acquisition modes available and we based our choice of the most suitable
- mode on coherence images computed from more than 30 images acquired in 2009 on different
- passes, at different polarizations, and with different angles of incidence. We considered only
- images acquired in the StripMap mode, scanning the surface with a footprint of 30 x 50 km
- 25 and a spatial resolution of about 3 m (Table 32), in order to obtain the best possible
- 26 compromise between maximum spatial resolution and maximum coveragein order to
- 27 compromise the best spatial resolution and the best coverage. Our investigations indicated that
- data from an ascending pass, in VV polarization and with an incidence angle of 40° was the
- 29 most suitable for the study (Spannraft, 2010; May, 2011). Interferograms computed from
- 30 winter acquisitions could not be considered, because snow influenced the radar signal
- resulting in too few coherences to process.
- 32 TerraSAR-X interferograms were computed using a 1-look in "range" and 1-look in
- 33 "azimuth", in order to achieve the best possible resolution over the lithalsas. A very high

- 1 resolution DEM was used for the differential interferometry, in a two-pass approach (Bamler
- and Hartl, 1998). The DEM was produced by the Direction de la cartographie topographique
- du ministère des ressources et de la faune à Québec (MRNF) from stereoscopic analysis of
- 4 aerial photographs, and has a spatial resolution of 1 m. GAMMA Software (GAMMA Remote
- 5 Sensing AG, 2008) was used for the processing and an area of 62000 x 25000 pixels defined
- 6 for the calculation of the differential iInterferograms. In order to support phase unwrapping
- 7 and as a measure of the quality of the interferograms, coherence was estimated using an
- 8 adaptable window from the 1-look differential SAR interferograms (Wegmüller and Werner,
- 9 1996). The coherence was first estimated using a fixed, relatively small window size of 15
- pixels. The window size was then determined from the irst estimate, applying successively
- larger windows up to 45 pixels in order to estimate lower coherence. This procedure enabled
- us to obtain reliable coherence values without compromising too much on the spatial
- 13 resolution.
- 14 The differential interferograms, which in their initial stage only contained information on the
- phase difference, were then unwrapped using the minimum cost flow algorithm in order to
- retrieve vertical displacement (Constantini and Rosen, 1999). The high resolution DEM was
- 17 also used for georeferencing.

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4 Results and discussion

4.1 Field measurements – differential GPS (d-GPS)

21 Results

- 22 The field measurements showed a similar pattern at most of the measurement points, with
- 23 88.9% of these points recording uplift during freezing periods (after August 2009 March
- 24 2010: average uplift 0.44 m; August 2010 April 2011: average uplift 0.11m) and subsidence
- 25 during thawing (March 2010 August 2010: average subsidence 0.46 m). The vertical
- 26 movements at those measurement points that did not conform to this pattern were small
- 27 (average: 0.1 m) compared to the average vertical movement of all points of 0.4 m between
- 28 August 2009 and April 2011.
- 29 Figure- 4 shows the heights of the lithalsa surfaces (both an average height for all three
- 30 lithalsas and separate heights for each lithalsa, averaged from all the relevant measurement
- 31 points) over the 20 month period relative to the height of the base station, measured on 6
- different dates (14.08.2009, 25.03.2010, 08.05.2010, 12.08.2010, 27.10.10, and 09.04.2011)
- and interpolated over the entire 20 month period. It should be pointed out that for October

- 2010 observations were only available from Lithalsa I due to the weather conditions that did
- 2 not allow further measurements.
- 3 The average heights (black bars) increase by 0.44 m between August 2009 and March 2010,
- 4 followed by a rapid decrease between March 2010 and May 2010 of 0.32 m, with a further
- 5 decrease of 0.14 m to August 2010, followed in turn by a slight increase of 0.10 m to April
- 6 2011. The difference between the highest average elevation (March 2010) and the lowest
- 7 average elevation (August 2010) was 0.47 m. Between March 2010 and May 2010 an average
- 8 subsidence across all lithalsas of 0.35 m was recorded, which represents 70.6 % of the total
- 9 subsidence over the entire year 2010. The subsequent average subsidence across all lithalsas
- between May 2010 and August 2010 was far less (0.12 m) even though the period was nearly
- 11 2 months longer.
- 12 These records clearly confirm the expected seasonal frost heave and thaw subsidence, and
- 13 also indicate that that these processes are not linear over the whole year: the frost heaving
- 14 during the freezing period (after August 2009 April 2010) was rather slow compared to the
- 15 rapid subsidence following the initial thaw in late April or May. The freezing process
- 16 therefore seems to operate much more slowly than the thawing process. The very minor frost
- heave observed during the 2010-2011 freezing period (average across all lithalsas: 0.04 m)
- 18 was not as pronounced as in the previous (2009-2010) freezing period. Possible reasons for
- 19 this difference are discussed later in this section.
- 20 The relative heights of the individual lithalsas (grey bars) all show similar trends but the
- 21 amplitudes of their vertical movements vary considerably: Lithalsa R shows the least
- variation in height over time (August 2009 April 2011), with the maximum recorded
- vertical movement being the subsidence of 0.19 m between March 2010 and August 2010. All
- 24 recorded vertical movements totaled over the entire period and averaged over all
- 25 measurement points on Lithalsa R amount to 0.48 m. The net movement of lithalsa R amount
- 26 to 0.06 m.
- 27 The maximum recorded vertical movement averaged across all measurement points on
- 28 Lithalsa M was 0.20 m (between May 2010 and August 2010), and the total vertical
- 29 movement (as for Lithalsa R) was 0.57 m. Lithalsa M reached its maximum uplift two months
- 30 later than the other lithalsas.
- 31 Lithalsa I showed much greater vertical movement over the year than the other lithalsas, with
- a dramatic peak in its relative height in March 2010 followed by a very rapid decrease to May
- 33 2010. The greatest vertical movement (1.24 m) occurred between August 2009 and March

- 1 2010, and the sum of all vertical movement (as above) over the entire period was 3.2 m.
- 2 Lithalsa I is the only lithalsa for which records are available from October 2010. The net
- 3 movement at <u>L</u>lithalsa I <u>is with(-0.01m) was</u> again less than <u>the net movement</u> at the other two
- 4 lithalsas.
- 5 Analyzing the measurements from individual measurement points (Fig. 3) reveals that the
- 6 smallest vertical movement occurred at a point on Lithalsa R (R3), which had less than 0.2 m
- 7 total movement over the 20 months period. The largest vertical movements (i.e. the
- 8 summations of all movements at each location of over the 20 month period) occurred on
- 9 <u>at Lithalsa I</u>, at I4 (5.7 m) and I5 (6.0 m) <u>on</u>. <u>Lithalsa I</u>. These high numbers on Lithalsa I are
- largely due the rapid subsidence that occured between March and May 2010. Observations
- 11 from the R12 point indicate continuous subsidence during this period. This behavior is
- probably due to the location of R12 on at the outer slope of the lithalsa (Fig. 3), where
- advanced degradation is evident in the form of cracks and solifluction occurs.
- 14 Taking into account the different trends over the 20 month period as well as the behavior at
- the individual measurement points, it is clear that Lithalsa I was the most dynamic lithalsa
- over the observation period, while Lithalsa R was the least dynamic. Lithalsa I was not only
- the most dynamic at all of the measurement points but also showed the greatest amount of
- variation between the measurement points. Hence, as far as the seasonal behavior of the frost
- mounds is concerned, the lithalsa with the least evidence of degradation (Lithalsa I) is the
- 20 most active of the three lithalsas while Lithalsa R, which shows the most advanced signs of
- 21 degradation, is the least active.

- Discussion
- 24 The records clearly confirm the expected seasonal frost heave and thaw subsidence and reveal
- a correlation between a lithalsa's degradation and its seasonal variations. They also indicate
- 26 that that these processes do not operate in a linear manner over the whole year: the frost
- 27 heaving during the freezing period (starting after August 2009) was rather slow compared to
- 28 the rapid subsidence that followed the initial thaw in late April or May. The freezing process
- 29 therefore seems to operate much more slowly than the thawing process. The very minor frost
- 30 heave observed during the 2010-2011 freezing period (average across all lithalsas: 0.04 m)
- was not as pronounced as that observed during the previous (2009-2010) freezing period.
- 32 Our results all conform to the expected seasonal variations in the elevation of lithalsas over
- 33 the course of a year; they also reveal the correlation between a lithalsa's degradation and its
- 34 seasonal variations. However, the relatively small amount of uplift in all three lithalsas

between the fall of 2010 and April 2011 requires some explanation. The possibility of early 1 thawing in 2011 having already resulted in any subsidence by April can be discounted as air temperatures were still well below 0°C (the average air temperature for January to April, 2011 was -16°C; CEN, 2013). There are, however, two other possible explanations: (i) maximum thawing had probably not yet been reached in August 2010, which would mean that the lithalsas were still in the process of subsiding (as suggested by the observations from Lithalsa I in October 2010, which show further subsidence of 0.03 m since August 2010), and (ii) the late initiation of freezing in 2010, when air temperatures did not drop permanently below 0°C until the 17th of November which is almost one month later than in 2009 (20thOctober: CEN, 2013), is likely to have delayed the uplift process, which was therefore possibly not yet 10 11 completed in April 2011. A detailed analysis of each individual measurement point yielded additional information: the

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low average increase in elevation recorded between August 2010 and April 2011 is due to 35% of the measurement points actually experiencing subsidence rather than elevation. Five of these points in particular (R6, R9, R11, M4, and M13) showed a great deal of subsidence (averaging -0.19 m) and were therefore largely responsible for the low average uplift. The seasonal uplift (frost heave) trend is thus dampened by just 13% of the measurements that exhibit high counter-trends (i.e. subsidence). If these 5 points are ignored the average uplift amounts to almost 0.1 m.

In order to better understand the behavior at individual measurement points we also took into account the vegetation and noted that 93% of the subsiding points were either vegetation-free or covered only with a smallfew patches of amount of lichen. Thirteen of the fourteen measurement points that recorded subsidence between August 2010 and April 2011 also experienced below-average frost heave in the preceding winter of 2009-2010. Overall, 85% of the points with below average least uplift were either mostly covered with lichen or nonvegetated. Those measurement points with above average uplift (>61% of all measurement points in the winter of 2009/2010 and >83% of all measurement points in the winter of 2010/2011) were covered with prostrate shrubs. A similar observation can be made for the summer thawing process (May 2010 – August 2010): 78% of the points with below average subsidence (14 out of 39) were either covered with lichen or non-vegetated, while (88%) of the points experiencing with above average subsidence (25 out of 39) were covered with prostrate shrubs. Between March 2010 and May 2010 none of the non-vegetated or lichencovered measurement points showed above-average subsidence, but most (80%) of these points showed either continuing uplift or minor subsidence. Patches Areass with prostrate

- shrubs therefore clearly start to subside earlier than those with little or no vegetation. In view
- of the weather in the spring of 2010, temporary early thawing is a real possibility as there had
- 3 already been 17 days, with temperatures of up to 6°C (reached on 31st March 2010; CEN,
- 4 2013), before the survey was conducted (8th of May, 2010).
- 5 The lower overall dynamics at non-vegetated measurement points is not surprising since the
- 6 records of the active layer than depths in during the same year (2010) indicate that non-
- 7 vegetated areas had very $\frac{\text{thin-shallow}}{\text{shallow}}$ ($\leq 5-60$ cm) thaw depths in the summer (August)
- 8 compared to patches areas covered with shrubs or trees, where the thaw depth was -up to 200
- 9 <u>m</u> (Beck et al., 2015). This is due to the absence of any insulation during the winter (i.e. no
- insulating cover of either vegetation or snow), resulting in lower ground temperatures (e.g.
- 11 Beck et al. 2015; Clebsch and Shanks, 1968; Mackay, 1974; Romanovsky and Osterkamp,
- 12 1995; Nelson et al., 1997). It can therefore be assumed that subsidence at these points starts
- much later than elsewhere. The relationships between the different vegetation types and the
- changes in elevations changes is are shown in Figure. 5.
- 15 Both the vegetation and the snow cover influence the thermal regime of the ground. However,
- since frost mounds are exposed features in the landscape any snow cover is usually quickly
- 17 removed by the wind and they are commonly almost frost free (Fig. 6). The influence of snow
- cover on the mounds has therefore not been included in this study.
- 19 4.2 Remote sensing Delifferential Interferometry Synthetic Aperture Radar (D-
- 20 InSAR)
- 21 Results
- Out of the 11 TerraSAR-X acquisitions in 2009 and 2010, only six interferograms showed a
- reasonable coherence with coherence values greater than about 0.25 computed over the whole
- area of interest (i.e. 0.23 for the 7 May/14 August 2009 image pair, 0.40 for the 14 August/30
- 25 August 2009 pair, 0.29 for the 14 August/30 October 2009 pair, 0.27 for the 5 May/12 August
- 26 2010 air, 0.53 for the 12 August/28 August 2010 pair, and 0.28 for the 12 August/28 October
- 27 2010 pair). All other interferograms were much less correlated. Areas covered by water
- bodies, vegetated areas, and pixels located within shadows are particularly affected by
- 29 decorrelation with coherence values below 0.3, while built-up areas are by far the most
- 30 coherent class, with coherence values greater than 0.9. However, although the average
- 31 coherence value from the six interferograms is high enough for generalised further analysis
- 32 (Carballo and Fieguth, 2002; Hanssen, 2001), the coherence values over the three lithalsas

(Table 4) is too low to be considered adequate for further analysis. In this case, if phase unwrapping is performed without using a coherence threshold it will yield phase values approaching zero, which would be typical of noisy regions. However, these values show no correlation with the large displacements measured using d-GPS technology and have therefore not been subjected to any further analysis.

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Discussion

Decorrelation in the TerraSAR-X differential interferograms over the lithalsas (Fig. 7a) is not surprising considering the large, rapid, vertical movements (several decimeters in less than half a year) measured using d-GPS technology (Zebker & Villasenor). There are also large variations in movement within each of the lithalsas. Amplitudes of several decimeters in lithalsa movements were recorded over less than half a year, with variations of several centimeters between individual measurement points within each of the lithalsas (which are only about 40 m in diameter); these amplitudes far exceed the the range that can be quantified with TerraSAR-X data, where a phase cycle corresponds to 1.6 cm and the time interval between acquisitions is, at best, 11 days. Decorrelation due to large displacements resulting from freeze-up processes has also been identified by Short et al. (2011), when they tried to coregister TerraSAR-X and RADARSAT-2 data from Herschel Island, acquire in May, October and November. The possibility of temporal decorrelation associated with the land cover type can be discounted because the lithalsas have only very sparse vegetation cover, or none at all, as is also the case in surrounding areas that are characterized by much higher coherence values (Fig. 7b). Changes in the dielectric properties (soil and vegetation moisture) can also influence both the coherence and the phase (Barrett et al., 2012). However, investigations in Canadian permafrost regions (Pangnirtung and Iqaluit) by Short et al. (2014) examined the influence of soil moisture and found that it was unlikely to be a significant source of error Nevertheless the six differential interferograms reveal two interesting large scale signals. Firstly, to the north of Umiujaq (56°33.6' N, -76°32.94'E) fringes increase with time and may be an indication of localized slow movements in a rocky area with only sparse vegetation (such as lichens and mosses). A corner reflector was fixed on solid rock in this area by INRS for a RADARSAT-2 study, oriented for a descending orbit. The signal in the TerraSAR-X interferograms could be related to localized movement of the corner reflector, to the displacement of terrain relative to the corner reflector, or to thermal dilation associated with the structure on which the corner reflector is located. It is not possible to make any further interpretations concerning the cause of the detected movement without additional local

information. Secondly, to the west of the lithalsas (around 56°33.18'N, -76.30.96'E), 1 2 widespread slow movements can be identified over the 11 day period from 14 to 23 August 2009. This area is part of the Cuestas (solid rock) but land cover classifications based on an 3 IKONOS image (2005) and a GeoEye image (2009) show vegetated patches with prostrate 4 5 shrubs (May, 2011), interspersed with temporary pools of water. Following the signals from the differential interferogram are therefore very likely to be associated with temporary 6 7 ponding. This interpretation is supported by the precipitation records: 63% of the total precipitation for August (total: 64.4 mm) fell between the two acquisition dates (i.e. between 8 14.08.2009 and 30.08.2009), whereas it was very dry (only 5.8 mm precipitation) over the 9 seven days prior to the first acquisition. 10

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5 Conclusion

The dD-GPS records measurements have confirmed the expected vertical movements of lithalsas relatively to the <u>surrounding</u> unfrozen <u>environment groundaround them.</u> The average uplifts during the two freezing periods (winter 2010 and winter 2011) measured with using d-GPS technology are were 0.4 m and 0.1 m. The average measured subsidence during the thawing period (summer 2010) is was 0.5 m. The results also indicate different patterns of behavior for each of the three lithalsas, reflecting their degradation status: maximal movements were recorded for the less least degraded lithalsa (21% above the average) and minimal movements were recorded for the most degraded lithalsa (40% below the average). With regard to the vegetation cover, patches with prostrate shrubs cover experienced greater uplift and subsidence than those with little or no vegetation. The amount of movements also showsindicates that permafrost features in this region are currently undergoing active degradation. Furthermore, the results and interpretations from our research using d-GPS technology in sub-Arctic permafrost regions will have important implications for planning the use of D-InSAR in such regions, and for interpreting the results obtained. Furthermore the d-GPS implications and experiments in sub-Arctic permafrost regions and the achieved results are very important for the planning of D-InSAR experiments and the understanding of D-InSAR in sub-Arctic regions. As Since in-situ subsidence data in-from this-such environments is very rare, D-InSAR analysis is often performed without a-priori knowledge. However Though, these movements could not be detected with D-InSAR due to decorrelation. It could be shown that IL arge displacements can occurhave been shown to be possible, which makes the application of D-InSAR in this such regions very challenging. This became evident by as

<u>a result of</u> capturing the <u>lithalsas</u>' dynamics <u>of lithalsas</u> in the differential interferograms based on the X-band data <u>of-from</u> TerraSAR-X.: This investigation therefore revealed the limitations of-<u>D-InSARthis method</u>, <u>as-since</u> the range of movements (several cm) could not be represented in the D-InSAR products. However, slow movements could be identified in the general vicinity, to the north of Umiujaq and east of the lithalsas. These findings are of <u>high</u> <u>considerable</u> importance as they confirm the usability of D-InSAR based on X-band to detect vertical dynamics in sub-Arctic regions.

Author contributions

I. Beck was responsible for the design of the experiments, the field work, <u>and</u> the generation of the D-InSAR products, as well as <u>for</u> the analysis and interpretation of the results. R. Ludwig and M. Bernier <u>were supervising supervised</u> her work and <u>assisted provided assistance</u> her during the study. S. Tazio was supported the preparation of the D-InSAR products and the analysis. J. Boike was responsible for the interpretation of the permafrost processes. All co-authors have supported I. Beck <u>with in</u> the preparation of the manuscript.

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- 13 differential interferograms considered in this study

- Table 1. Acquisition dates for the d-GPS and TerraSAR-X data and details of the useable
- 19 differential interferograms considered in this study.

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	D-GPS	TerraSAR-X acquisition dates	Detailed dates of useable interferograms			
Year	acquisition dates		Dates	Temporal baseline [d] *	Perpendicular baseline [m] **	
	20.04	07.05	07.05 / 14.08	99	125.36	
	14.08	14.08				
2009		25.08	14.08 / 25.08	11	-66.79	
		27.09				
		30.10	14.08 / 30.10	55	12.78	

	25.03	22.03			
	08.05	05.05	05.05 / 12.08	99	0.43
2010	12.08	12.08			
		23.08	12.08 / 23.08	11	-159.00
	27.10	28.10	12.08 / 28.10	77	-195.41
2011	09.04				

^{*}time delay between the aquisitions

	<u>Lithalsa R</u>	<u>Lithalsa M</u>	<u>Lithalsa I</u>
Diameter [m]	<u>40</u>	<u>40</u>	<u>40</u>
<u>Soil</u>	Aeolian sediments	Marine and littoral	Aeolian sediments
	(Sand, silt, gravel)	<u>sediments</u>	(Sand, silt, gravel)
		<u>(sand)</u>	
<u>Vegetation</u>	Bare ground, lichens,	Bare ground, lichens,	Bare ground, lichens,
	prostrate shrubs	prostrate shrubs	prostrate shrubs
<u>Ponds</u>	Ca. 220 m² at east	Ca. 65 m ² at north	_
	<u>slope</u>	<u>slope</u>	
Degradation status	Advanced cracks	Cracks visible	_
	<u>visible</u>		

Table 2. Characteristics of the three lithalsas

3

- 4 Table <u>32</u>. Characteristics of the TerraSAR-X sensor and the acquisition mode used for this
- 5 study (based on CAF, 2009)

Spatial resolution:		Acquisition mode:		
Swath width	Swath width ~ 15 km		Stripmap	

^{**}separation in meters between two antenna positions

Slant range resolution	1.2 km	Polarization mode	Dual (VV)*	
Ground range resolution		Pass & look direction	Ascending/ Right	
- Incidence angle: 40°	1.8 m	Product type	SSC**	
Range pixel spacing	0.9 m	Local acquisition time	6.46 pm	
Azimuth pixel spacing	2.5 m	Processing level	L1B	
*VV: vertical/ vertical **SSC: Single Look Slant Range Complex				

Table <u>43</u>. Average coherence over the three lithalsas for the six interferograms

	2009			2010		
	_		_	12.08_ 05.05	23.08	12.08_ 28.10
Lithalsa R	0.17	0.18	0.24	0.10	0.20	0.215
Lithalsa M	0.14	0.20	0.14	0.13	0.19	0.15
Lithalsa I	0.12	0.34	0.154	0.13	0.46	0.10

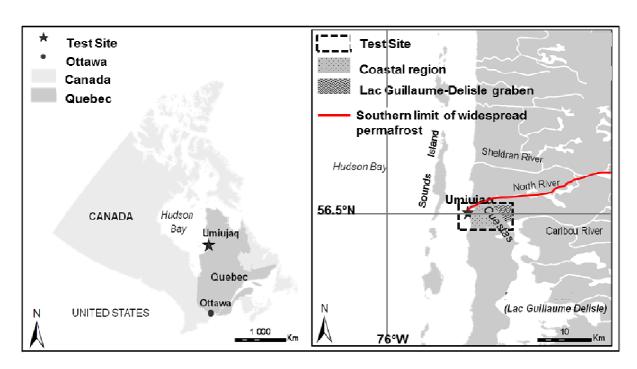
3



Figure 1A. One exemplary A typical lithalsa within the study area near, Umiujaq (,-northern Quebec), with a diameter of 20 m. The picture has been Photo taken in April 2009, to the east of the Cuestas (56°33'N 76°28' W)

Figure 1B. Thermokarst pond and eroding slope on Lof-lithalsa R.

Figure 1C. Cracks up to 0.5 m deep at on slope of Llithalsa R. They are up to 0.5 m high.



4 Figure 2. Location of the study area in the vicinity of Umiujaq, northern Quebec, Canada

- 5 (left), and the distribution of the two main types of landscape types (right): the coastal region
- 6 to the west of the Cuestas and the Lac Guillaume-Delisle graben to the east of the Cuestas.

- 1 The approximate boundary between widespread discontinuous permafrost to the north and
- 2 scattered sporadic permafrost to the south (based on Allard and Séguin, 1987) is shown in red.

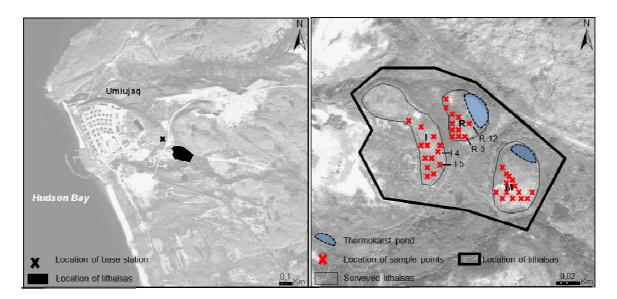


Figure 3. Left: location of the surveyed lithalsas and the base station, south-east of Umiujaq (background: GeoEye image from 25.09. 2009). Right: enlargement showing the three lithalsas (I, R and M) and the locations of the individual measurements points. The identified measurement points (R3, R12, I4, I5) are specifically discussed in Section 4.

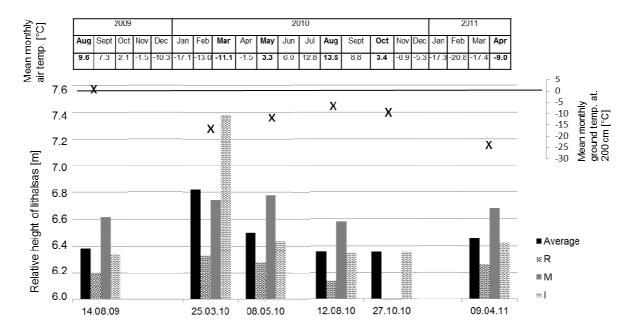


Figure 4. Heights of the three lithalsas (grey bars) and the<u>ir</u> average <u>of their</u> heights (black bars), relative to the base station, on the 6 measuring dates spread over a 20 month period. The heights represent the average of heights from all measurement points within each individual lithalsa. The accuracy of the records amounts to several centimeters The records are

accurate to within a few centimeters. The lithalsas were not covered by snow during the measurements. The temperatures at the top are the mean monthly air temperatures of the specific—year provided—year provided (CEN, 2013). Temperatures written in bold are for the month with d-GPS measurements.

by Environment Canada (2004).

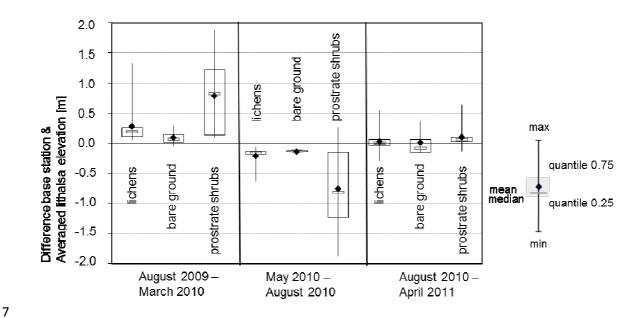
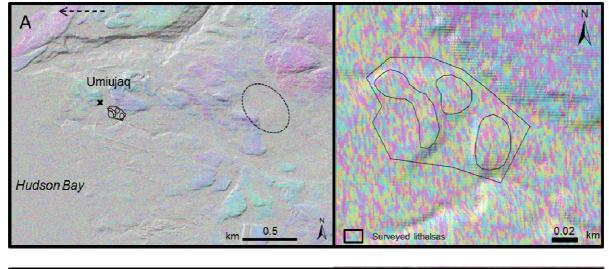
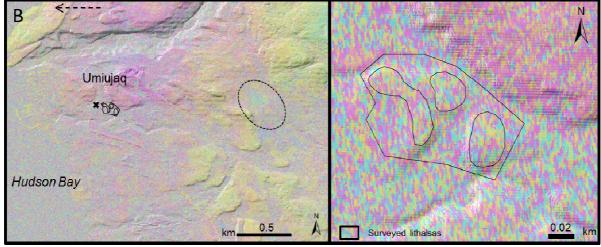


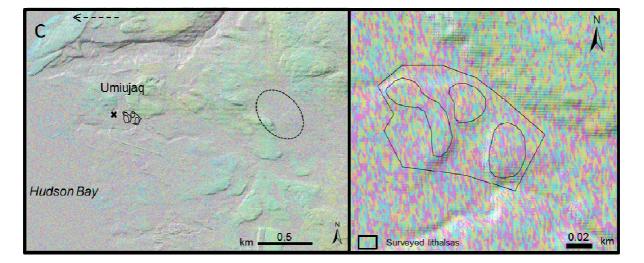
Figure 5. Box plots of surface cover and elevation changes for the three lithalsas, measured between August 2009 and March 2010, between May 2010 and August 2010, and between August 2010 and April 2011, based on all 39 measurement points on the three lithalsas.



Figure 6. Photo taken in April 2010 showing sparse snow cover on the lithalsas (Lithalsa M in this case) during the field visits.







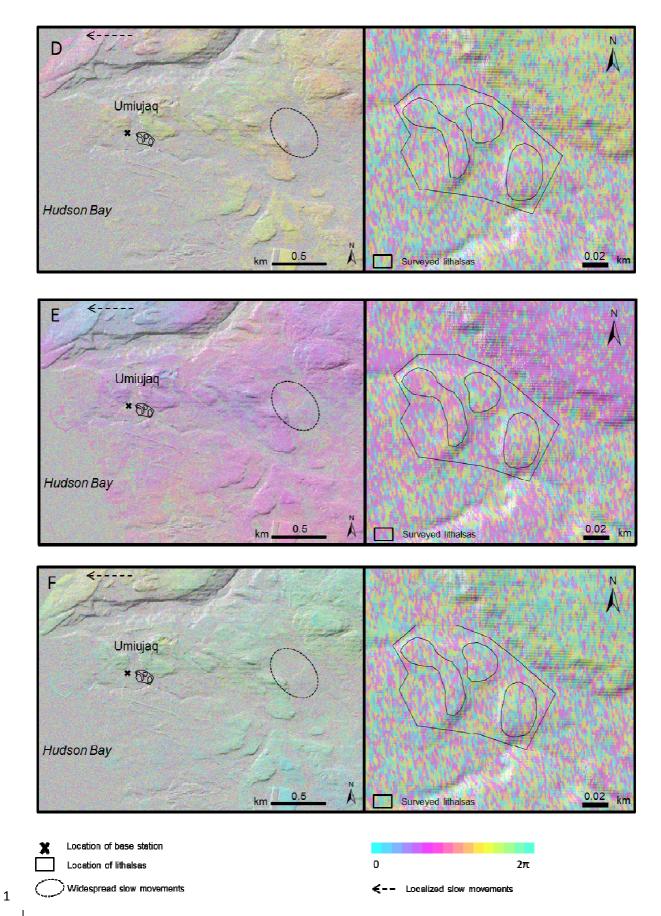


Figure 67a. The six interferograms (A: 14.08.09-07.05.09, B: 14.08.09-25.08.09, C: 14.08.09-30.10.09, D: 12.08.10-05.05.10, E: 12.08.10-23.08.10, and F: 12.08.10-28.10.10). Left: broad

- 1 area around Umiujaq, northern Quebec, Canada. The dashed arrow to the north of Umiujaq
- 2 indicates the fringes of slow movements; the dotted circles indicates the area of signals to the
- as east of the lithalsas. Right: the area of covering the three lithalsas of interest; the amount of
- 4 movement exceeds the amount that can be quantified with TerraSAR-X data.

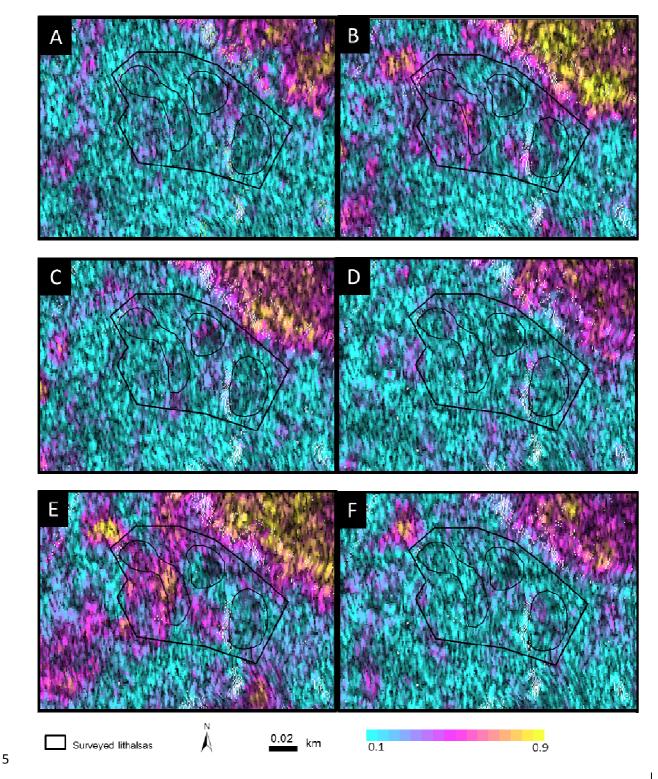


Figure 67b. The coherence values of the six interferograms in the area of the three lithalsas of interest, near Umiujaq, northern Quebec, Canada (A: 14.08.09-07.05.09, B: 14.08.09-

- 1 25.08.09, C: 14.08.09-30.10.09, D: 12.08.10-05.05.10, E: 12.08.10-23.08.10, and F: 12.08.10-
- 2 28.10.10)