



1 **Earth's surface mass transport derived from**
2 **GRACE, evaluated by GPS, ICESat, hydrological**
3 **modeling and altimetry satellite orbits**

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5

6 **ABSTRACT**

7 The Gravity Recovery and Climate Experiment (GRACE) delivers the most accu-
8 rate quantification of global mass variations with monthly temporal resolution on
9 large spatial scales. Future gravity missions will take advantage of improved mea-
10 surement technologies such as enhanced orbit configurations and tracking systems as
11 well as reduced temporal aliasing errors. In order to achieve the latter, sub-monthly
12 to daily innovative models are computed. In addition, non-conventional methods



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13 based on radial basis functions (RBF) and mascons will give the ability to compute
14 models in regional and global representation as well. The present study compares
15 for the first time a complete global series of solutions obtained by the RBF method
16 with conventional solutions in order to quantify recent ice-mass changes. We further
17 compare the ice-induced crustal deformations due to the dynamic loading of the
18 crustal layer with the Global Positioning System (GPS) uplift measurements along
19 Greenland's coastline. Available mass change estimates based on ICESat (Ice, Cloud,
20 and land Elevation Satellite) laser altimetry measurements both in Greenland and
21 Antarctica are used to assess the GRACE results.

22 A comparison of GRACE time series with hydrological modeling for various basin
23 extensions reveals overall high correlation to surface and groundwater storage com-
24 partments. The forward computation of satellite orbits for altimetry satellites such
25 as Envisat, Jason-1 and Jason-2 compares the performance of GRACE time variable
26 gravity fields with models including time variability, such as EIGEN-6S4.

27 **Key words:** GRACE – Radial basis functions – Kalman filtering – GPS deforma-
28 tion – Time-variable gravity field – Altimetry satellite orbits

29 1 INTRODUCTION

30 Since 2002 the Gravity Recovery And Climate Experiment (GRACE), Tapley et al. (2004)
31 has been measuring temporal variations of Earth's gravitational field highly accurately. These
32 data provide valuable information on the distribution and variation of mass in the Earth's sub-
33 systems such as the atmosphere, hydrosphere, ocean and the cryosphere. The latest GRACE
34 time-series of monthly gravity field solutions are computed in terms of spherical harmonic
35 model coefficients at the German Research Centre for Geosciences (GFZ), version RL05a,
36 University of Texas/Center for Space Research (CSR), version 05 and Technical University
37 Graz, Institute of Geodesy (ITSG) version 2016. They show significantly less noise and spu-
38 rious artifacts compared to their predecessors.

39 The Earth observation mission GRACE provides the only way to estimate groundwater
40 storage changes on a global scale and in remote areas. Moreover, in order to gain further
41 access to mass transport of short appearances, regional solutions in areas of strong anomalous
42 signals need to be developed and new methods for their computation have to be investigated.

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43 One candidate approach in this aspect is the transformation of the measurement data to
44 in-situ (proxy) gravity observables with subsequent inversion and continuation by means of
45 rigorous integral equations (Novák 2007). This non-conventional approach for the analysis
46 of GRACE inter-satellite range observations, processed in combination with best knowledge
47 reduced dynamic GRACE orbits has been elaborated in Gruber et al. (2014) and a detailed
48 theoretical foundation of the method is presented in (Gruber et al., submitted to GJI). In
49 brief, the transformed observations are first reduced by available geophysical background
50 models and subsequently inverted as well as downward continued by a rigorous formulation in
51 terms of reproducing kernel functions. Then, time-variable gravity field anomaly maps with
52 respect to the subtracted background data have been derived. The observation equations are
53 solved in spatial representation and are well suited for Kalman filtered solutions as covariance
54 information is not required in spectral domain and can be applied to regional and insular
55 domains only. This gives the opportunity to enhance the temporal resolution towards sub-
56 monthly (weekly or daily) time series and to advance into local domains, thereby preserving
57 the accuracy that is achieved from the standard monthly inversions.

58 A Kalman filter to derive daily gravity field solutions, first applied to GRACE data by
59 (Kurtenbach et al. 2009; Kurtenbach et al. 2011), has been applied by us to the transformed
60 GRACE gradient data. The main features are a stochastic process model for the data pre-
61 diction step and the conversion of the range measurements to in-situ gravity observations.
62 Standard integral equations are then used to solve for the gravity variations on surface grid
63 tiles (Gruber et al. 2014). The applied Poisson kernel function thereby isotropically localizes
64 the signal in spatial domain in contrast to a localization in spectral domain where global
65 multi-pole moments (spherical harmonic coefficients) are estimated.

66 During least squares prediction, the surface grid tiles for the following day are recursively
67 computed from the previous day and consecutively updated by the LIB observations in the
68 Kalman gain. It should be noted that these solutions are constrained in two aspects. Firstly,
69 by the applied background modeling that has been derived from available monthly GRACE
70 solutions and trends as well as annual signal estimates thereof. Secondly, by the stochastic
71 modeling of additional atmospheric and hydrological signal variations derived from geophys-
72 ical models. It is therefore not necessary to post-filter the results as they do not exhibit
73 GRACE-like anisotropic artifacts from the subsequent data inversion. Despite the regularized
74 processing methodology, the system is well capable of capturing hydro-geophysical signals in
75 their respective amplitudes.

76 First numerical results obtained using this method and their comparisons to standard



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77 GRACE products were presented in (Dahle et al. 2016) and have been significantly enhanced
78 since then. In this article we discuss the following evaluation methods with our latest results:

- 79 (i) Continental uplift rates from the Greenland GPS Network (G-NET) and Center for
80 Orbit Determination in Europe (CODE)
- 81 (ii) Ice mass balances from ICESat
- 82 (iii) Hydrological basin comparison against the WaterGap hydrological model (WGHM)
- 83 (iv) Altimetry satellite orbits: Satellite Laser Ranging (SLR) and Doppler Orbitography and
84 Radiopositioning Integrated by Satellite (DORIS) observation fits and arc overlaps

85 **2 GREENLAND AND CONTINENTAL GPS-SITES COMPARISON**

86 A significant spread of ice mass loss into northwest Greenland has been observed by GRACE
87 and GPS during recent years (cf. Khan et al. 2010). We make use of monthly averaged ver-
88 tical GPS site displacements from the Greenland GPS Network (G-NET), led by Ohio State
89 University's division of Geodetic Science. G-NET is a network of 46 continuous GPS stations,
90 installed on bedrock, spread across Greenland. We compare them with the crustal deforma-
91 tions inferred from post-filtered monthly GRACE gravity fields of ITSG2016 (Mayer-Gürr et
92 al. 2016), GFZ Release 5a (Dahle et al. 2012), CSR Release 5 (Bettadpur et al. 2012) and
93 the monthly averaged solutions derived from spherical radial basis functions (GFZ RBF). It
94 should be noted that GPS site data are point values, whereas the GRACE solutions stem
95 from area integrals. While this doesn't exclude direct comparison between the two data sets,
96 insular discrepancies can be expected.

97 The simultaneous use of GNSS and GRACE data is a subject that has already been
98 discussed in detail in the geodetic literature (e.g. Kusche and Schrama 2005, van Dam et
99 al. 2007). The aforementioned publications focus on the comparison between the GPS and
100 GRACE products, in terms of the regional or global mass distribution and/or the vertical
101 displacements respectively.

102 We firstly complete all models with a center of mass to center of figure translation (de-
103 gree 1, following Swenson et al. 2008). Changes in the ocean mass cause an offset between
104 the center-of-mass and the center-of-figure frame, commonly denoted as geocenter motion.
105 Briefly, any natural and anthropogenic water mass re-distribution at Earth's surface causes
106 changes in global ocean mass. Net-inflow of fresh water and exchange between ice and wa-
107 ter are typical phenomena that affect eu-static sea-level variability. The changes are reflected
108 in the geocenter motion (degree 1) and are non-negligible for the GRACE mission. Since the

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109 global eu-static sea-level variations are excluded from the de-aliasing model they can therefore
110 be derived empirically from the gravity field solutions.

111 Secondly, the Earth's flattening (C_{20}) being poorly observed by GRACE, has been replaced
112 by a satellite laser ranging (SLR) derived time-series from (Cheng et al. 2013) in the spherical
113 harmonic models (ITSG 2016, GFZ RL05a, CSR RL05). The flattening variations in the case
114 of the GFZ RBF solutions have remained unchanged after their co-estimation during Kalman
115 filtering.

116 The atmospheric and non-tidal ocean loading (GAC) is added back to the GRACE in-
117 ferred mass changes and the glacial isostatic adjustment (GIA) is removed from the temporal
118 GRACE coefficients using the GIA predictions according to the ICE-5G v1.3 model (Peltier
119 2004). This step is required to avoid propagation of gravity changes that are caused by the
120 vertical displacements from GIA into the lithosphere uplift calculation from GRACE, which is
121 obtained after a forward computation in the G-NET sites by means of viscoelastic load Love
122 numbers k'_n and h'_n according to Farrell (1972).

123 Finally, the named GIA-induced uplift from the ICE-5G v1.3 model is again restored,
124 thus the buoyancy effect at the base of the lithosphere (Wahr 1995) was taken into account.
125 In each site, the vertical displacements from the GPS time-series is then correlated with the
126 GRACE results (from monthly means) and computed over all stations.

127 Fig. 1 shows the correlations between the G-NET station uplift and the ice-induced crustal
128 deformations due to dynamic loading of the crustal layer obtained using the temporal gravity
129 field solutions: GFZ RBF and CSR RL05.

130 Main differences were found in the eastern part of Greenland, whereas only minor differ-
131 ences can be observed between the three spherical harmonic models (ITSG 2016, GFZ RL05a,
132 CSR RL05). The relatively lower correlations with G-NET around the eastern stations at
133 74°N , (DANE, HMBG, WTHG) can be explained by deficiencies in the GIA uplift model
134 (Dr. Ingo Sasgen, personal communication, July 6, 2017), that was therefore left out for the
135 computation of the average correlation numbers. These average correlations over the sta-
136 tions are very high, with some minor, insignificant deviations: GFZ RL05a: 90.2%, ITSG2016:
137 90.1%, CSR RL05: 89.6 % and GFZ RBF: 89.0% .

138 Then, the global GPS station network displacements from the Center of Orbit determina-
139 tion in Europe (CODE), computed by (Steigenberger et al. 2011) for the time span 2002-2012
140 have been treated accordingly. In Fig. 2, the correlations of the vertical station variations in-
141 ferred from GFZ GRACE RBF solutions and selected CODE GPS stations are displayed. Due
142 to minor differences between the individual solutions the GFZ RBF solutions are displayed



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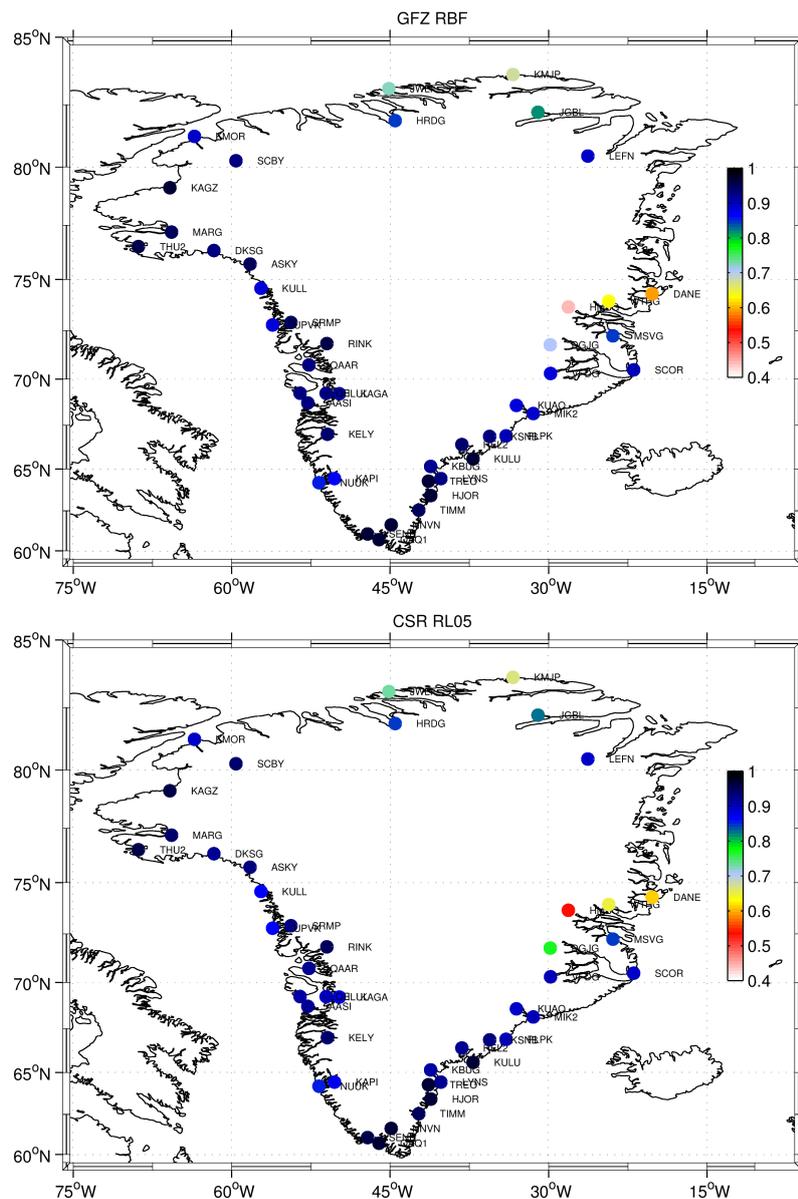


Figure 1. Correlations between the G-NET station uplift and the ice-induced crustal deformations due to dynamic loading of the crustal layer obtained using the temporal gravity field solutions. Only very minor differences for GFZ RBF and CSR RL5, mainly in the eastern part of Greenland can be exhibited.

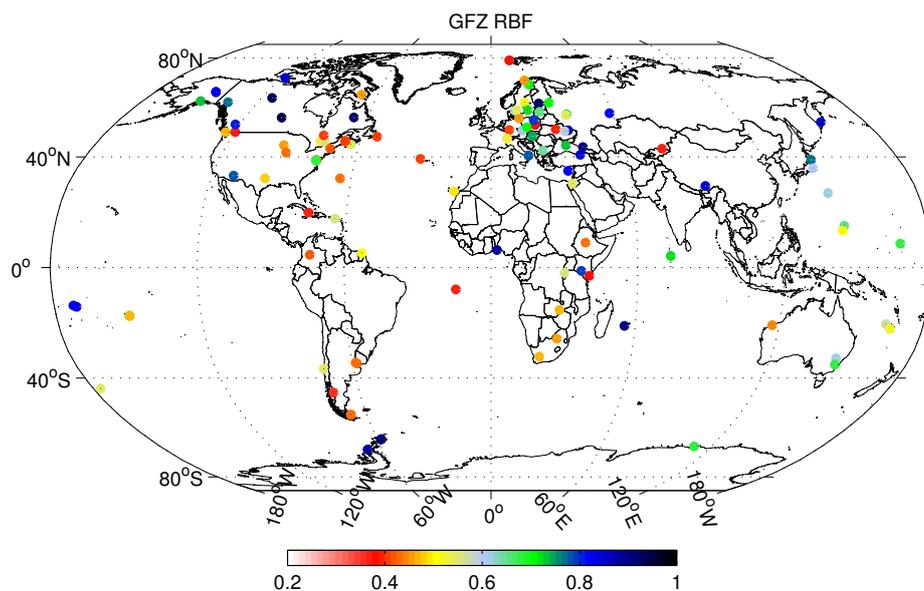


Figure 2. Correlations of the vertical station variations inferred from GFZ GRACE RBF solutions and the global GPS station network from CODE. Only stations with correlations $r > 0.2$ (in total 95 stations) were considered.

143 and serve as proxy for GFZ RL05a, ITSG2016 and CSR RL05, as well. Average correlations
144 for the stations with correlations $r > 0.2$ (in total, 95 stations), are: CSR RL05: 56.8%,
145 GFZ RBF: 56.6%, GFZ RL05a: 53.9% and ITSG2016: 53.5%.

146 The reason why the global station network generally correlates less than the G-NET sites
147 can be explained by the uplift signal strength and the individual data quality (disruptions
148 or damages) but also due to their location, e.g. on islands or coastal regions where signal
149 separation is difficult. One should keep in mind that we are comparing (post-filtered) area
150 mean values from GRACE with point values from GPS such that aliasing of neighboring signal
151 occurs.

152 Nevertheless, for many stations the correlations are high (blue dots) and strongly support
153 the ability of GRACE to remotely monitor mass induced uplift rates.

154 3 ICESAT AND GRACE MASS CHANGES

155 The extent of the Arctic sea ice has reached a new record low in September 2012. According
156 to the European Environment Agency (2016), climate change causes sea ice melting in the



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157 region at a rate much faster than estimated by earlier projections. The snow cover also shows
158 a downward trend. The melting Arctic might impact not only the people living in the region,
159 but thus also elsewhere in Europe and beyond.

160 Ice-mass changes of both the Greenland Ice Sheet (GIS) and the Antarctic Ice Sheet (AIS)
161 have been inferred from monthly gravity fields of different GRACE solutions (GFZ RL05a,
162 CSR RL05 and GFZ RBF). Except for GFZ RBF, all solutions have been filtered using
163 an unisotropic decorrelating filter DDK4 (Kusche et al. 2009). Spherical harmonic degree 1
164 coefficients were added as described in Section 2 as well as the Earth's oblateness, $C_{2,0}$. Mass
165 changes of the solid Earth due to glacial isostatic adjustment (GIA) have been corrected by
166 means of the ICE-5G v1.3 model for the GIS and the IJ05_R2 model (Ivins et al. 2013) for the
167 AIS. All results presented in the following are updates of the findings in Groh et al. (2014a,
168 2014b) to which the reader is referred for a detailed description of the processing.

169 Mass change time series for the GIS (01/2003–12/2013) are shown in Fig. 3. All time series
170 are in good agreement and exhibit comparable linear and seasonal variations. Only minor
171 differences are visible for specific periods. In general, the mass change time series for the AIS
172 (Fig. 4) are also in good agreement. Although differences in the linear trend estimates are
173 visible, they still agree with the corresponding accuracy measures, which are clearly dominated
174 by remaining uncertainties in the GIA predictions.

175 ICESat laser altimetry observations can be used to derive linear ice-mass changes over
176 Greenland and Antarctica, which can be compared to corresponding GRACE results. Here
177 we utilise the ICESat-derived mass change estimates presented in Groh et al. (2014a, 2014b)
178 to compare them to our GRACE ice-mass trend estimates for the period 10/2003–10/2009,
179 the operational period of ICESat. Additional trend estimates for selected drainage basins are
180 compared in Fig. 5. Despite the different observation techniques and resolution capabilities
181 Fig. 5 reveals an overall good agreement between the tested solutions. Still, some differences
182 between ICESat and the three GRACE solutions, exist. For example, the ICESat results
183 for eastern Greenland exceed those from GRACE substantially. Moreover, while GRACE
184 observes a mass gain for the East Antarctic Ice Sheet, the opposite conclusion can be drawn
185 from the ICESat results. These differences can be related to the different error sources of
186 both techniques. Moreover, limitations in the density assumption (here: density of pure ice)
187 used to convert altimetric height changes into mass change can also contribute to the revealed
188 differences.

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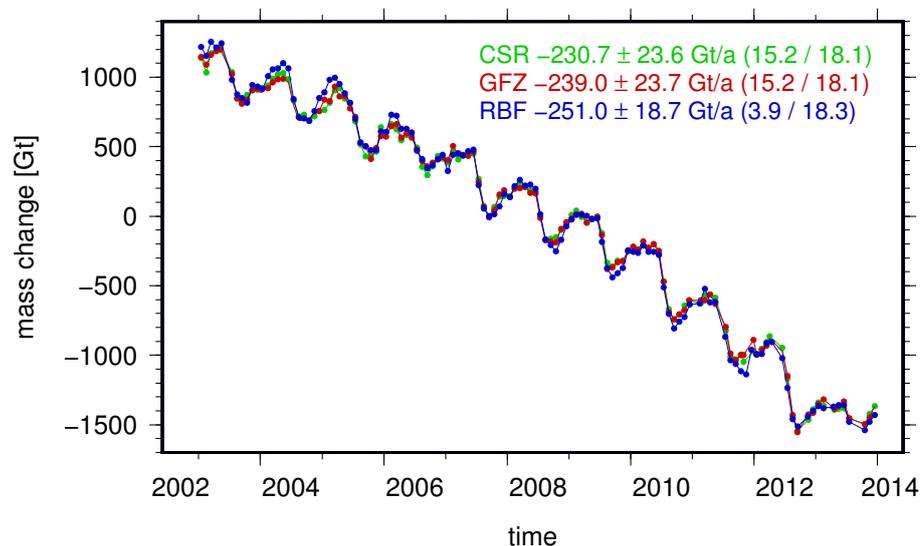


Figure 3. Greenland linear Ice Sheet mass change estimates per year from different GRACE solutions (CSR RL05, GFZ RL05a and GFZ RBF) from 01/2003 - 12/2013. Values in brackets indicate different components of the total error budget (GIA model uncertainties – last value and all remaining error contributions, including leakage errors and GRACE errors – first value).

191 4 GLOBAL MAJOR HYDROLOGICAL BASIN COMPARISON

192 Global catchment aggregated values (CAVs) for hydrological basins greater than $\approx 50,000 \text{ km}^2$
193 have been computed from WGHM (Döll et al., 2003) and compared to the equivalent water
194 layer variations (EWH, according to Wahr et al. 1998) from results obtained from GRACE.
195 The aggregation was performed by equally weighted sums over regular surface tiles.

196 The GRACE monthly fields were used after post processing with DDK4 according to
197 Kusche et al. (2009), consistently for the spherical harmonic models (CSR RL5, GFZ RL05a
198 and ITSG2016) and monthly mean values of daily Kalman filtered results for the GFZ RBF
199 solution. The GRACE data have again been reduced for glacial isostatic adjustment (GIA)
200 and seasonal variations were removed beforehand from all data sets in order to focus on non-



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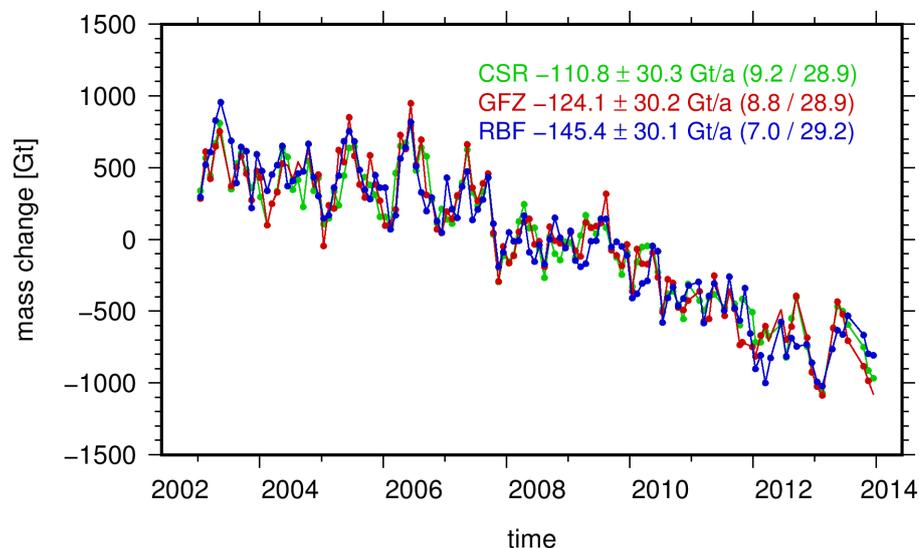


Figure 4. Antarctic linear Ice Sheet mass change estimates per year from different GRACE solutions (CSR RL05, GFZ RL05a and GFZ RBF) from 01/2003 - 12/2013. Values in brackets indicate different components of the total error budget (GIA model uncertainties – last value and all remaining error contributions, including leakage errors and GRACE errors – first value).

201 seasonal coherence. Moreover, in the case of the GFZ RBF solution, the seasonal cycle has
202 already been introduced as a time variable background model.

203 The database containing in total 188 basins (of which 163 were used) was obtained from
204 the interactive GeoNetwork (FAO, 2015). We used (i) Pearson's bi-variate correlation coefficient
205 (XO), (ii) the standard deviation (SD) of the differences between two series and (iii) the
206 scale corresponding to the GRACE basin series w.r.t it's hydrological counterpart, in order
207 to reveal their agreement. The averaged agreements, are displayed in Tab.1. A positive corre-
208 lation threshold of 10% was presumed for the individual GRACE solutions for each basin to
209 exclude e.g. deserts or islands, where strong impact from signal leakage of surrounding water
210 deteriorates our results.



Table 1. Comparison of average GRACE basin estimates against hydrological modeling (WGHM). Bold faced numbers highlight the best performance in the category. Values in brackets are obtained if the seasonal signal is included.

	ITSG2016	GFZ RL05a	GFZ RBF	CSR RL5
(i) XO [%]	60.5 (70.6)	53.1 (65.6)	53.1 (68.2)	57.4 (68.5)
(ii) SD(d) [cm]	4.45 (7.44)	4.81 (7.68)	4.37 (7.36)	4.64 (7.56)
(iii) Scale	0.93 (0.98)	0.90 (0.96)	0.96 (1.00)	0.92 (0.97)

211 All four solutions perform very close with only minor differences, mainly discovered in
212 terms of correlations to the hydrology model (WGHM) over the timespan (2002-2013) . While
213 the correlation gives an opportunity to find out how coherent our remotely sensed results rep-
214 resent a certain 'ground truth', the SD of the differences indicate the reliability of the results.
215 The amplitudes indicate to which extent remote mass balances are captured on average.

216 Best correlation results have been found for the ITSG 2016 solution with 60.5% for the
217 de-seasoned results and 70.6% for the full signal. Lowest standard deviations of the differences
218 to hydrological basin averages were found with 4.4 cm for GFZ RBF after de-seasoning and 7.4
219 cm for the full signal. The best scale correspondence which projects GRACE basin estimates
220 onto the reference hydrology were found for the GFZ RBF solutions. GRACE equivalent water
221 layer estimates thus capture on average most of the hydrological signal strength.

222

223 Fig. 7 displays the comparative correlations for each basin w.r.t. the hydrological model
224 (WGHM) that represents total water storage variations throughout the period 2002 – 2013.
225 This comparative comparison provides a performance indicator for different GRACE solutions
226 by means of their individual agreement with WGHM on the level of CAVs and geographical
227 location.

228 Still, remains difficult to identify systematic patterns such as basin size or basin location
229 that would indicate e.g. data sampling or specific processing properties. The results overall
230 strongly support the capability of GRACE to monitor global water storage variations remotely
231 from space despite of the band limitation of the solutions and their signal omission errors.

232 To counteract this in Steckler et al. (2010), the basin scale masks for water loading in
233 Bangladesh were processed by a truncated spherical harmonic representation in order to sim-
234 ulate the omission error from the model resolution. In our approach we have converted each



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235 fine scale basin mask of $[0.5^\circ \times 0.5^\circ]$ into a coarse mask of $[2^\circ \times 2^\circ]$ which entirely includes
236 the fine scale mask in the sense of a convex hull. The domain is thus enlarged to encounter
237 to a certain extent for signal leakage-out effects. On the other hand leakage-in cannot be
238 treated effectively other than by an increased model resolution under the provision that the
239 measurement system is sensitive to it. Main limitations thus remain gravity signal attenuation
240 at GRACE mission altitude and the separation width of the twin satellite system.

241 5 ALTIMETRY SATELLITE ORBITS

242 Recently, the impact of time variable geopotential models on altimetry satellite orbits has been
243 investigated (Rudenko et al. 2014). Following these ideas, we test the GFZ RBF solutions for
244 precise orbit determination of Envisat (2002-2012), Jason-1 (2002-2013) and Jason-2 (2008-
245 2015) at the time intervals given in the parentheses.

246 We have chosen these satellites since their missions coincide with the GRACE time in-
247 terval. The orbits are derived at 7-day arcs for Envisat and 12-day arcs for Jason-1 and
248 Jason-2 by using the same background models for each satellite (Rudenko et al. 2017), but
249 choosing three different Earth gravity field models/solutions: EIGEN-6S4 (Förste et al. 2016),
250 GFZ RBF and GFZ RL05a. For the propagation of the orbits, based on the GFZ RBF time
251 variable part, we first convert the grid tiles into spherical harmonic coefficients, and add the
252 static part of the EIGEN-6S4 model. The static part of the satellite-only global gravity field
253 model EIGEN-6S4 is complete up to degree and order 300. The time variable gravity part of
254 the model is represented by a drift, annual and semi-annual variations per year of spherical
255 harmonic coefficients up to degree and order 80 by July 1, 2014.

256 We have computed fits (observed minus calculated) of SLR and DORIS observations used
257 for precise orbit determination of the satellites and two-day arc overlaps. Since the only
258 difference in our tests consists in a replacement of Earth's gravity field models/solutions,
259 smaller values of observation fits and arc overlaps indicate better performance of a respective
260 Earth's gravity field model/solution.

261 The mean values of SLR and DORIS RMS fits and two-day radial arc overlaps for each
262 satellite obtained using the EIGEN-6S4 model, GFZ RL05a and GFZ RBF solutions are shown
263 in Tab. 2.

264

265

266



Table 2. The mean values of SLR and DORIS RMS fits and two-day radial arc overlaps for Envisat (2002-2012), Jason-1 (2002-2013) and Jason-2 (2008-2015), obtained using the EIGEN-6S4 model, GFZ RBF and GFZ RL05a solutions.

Satellite	Altitude [km]	Model/Solution	SLR fits [cm]	DORIS fits [mm/s]	Radial arc overlap [cm]
Envisat	800	EIGEN-6S4	1.27	0.4214	0.53
		GFZ RBF	1.28	0.4215	0.57
		GFZ RL05a	1.28	0.4216	0.60
Jason-1	1336	EIGEN-6S4	1.19	0.3532	0.79
		GFZ RBF	1.20	0.3538	0.77
		GFZ RL05a	1.19	0.3533	0.79
Jason-2	1336	EIGEN-6S4	1.23	0.3486	0.56
		GFZ RBF	1.24	0.3486	0.56
		GFZ RL05a	1.23	0.3489	0.56

267

268 The results obtained using the GFZ RBF solutions are in agreement with those obtained
269 using the EIGEN-6S4 model and slightly outperform the results obtained using the GFZ
270 RL05a solution. Since Envisat is more sensitive to the Earth's gravitational field due to its
271 lower altitude than two Jason satellites, we look at the results obtained for this satellite in
272 more detail. The DORIS measurements (Fig. 8) seem to be less suitable to detect the impact
273 of the replacement of EIGEN-6S4 gravity field model by GFZ RBF solutions, since there are
274 no notable differences in the fits of these observations derived different Earth's gravity field
275 realizations.

276 SLR RMS fits (Fig. 9) show comparable or even better performance (smaller RMS fits)
277 at some orbital arcs for Envisat until the middle of 2008 when using GFZ RBF solutions
278 and better performance when using the EIGEN-6S4 model from the middle of 2008 onwards.
279 This is probably caused by insufficient trend estimates in the background modeling and can
280 be addressed in a next iteration. The inconsistency is also confirmed when looking at weekly
281 obtained two-day arc overlaps in Fig. 10. The radial arc overlaps are of comparable accuracy
282 when using GFZ RBF, GFZ RL05a solutions and the EIGEN-6S4 model for Jason-1 and
283 Jason-2, while for Jason-1, the GFZ RBF solutions even outperform the model and other
284 solutions, cf. Table 1.



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285 **6 DISCUSSION AND OUTLOOK**

286 In this study a set of evaluation methods is used to compare the novel RBF GRACE solutions
287 with other widely used standard GRACE solutions. Their absolute figures confirm once again
288 the high potential and ability of GRACE or GRACE-like missions to significantly contribute
289 to climate relevant indicators such as the quantification of ice-mass loss over Greenland. While
290 a single correlation result gives only limited evidence of the overall quality of a solution, the
291 sum over several evaluations may provide a fair picture of the relative performances in a close
292 comparison with each other. The obtained spread of results is found relatively small and has
293 clearly converged with each new release, however, still minor differences are found and may
294 help to further improve the data processing methods within the GRACE community.

295 More in detail, the comparison to G-NET and CODE GPS uplift rates confirmed the
296 temporal loading of mass redistribution that is revealed in the GRACE solutions. Both vertical
297 data sets have helped in the past to validate and confirm the spatial resolution of the GRACE
298 results. All four GRACE time variable gravity field solutions that we have tested (ITSG2016,
299 GFZ RL05a, GFZ RBF and CSR RL05) show consistently high correlations (89-90%) with the
300 vertical site displacements from the G-NET GPS Network. The correlations to the global GPS
301 station network from CODE are lesser (52-55%). This can be explained by the lower uplift
302 signal strength and the individual data quality but also due to their location, e.g. on islands.
303 However, for many stations the correlations are high and confirm the ability of GRACE to
304 remotely monitor mass induced uplift rates.

305 Our direct comparison with linear ice-mass changes from ICESat results with the GRACE
306 loading data reveals a very good agreement, but also spatial differences, when comparing over
307 smaller drainage basins.

308 The comparative agreement to the hydrological model WGHM shows that monthly means
309 of the GFZ RBF solutions are of equal quality as the renowned products. All GRACE models
310 under consideration perform very closely and support the fact that large scale hydrology can be
311 accurately monitored remotely from space, especially the trend estimates of the Earth's polar
312 ice-sheets melting and groundwater depletion over large deserted areas. The transformation
313 of K-Band and trajectory data from dynamic to in-situ observations has been successfully
314 used to compute the GFZ RBF solutions. An improved de-aliasing for monthly gravity field
315 products is feasible when estimating additional sub-monthly results for time-variable gravity
316 signals and residual atmosphere and oceanic loading. The (Kalman-) regularization reduces
317 artifacts during inversion such that no post-filtering is indicated for these products.

318 Precise orbit determination of low orbit Earth's satellites, such as e.g. Envisat, has been

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319 shown to be a powerful tool to validate daily and monthly Earth's time-variable gravity field
320 solutions. In general, the orbit tests for altimetry satellites Envisat, Jason-1 and Jason-2 over
321 the total 2002-2015 time interval show rather comparable quality of the orbits derived using
322 EIGEN-6S4 model, GFZ RBF and GFZ RL05a solutions. DORIS measurements seem to be
323 less sensitive to the replacement of up-to-date time variable Earth gravity field models and
324 solutions. On the contrary, SLR residuals and arc overlaps of altimetry satellite orbits are
325 sensitive to the quality of the underlying background models. From 2002 until the middle
326 of 2008, SLR RMS fits of Envisat obtained using GFZ RBF solutions perform comparably
327 and even better at some weeks than those derived using the EIGEN-6S4 model, whereas this
328 model outperforms the GFZ RBF solutions from 2008 onwards.

329 Radial arc overlaps are of comparable accuracy, when using GFZ RBF, GFZ RL05a so-
330 lutions and the EIGEN-6S4 model for Jason-1 and Jason-2, while for Jason-1, the GFZ RBF
331 solutions even outperform the model and other solutions. For Envisat, which is more sen-
332 sitive to the gravity field modeling, the smallest radial arc overlaps are obtained using the
333 EIGEN-6S4 model, followed by GFZ RBF solutions and finally by GFZ RL05a solutions.
334 In this context, future reprocessing of GRACE time series can be verified against altimetry
335 results to confirm further improvements. In view of an upcoming GRACE follow-On mission
336 with improved instrument data, we may expect time-variable gravity fields to be included in
337 future orbit computations of altimetry satellites.

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353 Agencies are not responsible for any use that may be made of the information it contains.

354 Latest daily [$2^\circ \times 2^\circ$] grids in equivalent water heights, and [$1^\circ \times 1^\circ$] grids with GIA predic-
355 tions removed and center of mass to center of figure corrected, as well as spherical harmonic
356 coefficients, can be downloaded from
357 <ftp://gfzop.gfz-potsdam.de/EGSIEM/>.

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*GRACE gravity fields based on RBF method* 19**Table A1.** List of global hydrological catchment basins sorted by area. The correlations refer to the signal from GRACE derived water storage variations and the hydrological model WGHM after de-seasoning. The given numbers are a performance indicator for the individual solutions in a relative context.

Basin Name	Size [km ²]	ITSG2016 [%]	GFZ RL05a [%]	GFZ RBF [%]	CSR 05 [%]
Narva	48838	74	66	51	69
StJohn	55210	74	68	85	74
SouthPacificIslands	58689	24	36	26	26
EmsWeser	65326	49	30	19	47
ItalyWestCoast	68891	70	52	58	63
Guadiana	70409	78	72	82	76
Tagus	72920	79	73	84	78
Dniester	73438	67	65	75	67
Gironde	80159	85	75	80	77
Farahrud	82474	26	26	14	21
IndiaWestCoast	84089	73	68	68	70
BayofBengalNorthEastCoast	85714	92	90	90	91
Ireland	85904	33	16	14	37
Daugava	86070	85	81	77	84
Neman	92930	76	69	62	68
ItalyEastCoast	92978	82	69	73	77
SpainPortugalAtlanticCoast	93024	79	67	83	77
Churchill	93099	62	63	82	63
Douro	97412	81	72	82	80
Narmada	98279	80	80	78	81
Rhone	98367	81	76	73	77
SouthAfricaWestCoast	102100	46	42	61	35
SpainSouthandEastCoast	102185	64	52	53	60
BalticSeaCoast	106081	59	51	43	50
FranceWestCoast	108390	79	70	87	72
Loire	117049	84	80	81	81
Oder	121292	72	67	74	73
CentralPatagoniaHighlands	121293	55	45	52	58
MarChiquita	129715	68	69	64	65
RioLerma	130820	78	74	79	73
GrijalvaUsumacinta	132049	92	88	91	91
Elbe	140922	77	66	70	78
Mahandi	144672	88	87	84	88
RussiaSouthEastCoast	150259	67	61	51	59
RioBalsas	156042	77	71	74	76
ChaoPhraya	157686	91	91	90	90
Negro	162658	73	71	79	73
HongRedRiver	165007	86	86	82	84
PampasRegion	175610	35	35	21	33
SalinasGrandes	177187	49	52	46	48
HamuniMashkel	179360	71	62	65	60
NorthandSouthKorea	181759	49	41	64	42
VietNamCoast	186187	94	92	93	93
Rhine	187991	78	64	67	73
EasternJordanSyria	189266	40	33	17	39
Sulawesi	190307	77	68	73	77
ArabianSeaCoast	190641	73	54	72	57
Wisla	193658	77	72	75	72
YucatanPeninsula	197472	91	86	89	90
NorthBorneoCoast	202997	59	53	52	53
PersianGulfCoast	207160	52	44	45	49
Ural	215178	70	68	75	68
JavaTimor	223696	67	60	44	64
NorthArgentinaSouthAtlanticCoast	224076	65	64	56	67
Neva	229621	81	78	74	80
Fraser	232176	87	86	84	87
Caribbean	232942	69	61	55	71
MexicoInterior	239690	68	59	67	61
AfricaIndianOceanCoast	244531	73	65	54	70
Helmand	250573	57	52	54	53
UnitedStatesNorthAtlanticCoast	255343	77	64	81	71
Magdalena	259632	75	62	63	69
NamibiaCoast	260457	47	34	13	35
BlackSeaNorthCoast	262302	74	68	67	74
Salween	265822	88	88	85	88
NorthBrazilSouthAtlanticCoast	271751	89	86	87	88
NewZealand	272526	32	26	61	29
Krishna	274198	80	82	80	80
NorthernDvina	274880	95	93	92	95
EastBrazilSouthAtlanticCoast	285877	83	82	90	81
Finland	290606	69	60	55	65
ColombiaEcuadorPacificCoast	290939	34	23	35	24
PeruPacificCoast	290939	44	37	42	40
PapuaNewGuineaCoast	291136	67	62	62	68
Philippines	304285	73	49	76	66



Table A1. continued.

Basin Name	Size [km ²]	ITSG 2016 [%]	GFZ RL05a [%]	GFZ RBF [%]	CSR RL05 [%]
PeninsulaMalaysia	311477	16	20	15	16
Godavari	313892	87	86	84	87
CaribbeanCoast	317043	85	80	81	84
BlackSeaSouthCoast	318639	64	59	58	65
Parnaiba	331643	95	93	96	93
AdriaticSeaGreeceBlackSeaCoast	342127	82	83	87	82
MediterraneanSeaEastCoast	342785	76	73	83	77
LaPunaRegion	348890	79	62	47	73
BoHaiKoreanBayNorthCoast	353244	62	57	48	63
GreatBasin	370144	84	82	78	80
CaspianSeaSouthWestCoast	371831	31	38	40	31
SouthAmericaColorado	373863	48	45	47	50
Japan	378301	44	47	18	43
SouthernCentralAmerica	387927	91	89	90	89
Irrawaddy	402028	93	92	92	92
SouthAfricaSouthCoast	403126	72	47	48	69
Volta	411058	75	71	69	70
Limpopo	411553	59	45	40	56
XunJiang	412953	87	86	90	86
California	420022	78	73	78	76
Don	445212	66	66	69	62
LakeBalkash	445594	73	67	71	68
IrianJayaCoast	449015	73	66	58	65
GulfCoast	465689	86	84	74	85
Senegal	477345	93	85	91	91
Sumatra	477814	41	28	18	33
MexicoNorthwestCoast	478301	69	56	70	69
SouthArgentinaSouthAtlanticCoast	484180	51	48	63	53
Sweden	489477	75	71	69	79
AustraliaSouthCoast	490397	34	34	45	30
AngolaCoast	499542	74	66	62	70
Dnieper	513535	74	72	72	75
Sabarmati	523530	61	59	49	58
Kalimantan	542536	75	68	71	71
RioGrandeBravo	552385	57	50	46	51
MediterraneanSouthCoast	558292	26	12	18	27
CaspianSeaCoast	561343	65	65	63	64
NortheastSouthAmericaSouthAtlanticCoast	561413	80	79	70	80
ScandinaviaNorthCoast	578748	84	74	64	79
Madagascar	596220	88	78	86	84
SaoFrancisco	635159	90	86	87	87
RiftValley	638878	56	42	38	53
NorthAmericaColorado	650155	72	65	71	68
ChinaCoast	650882	74	58	60	74
RussiaBarentsSeaCoast	678113	96	91	88	95
AtlanticOceanSeaboard	689995	78	72	90	79
KaraSeaCoast	696301	89	87	89	88
GulfofGuinea	699755	36	34	28	36
GulfofMexicoNorthAtlanticCoast	701385	83	81	75	84
AustraliaEastCoast	734572	76	66	68	69
AustraliaWestCoast	738000	31	37	61	29
ColumbiaandNorthwesternUnitedStates	757681	90	89	86	89
CentralIran	787176	44	34	22	42
ShebelliJuba	796599	53	37	49	55
AmuDarya	799261	83	78	81	83
Danube	799650	81	82	88	81
Mekong	803303	90	91	88	89
AfricaNorthWestCoast	809724	29	22	21	28
UruguayBrazilSouthAtlanticCoast	830359	76	73	68	71
HuangHe	832494	39	44	35	34
AfricaSouthInterior	863869	81	79	71	81
Indus	867157	53	58	55	54
Tocantins	915661	94	94	95	93
TigrisEuphrates	916137	71	73	72	71
MurrayDarling	928776	76	70	85	72
Orinoco	974772	93	93	92	93
Orange	984867	76	59	40	69
AfricaWestCoast	1010044	85	85	84	85
AfricaEastCentralCoast	1041192	78	78	73	78



Table A1. continued.

Basin Name	Size [km ²]	ITSG 2016 [%]	GFZ RL05a [%]	GFZ RBF [%]	CSR RL05 [%]
SyrDarya	1117625	75	69	71	77
SaskatchewanNelson	1135754	62	59	56	63
SiberiaNorthCoast	1200168	89	83	87	85
StLawrence	1309589	75	77	87	76
Zambezi	1373296	90	90	88	90
Volga	1474073	84	85	87	85
HudsonBayCoast	1648738	29	34	62	28
GangesBramaputra	1671358	74	74	67	74
AustraliaNorthCoast	1692704	93	93	91	93
Mackenzie	1766094	85	82	82	82
Yangtze	1789482	85	80	81	83
Amur	2086009	70	68	54	71
Niger	2136941	92	90	89	91
ArcticOceanIslands	2166086	13	13	17	14
GobiInterior	2170053	53	28	28	44
PacificandArcticCoast	2266165	65	60	64	66
Lena	2416437	76	74	76	74
LakeChad	2461890	86	82	91	86
Yenisey	2574501	90	81	86	86
LaPlata	3016800	88	85	81	86
Ob	3025660	86	85	83	86
NorthwestTerritories	3044095	80	78	85	80
AustraliaInterior	3048596	69	68	43	68
SiberiaWestCoast	3052334	87	83	86	85
Nile	3074955	82	76	70	81
MississippiMissouri	3273240	83	81	78	84
Congo	3696670	66	57	65	64
Amazon	5970775	90	90	90	90

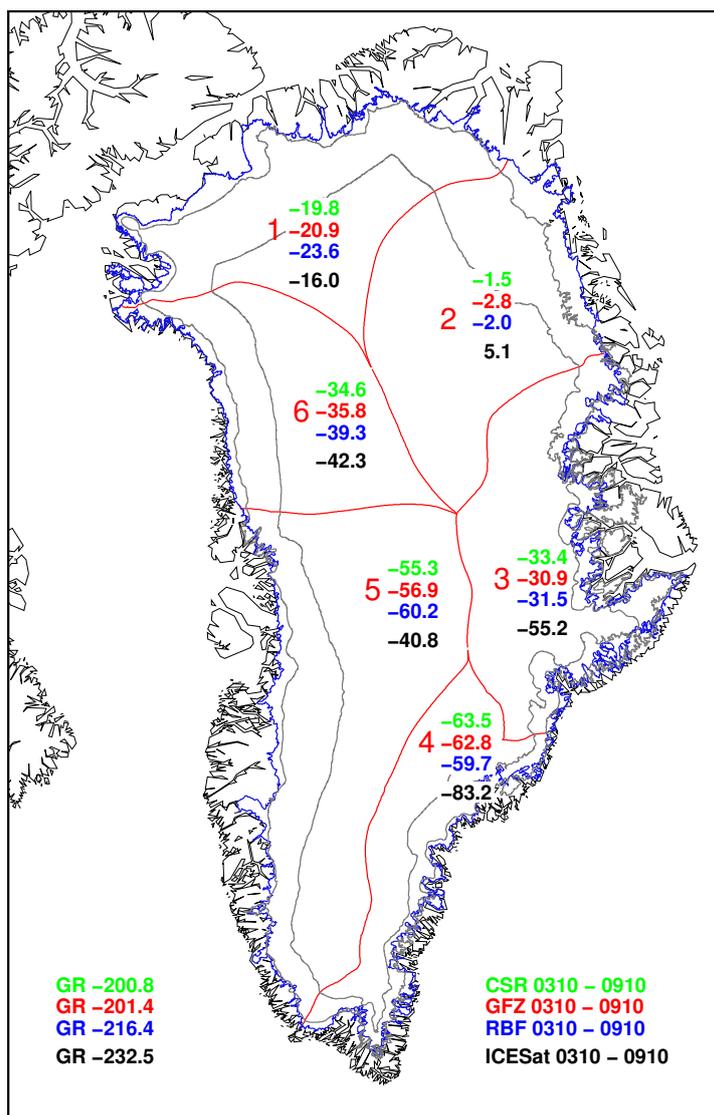


Figure 5. Mean annual ice-mass change (Gt/a) for the Greenland Ice Sheet as well as selected drainage basins (separated by red lines) and aggregations derived from different GRACE solutions and ICESat laser altimetry data over the period 10/2003–10/2009.

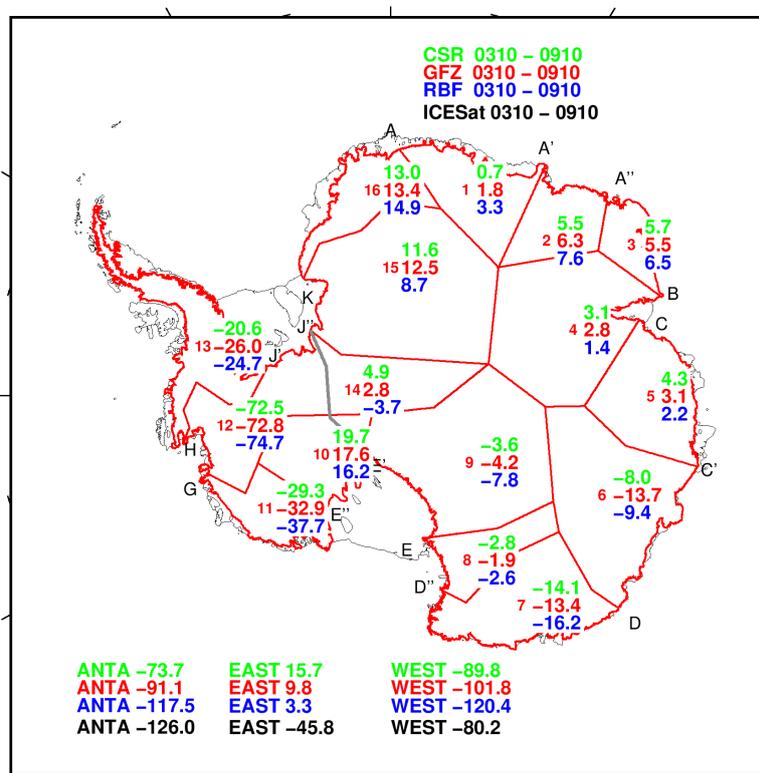


Figure 6. Mean annual ice-mass change (Gt/a) for both the Antarctic Ice Sheet as well as selected drainage basins (separated by red lines) and aggregations derived from different GRACE solutions and ICESat laser altimetry data over the period 10/2003–10/2009. The grey line depicts the boundary between the eastern and the western part of the AIS.



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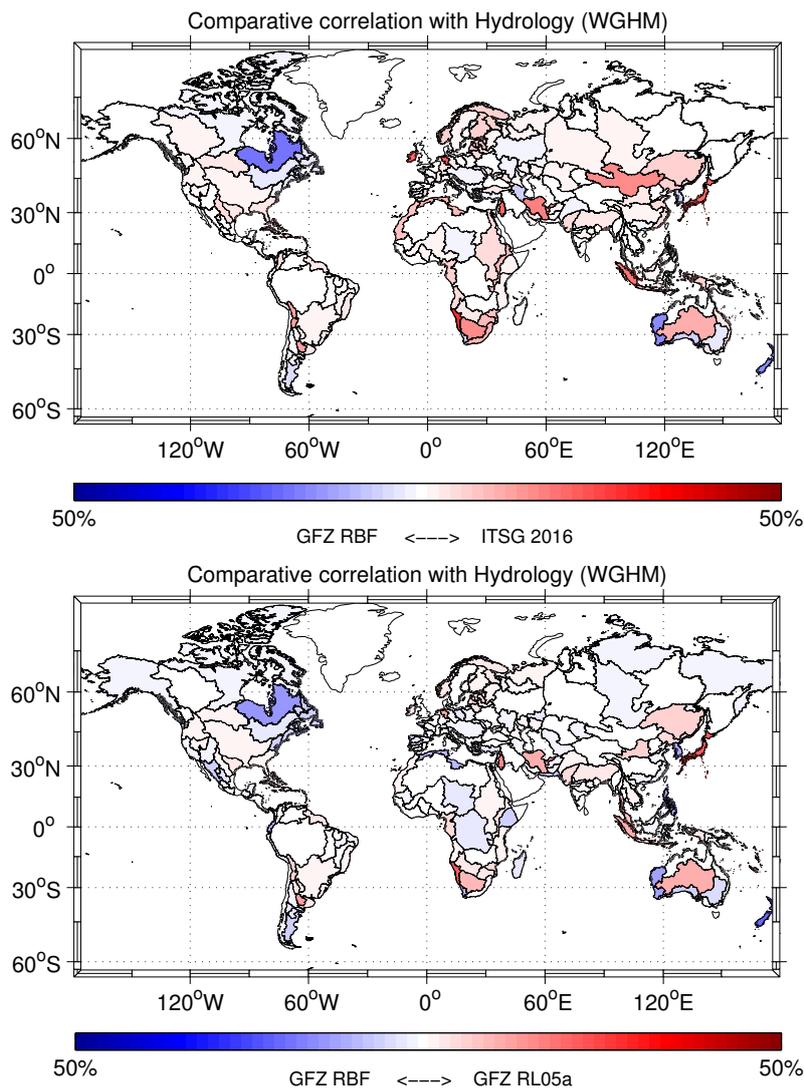


Figure 7. Comparative correlations of catchment aggregated values from GRACE results against hydrology; the plot depicts the relative difference (%) in each basin between the correlations of two time series with respect to the hydrological model (WGHM). Blue means higher coherence for the GFZ RBF solution and red marks higher coherence for the concurring model (GFZ RL05a, ITSG 2016). Hudson Bay Coast and Japan stick out slightly, which hints to post glacial rebound and the Tohoku megathrust Earthquake. See also text for further discussion. For a full list of all considered basins and their individual hydrological correlations, the reader is referred to Tab. A1 in the appendix.

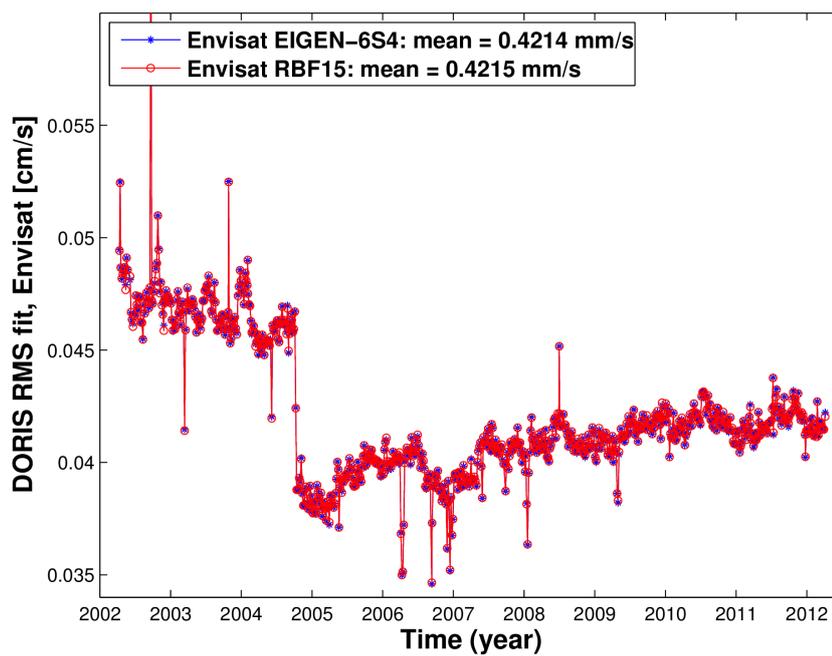


Figure 8. Weekly DORIS RMS fits of Envisat computed with different time-variable Earth gravity modeling: EIGEN-6S4 model and GFZ RBF solution.



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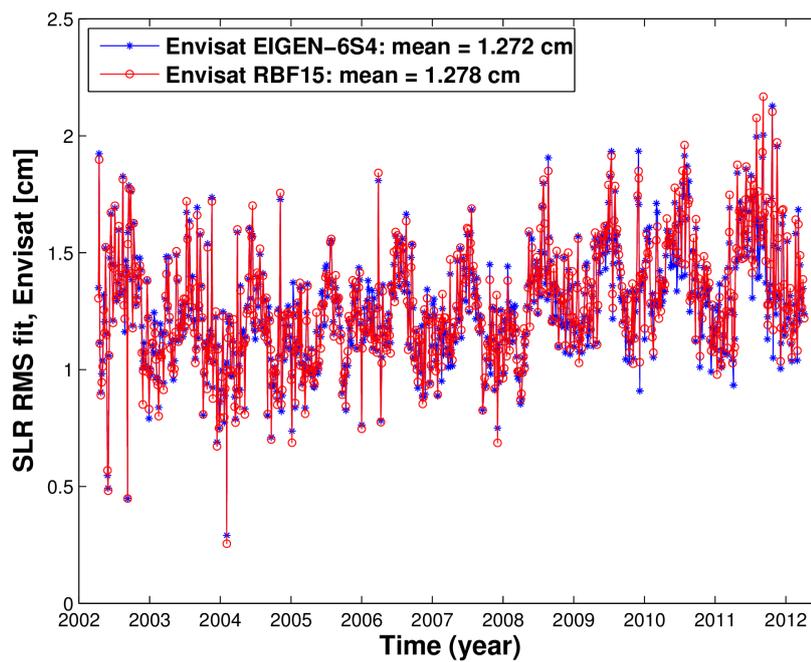


Figure 9. Weekly SLR RMS fits of Envisat computed with different time-variable Earth gravity modeling: EIGEN-6S4 model and GFZ RBF solution.

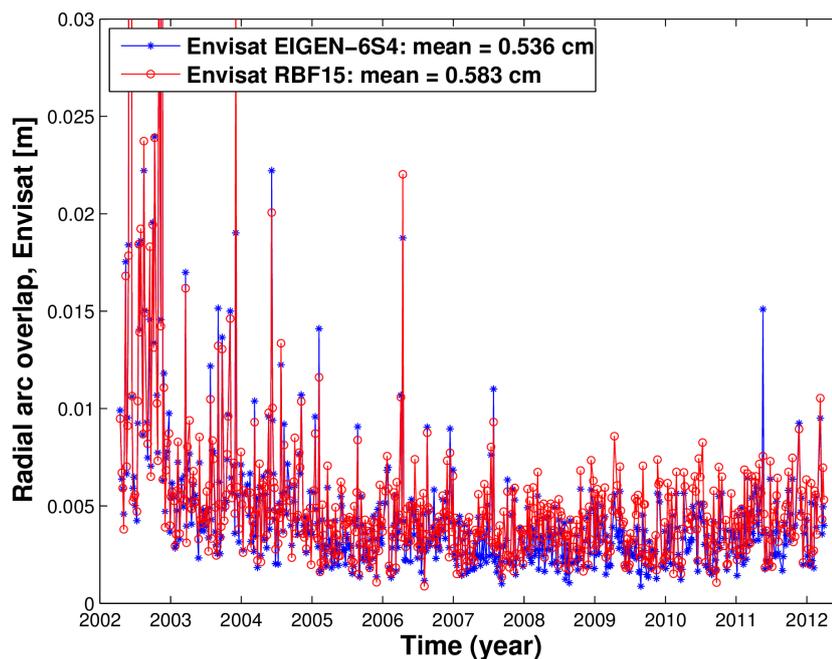


Figure 10. Weekly two-day radial arc overlaps for Envisat computed with different time-variable Earth gravity modeling: EIGEN-6S4 model and GFZ RBF solution.