

Author's Response To Reviewers

Title: Seismic signature of turbulence during the 2017 Oroville Dam spillway erosion crisis

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We thank our reviewers for their insightful comments. We address each comment below and attach a revised version of the manuscript containing updated figures and with altered text in red. In our comments, the page and line references are to this revised manuscript. The revised version of the paper supplement follows the revised manuscript.

Reviewer #1 (Victor Tsai) Comments

1. ***P1L15,18: See later comments about clarifying discharge scaling and upslope propagation.***

Changed “propagation up the hillside topography” to “propagation up the uneven hillside topography”

2. ***P2L17: Run-on sentence.***

Altered phrasing of sentence to:

“Because turbulence affects erosional processes in both hydraulic structures and natural rivers, techniques from the seismic river monitoring (fluvial-seismic) literature provide guidance.”

3. ***P2L28: Not clear what is implied by ‘geometry variations’.***

Changed “channel geometry variations” to “deviations from spatial uniformity”.

4. ***P3L20: It is not true that the Tsai and Gimbert models assume only Rayleigh waves are excited. In the Tsai model, it is true that a Rayleigh-wave Green’s function is used to approximate the response since the force is assumed to be close to vertical, but it is not a limitation of the general modeling framework. In the Gimbert model, a similar approximation is made, but again Love waves could be included in the most generic version of the model.***

We appreciate the distinction. The sentence has been changed to:

“While recent forward models to estimate the power spectral density of seismic energy produced by moving bedload and turbulently flowing water can accommodate the excitation of various seismic waves, their applications to date assume that only Rayleigh waves are excited (Tsai et al., 2012; Gimbert et al., 2014). This assumption has not been quantitatively tested.”

5. ***Figure 1: Panel c needs better labeling. First, it should be clarified where exactly the label ‘emergency spillway damage’ is referring to. Second, the same names for labels should be used as in panel b. Labels should also be larger, and generally easier to read. Finally, since the distance from the signal to the***

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station is an important parameter, it would be useful to mention somewhere (either in the text or figure) what those distances are. (It can be estimated using the scale bar, but a definite number would be useful.)

The figure was updated to have consistent labeling with panel b, the label size was increased, and the outline of the emergency spillway damage was added. The colorscale was also changed to highlight the erosion damage.

On P5L21-22, we added the following line:

“The seismometer is 1.4 km from the top of the flood control spillway channel and 1.9 km from the bottom of the channel”.

6. P6L1: Listed as 38-hour here but 26-hour in Figure 2. Please clarify.

The time correct length of time is period is 38 hours (between 8am PST on February 11th and 10pm PST on February 12th). We fixed this in Figure 2.

7. P6L18: “complied” should be “compiled”

Fixed.

8. P7L3: “causally” would not be clear to non-seismologists. Either explain in more detail or remove.

While that is a technical word, it also has a precise meaning to seismologists and we do not believe that it is too distracting or misleading to the non-seismologists. Therefore, because it adds specificity, we opt to keep it in the sentence.

9. Section 3.2 (P8-9): It is not clear that this description is very useful. It is technical, and not that well explained. It might be more straightforward to just describe the statistics used and refer to the references for details, rather than put in a technical section that is challenging to read. Alternatively, the section could be clarified. I believe I understand roughly what the authors did, but this understanding is not from reading the section. As just one example, on P8L7, it is not clear what dominant eigenvector is being discussed. Eigenvector of what?

Thank you for pointing out that this section needs clarification. We provided some elaboration in Section 3.2. We believe the inclusion of this section is justified by the challenging nature of the paper we reference (Park et al., 1987). Our hope is that our description of the polarization attributes will allow the FDPA method to gain wider appreciation and usage.

We have made edits throughout the paper to consistently refer to the eigenvector corresponding to the largest eigenvalue of the spectral covariance matrix at each frequency as the “dominant eigenvector”. We now define this usage on P7 L22-25 by inserting:

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“Henceforth, we refer to this as the dominant eigenvector. The complex-valued coefficients of this dominant eigenvector describe a particle motion ellipsoid at each frequency, whose properties are analyzed in this paper.”

10. L10P6: “Complex” should be described more.

Thank you for pointing out that complex is a vague word. We now refer to this as “eroded and incised channel shape.”

11. Figure 5: It is difficult to tell how much of the differences between 2017 and the other years are just due to the difference in range, and how much of the hysteretic behavior is due to something else. In particular, the low-flow part of 2017 does not appear to have strong hysteresis, and is therefore appears quite similar to the other years, and perhaps not distinguishable if the higher flow segments were not there. Incidentally, the color scale chosen for this figure is poor. Please modify to make the times more distinguishable. Potentially larger symbol sizes are needed, or the black edges could be removed to make clearer.

We have changed the x axis scale in the to the 2006 and 2011 time periods in Figure 5 to make the behavior more visible and have modified the color map, removed the black symbol edge lines, and improved the figure resolution. We agree that no hysteresis is observed in the 2006 and 2011 releases or in the early part of 2017, as stated on P11L4-6. The two releases shown are the largest two available for comparison. For consistency, we changed the color scale, line widths, symbol edge lines, and resolution in Figure 8 as well.

12. P11L9: Again, first eigenvector of what? Not clear what it is an eigenvector of.

We have made sure to consistently refer to the eigenvector corresponding to the largest eigenvalue of the spectral covariance matrix at each frequency as the “dominant eigenvector”. We now define this usage on P7 L22-25 by inserting:

“Henceforth, we refer to this as the dominant eigenvector. The complex-valued coefficients of this dominant eigenvector describe a particle motion ellipsoid at each frequency, whose properties are analyzed in this paper.”

13. P11L12: Break in slope is not clear. Please clarify.

By “break in slope”, we meant that below the threshold discharge of 200 cubic meters per second, the seismic power does not increase with discharge. We added a figure to the supplement showing the described change in the scaling relationship between dominant eigenvector power and discharge and inserted the following clarification on P12L5-9:

“Below a discharge of approximately $200 \text{ m}^3 \text{ s}^{-1}$, there does not appear to be a relationship between dominant eigenvector power and discharge. We therefore interpret $200 \text{ m}^3 \text{ s}^{-1}$, as the threshold discharge above which signals emanating from the Oroville spillway become the dominant source of seismic energy. Figure S2 in the supplemental materials shows the dominant eigenvector power for all discharges.”

14. P12L2-3: This statement needs better explanation. How is the change in scaling relationship consistent with a change in turbulent intensity? Why should the scaling exponent be expected to change in this way, rather than just changing the scale factor, for example (but not the exponent). Somewhere here, it would also be worth commenting on whether the raw signal (without doing a polarization analysis) shows the same behavior or not. Is it necessary to do a polarization analysis? Or is it just clearer using the decomposed polarities? What about the vertical?

On Page 12 we report our observations and develop the possible explanations for these observations in the discussion section. We changed the P12L16-17 to:

“The change in the scaling relationship between discharge and seismic power is consistent with the inferred increase in turbulent energy dissipation following the damage to the flood control spillway (see discussion)”.

We included the scale factor (coefficient) in Figure 6 and created a new table (Table 1) to show that both a change in coefficient and exponent are observed as a result of the damage. However, we focus in this paper on the exponent in the power function relating seismic power and discharge rather than the coefficient for the following reasons:

- a) The coefficient of the power function reflects the expected seismic power at a discharge of $1 \text{ m}^3 \text{ s}^{-1}$. Our data shows that we are likely not able to observe the spillway-excited seismic energy below a discharge of $200 \text{ m}^3 \text{ s}^{-1}$, and we only use the discharge data above this discharge to fit the power function. We expect the power function coefficient would vary between systems of different sizes (i.e. a small stream and a large river). Since we are only looking at one system in this paper, we only consider the variability in the exponent to be physically meaningful.
- b) In the fluvial geomorphology literature, the relationships between discharge and flow velocity, width, depth at a single river cross section are commonly described by power functions (Leopold and Maddock, 1953). This approach is called at-a-station hydraulic geometry, and the exponents of the power functions for flow velocity, width, and depth are used to infer the shape of the channel, channel roughness and, by extension, the degree of turbulence and energy expenditure. To evaluate the similarities and contrasts between rivers of different sizes and discharges, only the scaling exponents are compared.
- c) Other seismic studies have similarly characterized the relationship between discharge and seismic power, using the power relationships to infer changes in channel geometry and turbulent state at the same site (Gimbert, et al., 2016; Roth et al., 2017). We wish to place our study in the context of these observations by discussing the power function exponents (the power function coefficients were not reported in Gimbert et al., 2016 or Roth et al., 2017 so we have no basis of comparison).

On page 20 in the discussion and in the conclusion, we have revised our discussion of the water turbulence to more explicitly describe what we mean by “greater turbulence”.

“The increased scaling exponent following the crisis likely corresponds to the addition of new sources of turbulent energy dissipation generated from the rougher channel morphology associated with exposed bedrock and

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waterfall. For a uniform turbulent flow, as expected in the hydraulically smooth, constant-width channel geometry present during the 2005-2006 flood, discharge is log-linearly related to flow depth according to the Law of the Wall and ground motion is generated by fluctuating forces applied by scaled eddies within the flow, analogous to the processes described by Gimbert et al. (2014). After damage is created in the channel, several mechanisms likely increase the energy dissipated by the flow at a given discharge. The first is that the erosion damage introduced a steep vertical drop in the base of the channel, developing a waterfall. A waterfall will violate assumptions in the Gimbert et al. (2014) model formulation and lead to greater water velocities (from free fall) impacting the bed than would be found in a continuous turbulent channel flow. Second, the irregular channel shape resulting from erosion provides obstructions to the flowing water that create local pressure gradients around the obstacles. These pressure gradients cause a deflection in the flow and an increase in the shearing between flows of different velocities, increasing the energy dissipated by the turbulence in the flow. Third, erosion during the 2017 event incised a 47-meter-deep, V-shaped channel, which increased flow depths for the same discharge and changed the distribution of shear stresses applied to the bed. Greater flow depths would also allow for larger eddies to form. Our results suggest that the additional energy dissipated by these forms of turbulence is observed as an increase in the scaling relationship between discharge and seismic power. Our observations support the use of the exponent in the $P_W \propto Q$ power function to observe changing channel geometries in supply-limited fluvial systems (as in Gimbert et al., 2016), but are unable to identify a particular source mechanism.”

The original manuscript contained (on Page 20 Line 28-30) a sentence that addresses the vertical component power scaling (without polarization analysis): “We observe similar scaling relationships for the vertical component power, with 2006, 2011, and pre-crisis 2017 scaling as $P_W \propto Q^{1.74-1.98}$ and post-crisis 2017 scaling as $P_W \propto Q^{3.26}$.” For clarity, we inserted the parenthesis now on (Page 19 Line34 and Page 20 Lines1-2) so the sentence now reads:

“We observe similar scaling relationships for the vertical component power (without polarization analysis), with 2006, 2011, and pre-crisis 2017 scaling as $P_W \propto Q^{1.74-1.98}$ and post-crisis 2017 scaling as $P_W \propto Q^{3.26}$.”

15. *Figure 7: Zero discharge azimuths are actually somewhat well determined at a wide range of frequencies. It is true that azimuths are better determined for other times, but only relatively so. So, some discussion should be modified.*

Thanks for helping us see the glass half full ☺. We modified P15L3 to be “somewhat variable”

16. *P14L24: m/s Units are incorrect*

Thank you, fixed

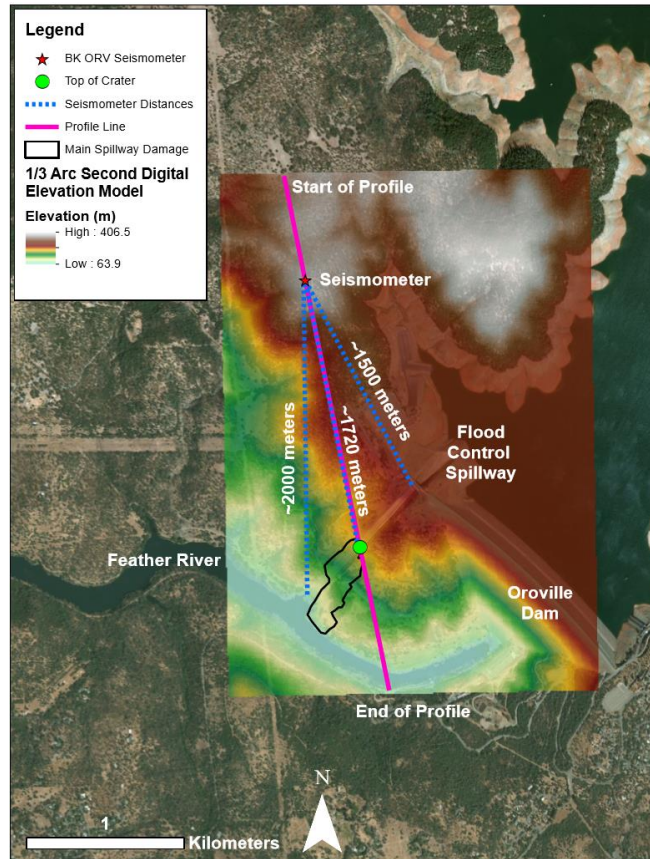
17. *P15L1: m/s Again units are incorrect*

Thank you, fixed

18. P16L26: Do these simulations use uniform velocities? If so, this might yield misleading results, since a more realistic structure in which velocities increase with depth naturally have stronger trapping of waves near the surface, and thus stronger surface waves. (If simulations use non-uniform velocities, that should be clarified as well.) Partly for this reason, it is not clear how much of this section's analysis really explains the deviations discussed.

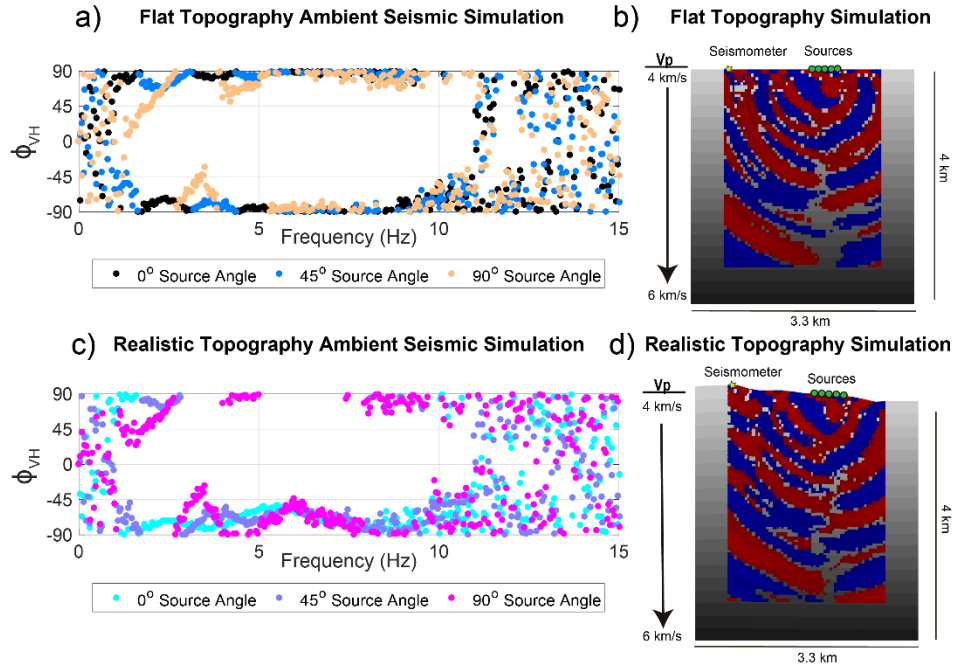
The simulations as shown in the manuscript used a uniform velocity structure, though we recognize the potential for a velocity structure to influence the results. This comment and comments by Reviewer #2 motivated us to conduct a series of new simulations:

- Introduce a linearly-increasing V_p from 4 km/sec to 6 km/sec while maintaining the Poisson solid assumption.
- Increased the depth of the model domain from 1 km to 4 km to minimize potential effect of domain edges.
- Change the dominant frequencies of the source, which were 0.1 to 5 Hz and represented the largest increase in seismic energy from the spillway as shown in Figure 4. The new dominant source frequencies are between 5 to 10 Hz, which represent the greatest deviations from Rayleigh-like particle motions observed in Figure 7.
- We reduce the simulated time from six minutes to four minutes due to increased computation time due to the larger domain.
- We approximate the source of the seismic energy as along the flood control spillway channel. Due to the position of the spillway channel, the distance between the channel and the station has a range of approximately 500 meters. We simulate the distributed source of the seismic energy as five independently fluctuating point sources along 500 meters of the seismic profile. This simplification ignores the different in hillslope topographies encountered by waves travelling from the top of the spillway and the bottom of the spillway. The below figure is an updated version of Figure S3 in the supplemental materials showing the configuration of the spillway.



- We add random noise to the resulting synthetic seismogram to represent the background seismic energy excited by other sources.

The results of the simulations after making these changes are similar to but much more realistic than those from previous simulations. The simulation with a realistic topography shows a deviation from a Rayleigh-like particle motion of $\pm 90^\circ$ to $\pm 45^\circ$ between 5 and 10 Hz, which is similar to the results presented in Figure 7. The updated Figure 9 showing the simulation results is below.



Since our simulations do not consider anisotropy or other possible velocity structures, we softened how we discuss the implications of the simulations. In the abstract, we change “...though numerical modelling indicates these deviations are explained by propagation up...” to “...though numerical modelling indicates these deviations may be explained by propagation up...”. We also change the P21L32-33 to “...but our SPEC2D modeling indicates that realistic topography is also a viable explanation for the polarization attributes we observe, noticeably ϕ_{VH} .”.

19. P17L9: *In a uniform velocity medium with a slope, surface waves simply travel along the slope, rather than horizontally. Part of the complexity shown and cited is due to the non-uniformity of the slope, not just the existence of a slope. This should be clarified.*

We agree, and clarify this point by inserting “irregular hillside topography” on P17L18 and on P18L15 we replace “... seismic waves propagate up-slope.” with “... propagate up a non-uniform slope.”

20. P18L23: *Again, why does greater turbulence imply a change in exponent? This argument needs to be fleshed out, and would add significantly to the conclusions if it can be done quantitatively. It is interesting that the Gimbert model appears to work better during pre-crisis times, but the reason it does not work later should be more specific than the generic ‘greater turbulence’ statement, since greater turbulence would also just be expected at higher flow rates within the same model.*

We addressed this in the response to Comment 14 above. One limitation of this study is that we do not have quantitative information on the turbulence within the flood control spillway. To make this clearer, we inserted the following sentence in P23L27-28: “Due to the hazardous conditions surrounding the spillway channel, inferences on the mechanisms and degree of turbulence are limited to interpretations of aerial photography.”

Reviewer #2 (Anonymous) Comments

1. *Page 2, Line 28. In this case are the authors referring to changes in channel geometry with time and/or spatially within the channel?*

For clarity, “channel geometry variations” has been changed to “deviations from spatial uniformity” on P2L28.

2. *Fig. 1 The bifurcation of the flood control spillway is clear, but the location and type of damage to the emergency spillway is not easy to see. Is the emergency spillway damage meant to refer to the few meters of erosion that appear to be almost uniform along it in the elevation difference map?*

The figure was updated to have consistent labeling with panel b, the label size was increased, and the outline of the emergency spillway damage was added. The colorscale was also changed to highlight the erosion damage.

3. *Page 11 and Fig. 6. Confidence intervals for the discharge exponent values ‘pre’ and ‘post-chasm’ would be useful information. There appears to be a compelling difference, but an attempt to quantify the uncertainty would be an improvement.*

We inserted a table of the 95% confidence intervals of the power function coefficients and exponents. The table as inserted is below:

Time Interval	Logarithm of Coefficient (Base 10)	95% Confidence Intervals		Exponent	95% Confidence Intervals	
		Lower Bound	Upper Bound		Lower Bound	Upper Bound
2017 Pre-Crisis	-18.055	-18.438	-17.671	1.7452	1.6016	1.8888
2017 Post-Crisis	-22.033	-22.225	-21.841	3.2602	3.1965	3.3238
2006 Release	-17.994	-18.225	-17.763	1.6994	1.6157	1.783
2011 Release	-18.207	-18.448	-17.967	1.8698	1.7776	1.962

Table 1: Coefficients, exponents, and uncertainty for power functions fit by least-square regression (shown in Fig. 6).

4. *Fig. 7. The authors might consider labeling the azimuth corridor that corresponds to the spillway as a handy visual reference. But I understand that it may not be ideal if it obstructs other information.*

We added dashed lines indicating the azimuth corridor and added the following sentence to the figure 7 caption: “Dashed lines in the first column of figures indicates the azimuth range of the spillway relative to the seismometer (See Fig. 1).”

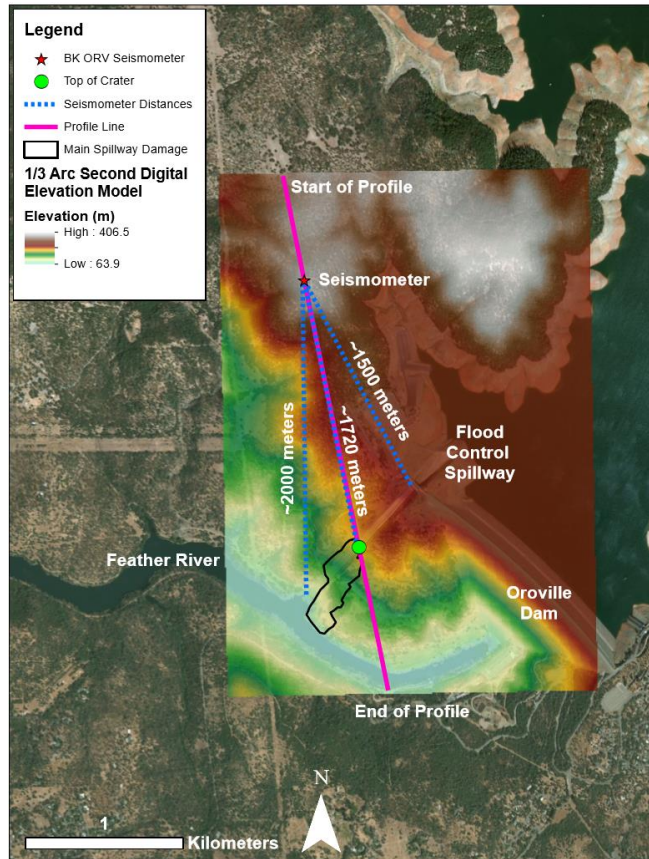
5. *Section 4.7. This is a good attempt at estimating the effect of topography on the polarization results, and the authors acknowledge some of the limitations of the 2D simulation. I would suggest a bit of additional caution regarding the simple velocity model because the frequency dependent polarization of surface waves could be strongly affected by depth-dependent (and spatially variable) velocity structure likely including anisotropy. I agree that the modeling effort presented provides a viable explanation for some*

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of the deviation from idealized surface wave propagation without topography, I'm just encouraging clear description of its limitations.

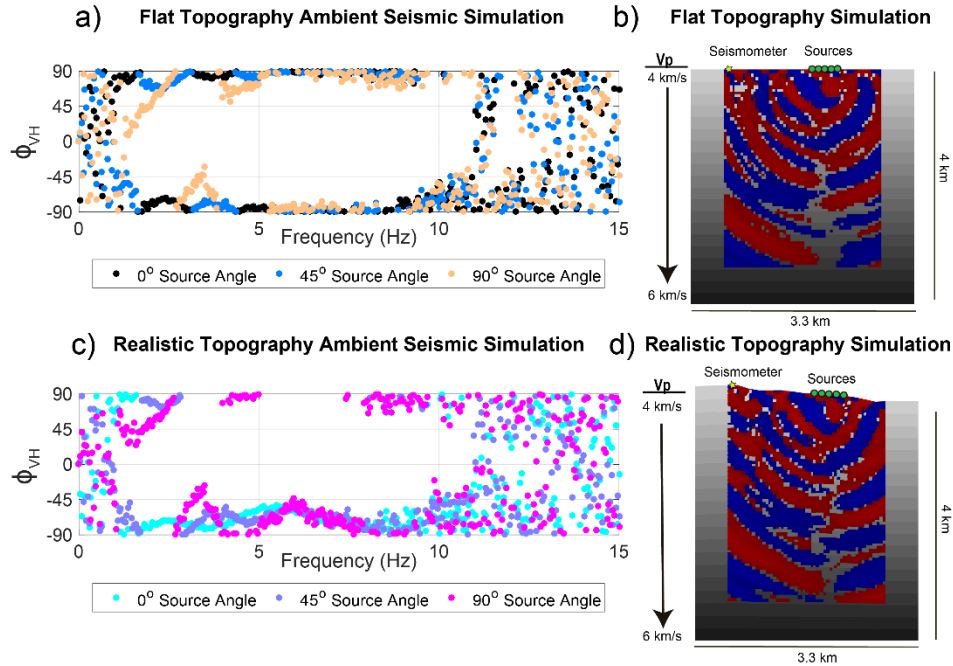
The simulations as shown in the manuscript used a uniform velocity structure, though we recognize the potential for a velocity structure to influence the results. This comment and comments by Victor Tsai (Reviewer #1) motivated us to change our simulation in the following ways:

- Introduce a linearly-increasing V_p from 4 km/sec to 6 km/sec while maintaining the Poisson solid assumption.
- Increased the depth of the model domain from 1 km to 4 km to minimize potential effect of domain edges.
- Change the dominant frequencies of the source, which were 0.1 to 5 Hz and represented the largest increase in seismic energy from the spillway as shown in Figure 4. The new dominant source frequencies are between 5 to 10 Hz, which represent the greatest deviations from Rayleigh-like particle motions observed in Figure 7.
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- We add random noise to the resulting synthetic seismogram to represent the background seismic energy excited by other sources.

The results of the simulations after making these changes are similar to but much more realistic than those from previous simulations. The simulation with a realistic topography shows a deviation from a Rayleigh-like particle motion of $\pm 90^\circ$ to $\pm 45^\circ$ between 5 and 10 Hz, which is similar to the results presented in Figure 7. The updated Figure 9 showing the simulation results is below.



Since our simulations do not consider anisotropy or other possible velocity structures, we softened how we discuss the implications of the simulations. In the abstract, we change “...though numerical modelling indicates these deviations are explained by propagation up...” to “...though numerical modelling indicates these deviations may be explained by propagation up...”. We also change the P21L32-33 to “...but our SPEC2D modeling indicates that realistic topography is also a viable explanation for the polarization attributes we observe, noticeably ϕ_{VH} .”.

6. *Section 4.7. and Fig. 9. Is the oscillating VH angle in Figure 9 because only one point source is considered? Would it be more realistic to sum the seismograms with staggered time shifts to simulate a temporally continuous and spatially distributed source process*

Thank you very much for this helpful suggestion! As you suggest, we now approximate a distributed source by five point sources that independently fluctuate with a dominant source frequency of 5-10 Hz. We also add in a low level of random noise to resulting synthetic seismograms to approximate background seismic noise. The oscillating VH angle behavior is diminished from both of these steps, and we believe the VH angle behavior is more realistic.

7. *Discussion. The difference in exponent ‘pre’ and ‘post-chasm’ is interesting, and even though there is not a clear explanation for it I think the higher exponent is a useful target for future studies. In regard to comparison with the Gimbert et al. model I wonder if the extreme steepening of the channel to essentially a waterfall into the ‘chasm’ is beyond the limits of the model formulated by Gimbert et al or if they actually thought the model assumptions would still be reasonably well justified in that setting?*

Clarified in the discussion. A waterfall certainly violates the assumption of the model. We make this more explicit in the discussion on P20L10-12 by including the sentence “A waterfall will violate assumptions in the

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Gimbert et al. (2014) model formulation and lead to greater water velocities (from free fall) impacting the bed than would be found in a continuous turbulent channel flow.”

The supplementary material is used appropriately and will be valuable to researchers in the field.

Thank you.

8. Continuous line numbering would be more helpful for review, but maybe that's a journal policy.

We agree, but page-based line numbering is derived from the journal template's format.

Seismic signature of turbulence during the 2017 Oroville Dam spillway erosion crisis

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Abstract

Knowing the location of large-scale turbulent eddies during catastrophic flooding events improves predictions of erosive scour. The erosion damage to the Oroville Dam flood control spillway in early 2017 is an example of the erosive power of turbulent flow. During this event, a defect in the simple concrete channel quickly eroded into a chasm 47 meters deep.

10 Erosion by turbulent flow is difficult to evaluate in real time, but near-channel seismic monitoring provides a tool to evaluate flow dynamics from a safe distance. Previous studies have had limited ability to identify source location or the type of surface wave (i.e. Love or Rayleigh wave) excited by different river processes. Here we use a single three-component seismometer method (Frequency-Dependent Polarization Analysis) to characterize the dominant seismic source location and seismic surface waves produced by the Oroville dam flood control spillway, using the abrupt change in spillway geometry as a natural

15 experiment. We find that the scaling exponent between seismic power and release discharge is greater following damage to the spillway, suggesting ~~larger turbulent eddies excite~~ additional sources of turbulent energy dissipation excite more seismic energy. The mean azimuth in the 5-10 Hz frequency band was used to resolve the location of spillway damage. Observed polarization attributes deviate from those expected for a Rayleigh wave, though numerical modelling indicates these deviations ~~are may be~~ explained by propagation up the uneven hillside topography. Our results suggest Frequency-Dependent Polarization

20 Analysis is a promising approach for locating areas of increased flow turbulence. This method could be applied to other erosion problems near engineered structures and to understanding energy dissipation, erosion, and channel morphology development in natural rivers, particularly at high discharges.

1 Introduction

Dam spillways are typically designed with features that generate controlled turbulent eddies, such as steps or changes in slope. These eddies entrain air into the flow, increase energy dissipation, and lower the mean flow velocity (Hunt and Kadavy, 2010a; Hunt and Kadavy, 2010b). Some of this dissipated energy is transferred as lift and drag forces on the bottom of the spillway channel. If a defect in the spillway channel is present, increased turbulence and associated forces can quickly enlarge the defect, eroding the spillway and underlying embankment (USBR, 2014). In some cases, erosion propagates headwards, undermining the structural integrity of the dam (USBR, 2014). Structural elements and routine maintenance are designed to minimize these channel defects, however, they can develop quickly during extreme flows. Therefore, real-time monitoring of spillway turbulence during times of high release could provide early warning of the onset of erosion. Although turbulence can be characterized with photographic images or measurements of velocity time series with submerged or overhead instrumentation, these procedures may be impractical on large structures or during catastrophic events. Seismic monitoring may provide a way to continuously evaluate turbulent intensity and associated erosion from safely outside channels or hydraulic structures.

Seismic waves have previously been used to characterize the geotechnical suitability of earthen dams and internal dam seepage using passive seismic interferometry (e.g. Planès et al., 2016), but have not been used to characterize open-channel turbulence in dam spillways. ~~Because T~~turbulence affects erosional processes in both hydraulic structures and natural rivers, ~~therefore,~~ techniques from the seismic river monitoring (fluvial-seismic) literature provide guidance. In the past decade, many authors have used near-channel seismometers to monitor rivers during monsoons (e.g. Burtin et al., 2008); natural floods (e.g. Govi, et al., 1993; Hsu, et al., 2011; Burtin et al., 2011; Roth et al., 2016) and controlled floods (Schmandt et al., 2013; Schmandt et al., 2017). In many of these studies, the authors seek to separate the various sources of seismic energy, including precipitation, bedload transport, and flow turbulence (e.g. Roth et al., 2016). Bedload transport is traditionally difficult to monitor, therefore, research has been focused on isolating this source. Characterizing turbulence in rivers has been given less consideration in the fluvial-seismic literature, even though macroturbulent eddies place important controls on channel erosion (Franca and Brocchini, 2015) and may be important in spillway erosion. A forward mechanistic model by Gimbert, et al. (2014) estimates the power spectral density of seismic energy produced by turbulently flowing water in a simple rectangular channel, in principle making it possible to use seismic data to invert for river depth and bed shear stress. This model, however, is based on assumptions of spatially uniform turbulence created by bed grain size; it ignores other sources of turbulence common in natural rivers and in engineered structures such as ~~channel geometry variations~~deviations from spatial uniformity. Recent work (Roth, et al., 2017) suggests that hysteresis between seismic power and discharge may also result from riverbed particle rearrangement, which leads to different turbulent characteristics within the flow. This fluvial seismic body of work suggests seismic monitoring may be able to resolve hydraulic changes ~~in even~~ in a dam spillway setting.

A near-spillway seismometer records seismic energy excited by a number of sources from different directions across a range of frequencies. These potential sources include primary and secondary microseisms, anthropogenic noise, wind, rain,

earthquakes, and nearby rivers. Without a way to differentiate among these sources by direction and frequency, interpreting seismic observations will be limited. This challenge was highlighted by Roth et al. (2016) and Roth et al. (2017), who indicated that the turbulent signal from a waterfall downstream of their study river reach may have dominated the observed low-frequency signals. Previous studies have attempted to locate the source of fluvial seismic energy by using arrays of seismometers, primarily by observing the variability in seismic amplitudes around the river section of interest (Burtin et al., 2011, and Schmandt et al., 2017). A study by Burtin, et al. (2010) developed noise correlation function envelopes to identify segments of the Trisuli River that generated the most seismic energy at a given frequency. The greatest coherence between seismometer pairs (and inferred greatest seismic energy production) was located along river segments with the steepest river slopes and highest estimated incision rates. This approach is a promising one, though it requires an extensive array of seismometers. A single-seismometer method for distinguishing various sources of seismic energy at different frequencies is more likely to be implemented in monitoring hydraulic structures and may be advantageous for fluvial seismic studies.

Discerning among seismic sources using a single station requires an evaluation of the three-dimensional ground motion recorded by a three-component seismometer. In traditional earthquake seismology, these motions indicate the arrival of body waves (P and S) and surface waves (Rayleigh and Love). For continuous ambient seismic sources such as turbulence, the phase relationships between the signals in each component can provide information on the wave type and its propagation direction. Several researchers have suggested that turbulence may excite Rayleigh surface waves whereas sliding and rolling bedload transport may excite Love surface waves, though these authors relied on comparing the seismic power of the three components rather than analyzing phase relationships among the components (Schmandt et al., (2013); Barrière et al., (2015); Roth et al., (2015)). While recent forward models to estimate the power spectral density of seismic energy produced by moving bedload and turbulently flowing water can accommodate the excitation of various seismic waves, their applications to date also assume that only Rayleigh waves are excited (Tsai et al., 2012; Gimbert et al., 2014). This, though these assumptions have not been quantitatively tested (Tsai et al., 2012; Gimbert et al., 2014). Identifying the surface wave type excited by turbulent sources will help to identify the dominant mechanisms generating seismic waves in spillways and natural channels.

In this study we employ a single-seismometer method to observe variations in turbulence intensity and location within a dam spillway. Our goals are to 1) evaluate the scaling exponent between seismic power and discharge for different turbulence and channel roughness conditions; 2) determine if a single-seismometer source location technique can be used to resolve changes in the location of flow turbulence in a spillway channel; and, 3) evaluate the surface wave type excited by spillway turbulence and erosion. The study site is the flood control spillway of the Oroville Dam, California, USA. Seismic and discharge data collected during the erosional event that damaged the flood control spillway in February and March 2017 provide a natural experiment for this study, during which a simple and straight channel was abruptly eroded into a complex one.

2 Oroville dam crisis

The Oroville dam, located 100 km north of Sacramento, CA in the Sierra Nevada foothills, is the tallest dam in the United States (Fig. 1a). The dam spans the Feather River and provides hydroelectric power, flood control, and water storage for irrigation. Completed in 1968, the dam is constructed on Mesozoic volcanic rocks contained in the Smartville Complex (Saucedo and Wagner, 1992). The dam is built adjacent to the Long Ravine Fault; therefore, a permanent seismic station was placed approximately 2 km from the dam site in 1963 to monitor possible reservoir-induced earthquakes (Lahr et al., 1976). Several studies have linked the unusually large drawdown and refilling of the reservoir in 1974-1975 to a 5.7 magnitude earthquake on 1 August 1975 located 12 km south of the reservoir (Beck, 1976; Lahr et al., 1976). In 1992, the Berkeley Seismological Laboratory installed a Streckeisen STS-1 broadband three-component seismometer at the site as station BK ORV (BDSN, 2017). We are not aware of any studies that have investigated ground motion generated by the flood control spillway.

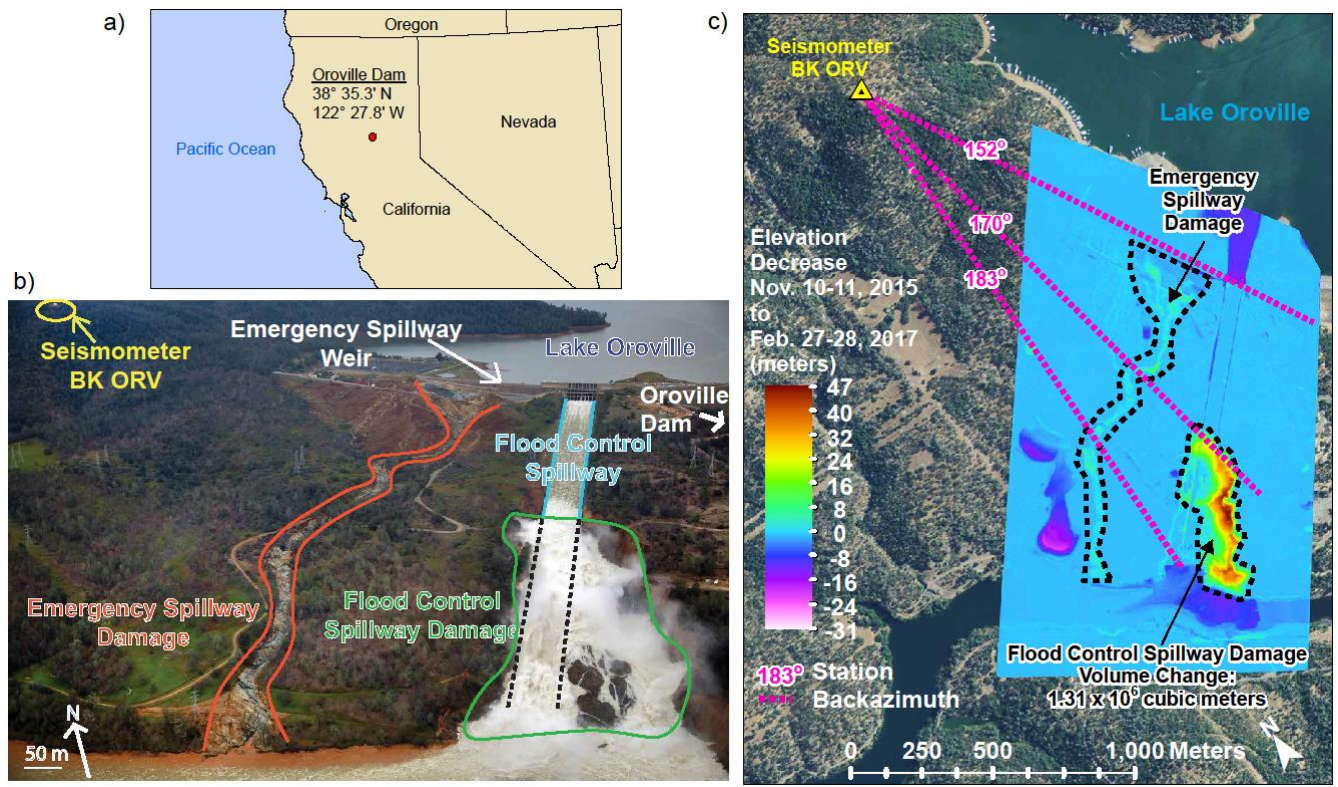


Figure 1: a) Location of the Oroville Dam in Northern California. b) The damage created along the Flood Control and Emergency Spillways of Oroville Dam in February and March, 2017. The seismometer used in this study is located approximately 2 km from the spillway. Photo credit: Dan Kolke, Department of Water Resources. Image taken on 2/15/2017. Estimated discharge during photograph is $2,800 \text{ m}^3 \text{ s}^{-1}$. c) A digital elevation model created from LiDAR points provided by the California Department of Water Resources. The elevation difference from a November 2015 elevation survey and a late February 2017 survey shows that the crisis incised a chasm up to 47 m deep. The volume of the main chasm is $1.3 \times 10^6 \text{ m}^3$. The incision resulting from the use of the emergency spillway is less than 20 m deep. The back-azimuth (clockwise from north) in degrees is displayed for the top of the flood control

spillway, the top of the chasm, and the bottom of the flood control spillway. The seismometer is at an average 13° slope above the base of the flood control spillway and an average 8° slope above the top of the flood control spillway.

At approximately 9 am PST on February 7th, 2017, during a controlled dam release of approximately 1400 m³ s⁻¹, a section of the concrete flood control spillway failed, leaving a defect in the spillway. A subsequent preliminary root cause analysis identified construction and maintenance flaws as the source of this initial defect (Bea, 2017; ODSIIFT, 2017a; ODSIIFT, 2017b). Ongoing heavy rainfall and runoff from the upstream watershed filled the reservoir to near capacity. Reservoir managers increased the discharge through the damaged spillway in a series of tests and ultimately raised the discharge to over 1500 m³ s⁻¹. This discharge and associated high flow velocities resulted in turbulent scour around the defect, rapidly eroding the underlying embankment and incising a gully that bypassed the concrete spillway channel. Dam managers then limited the flood control spillway discharge to below 1800 m³ s⁻¹ (California Department of Water Resources, 2017a). High incoming discharge from the Feather River raised the reservoir level to capacity, which activated an emergency spillway weir for the first time in the dam's 48-year history.

Discharges up to 360 m³ s⁻¹ flowed over the emergency spillway weir beginning at 8:00 am PST on February 11th while managers released approximately 1500 m³ s⁻¹ through the primary flood control spillway. Within 32 hours, rapid erosion at the base of the emergency spillway weir threatened to compromise its stability, triggering concerns of catastrophic failure. Managers increased the discharge through the previously damaged flood control spillway to 3000 m³ s⁻¹ and evacuated 180,000 people from the downstream city of Oroville, California. Elevated flood control spillway discharges lowered the reservoir level and stopped discharge through the emergency spillway weir on February 12th, 38 hours after activation. Elevated discharges continued through the damaged flood control spillway through the end of March, causing tens of meters of vertical incision into the weathered, sheared bedrock underlying the spillway (Bea, 2017). Figures 1b and 1c show the position of the seismometer and erosion incurred during the event. The seismometer is 1.4 km from the top of the flood control spillway channel and 1.9 km from the bottom of the -Usingchannel. Using LiDAR data collected in 2015 and March 23rd, 2017, we compute that 1.3 x 10⁶ m³ of material were removed from the flood control spillway damage area during the crisis, resulting in a vertical incision into the hillside of up to 47 m (Fig. 1c; see Supplemental Information) (California Department of Water Resources, 2017b).

3 Methods

3.1 Data collection and approach

In this study, we evaluate seismic signals detected during the Oroville Dam Erosion Crisis at broadband seismometer BK ORV, operated by the Berkeley Digital Seismological Network (BDSN, 2017). We divide the crisis period into five time intervals of constant discharge, each of which is longer than 15 hours in duration (Fig. 2). During each of these discharge intervals, channel geometry and discharge remain similar, allowing us to document the differences across intervals in the spillway-generated seismic signal. The five time intervals of interest are:

- 1) “Pre-Chasm” interval: 18 hours of $\sim 1400 \text{ m}^3 \text{ s}^{-1}$ routine flood control spillway release before the initial spillway damage on February 7th,
- 2) “Emergency Discharge” interval: 38-hour interval when the emergency spillway weir was active and $\sim 1500 \text{ m}^3 \text{ s}^{-1}$ was released through the flood control spillway
- 3) “High Discharge” interval: 78-hour interval when $\sim 3,000 \text{ m}^3 \text{ s}^{-1}$ were released through the damaged flood control spillway,
- 4) “Post-Chasm” interval: 87-hour interval of $\sim 1400 \text{ m}^3 \text{ s}^{-1}$ discharge through the damaged flood control spillway, and
- 5) “Zero Outflow” interval: 93-hour interval of zero discharge through the flood control spillway, which serves as a control interval.

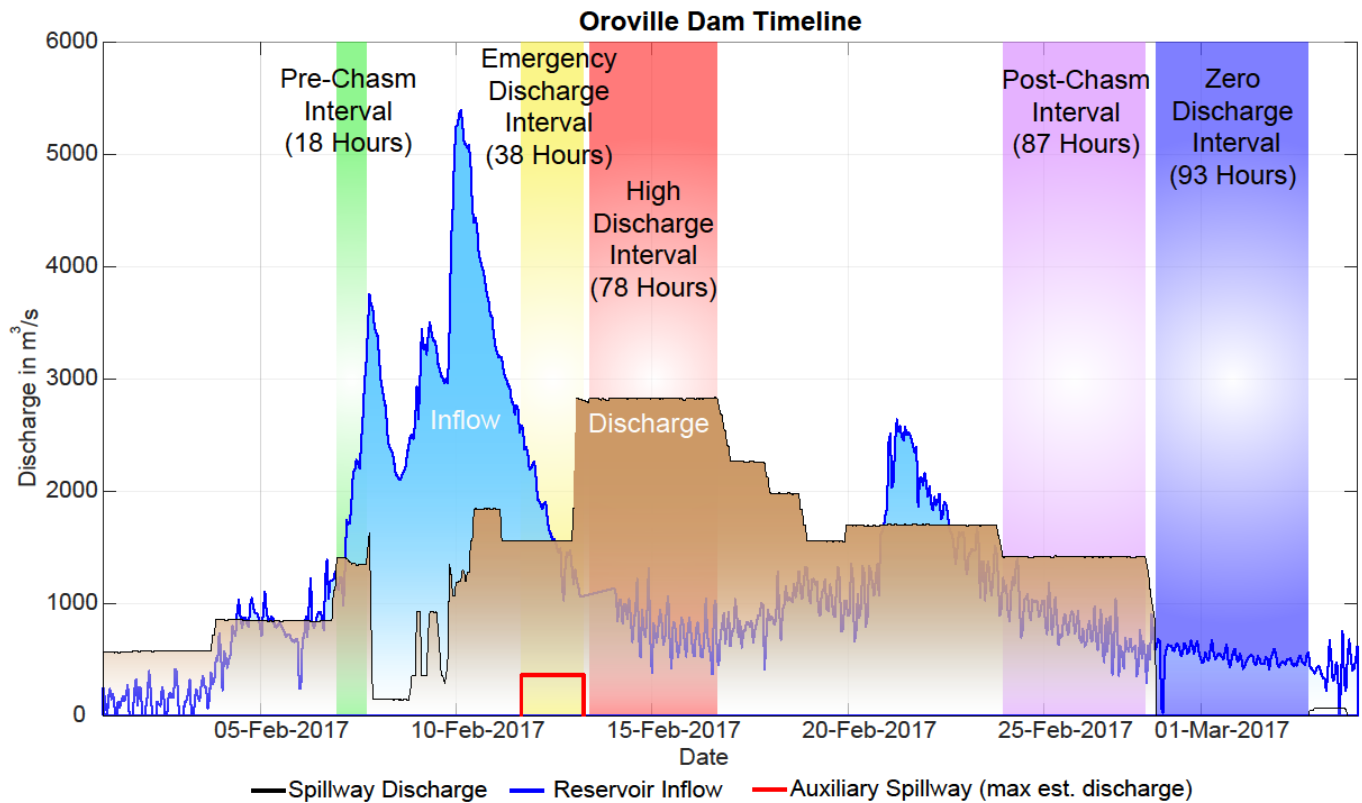


Figure 2: Discharge and inflow at Oroville Dam in early 2017, as reported by the California Department of Water Resources. The five time intervals of constant discharge in early 2017 used in this study are highlighted and labeled. The “Pre-Chasm” and “Post-Chasm” time intervals have approximately equal discharge, but very different channel geometries. Data gaps in discharge and inflow data are linearly interpolated in this figure. The inflows reported are from the Feather River to Lake Oroville. The discharge displayed for the emergency spillway weir is the maximum reported by CA DWR media updates, as no quantified measurements have been published for this data.

To encompass the erosion crisis period, we compiled seismic data and spillway discharge data from 1/1/2017 to 4/1/2017. For comparison to the erosion crisis, we also compiled seismic data and spillway discharge for the second and third highest release periods during which continuous discharge and seismic data are available. These intervals are from 02/25/2006 to 03/18/2006 and 03/01/2011 to 06/01/2011. The seismic and discharge data for these intervals were processed identically to the 2017 data. The Northern California Earthquake Data Center is the source of the seismic data for this study and instrument response was causally removed (Haney et al., 2012). The California Department of Water Resources' California Data Exchange Center is the source of all discharge data reported in this study (California Department of Water Resources, 2017c).

3.2 Frequency dependent polarization analysis

We expect that contributions to spillway-generated seismic energy will produce energy across a range of frequencies, analogous to observations in natural channels (Gimbert et al., 2014). Energy sources in different frequency bands may also exhibit excite a variety of seismic wave types, which result in different ground particle motions and seismic amplitudes. We extract particle motion polarization attributes at each frequency by applying Frequency Dependent Polarization Analysis (FDPA) to the single-station three-component data (Park et al., 1987). The approach in this study is similar to ambient noise analysis applied to seismometer networks, in which the particle motion from ambient noise is characterized (e.g. McNamara and Buland, 2003; Koper and Hawley 2010; Koper and Burlacu, 2015). Following Koper and Hawley (2010), for each component (u_x , u_y , u_z), an hour of record (as ground velocity) is selected and divided into 19 sub-windows that each overlap 50%. Each sub-window is tapered with a Hanning window, converted to ground acceleration, and the Fourier transform is computed. At each frequency considered (up to the Nyquist half the sampling frequency), the Fourier coefficients from each of three components are arranged into a 3x19 matrix, from which the 3x3 cross-spectral covariance matrix is estimated. The eigenvector corresponding to the largest eigenvalue of each 3x3 matrix describes the particle motion ellipsoid within the hour of observation at each frequency (Park et al., 1987). Henceforth, we refer to this as the dominant eigenvector. The complex-valued coefficients of this dominant eigenvector describe a particle motion ellipsoid at each frequency, whose properties are analyzed in this paper. The time averaging inherent to this methodology minimizes the influence of transient seismic sources such as earthquakes or intermittent anthropogenic noise. The application of FDPA is useful for identifying polarization characteristics at a range of frequencies, yet for weakly polarized seismic energy the polarization attributes are highly variable with time. Therefore, it is more meaningful to analyze the probability distributions of polarization attributes in time intervals of similar strong seismic polarization (Koper and Hawley, 2010).

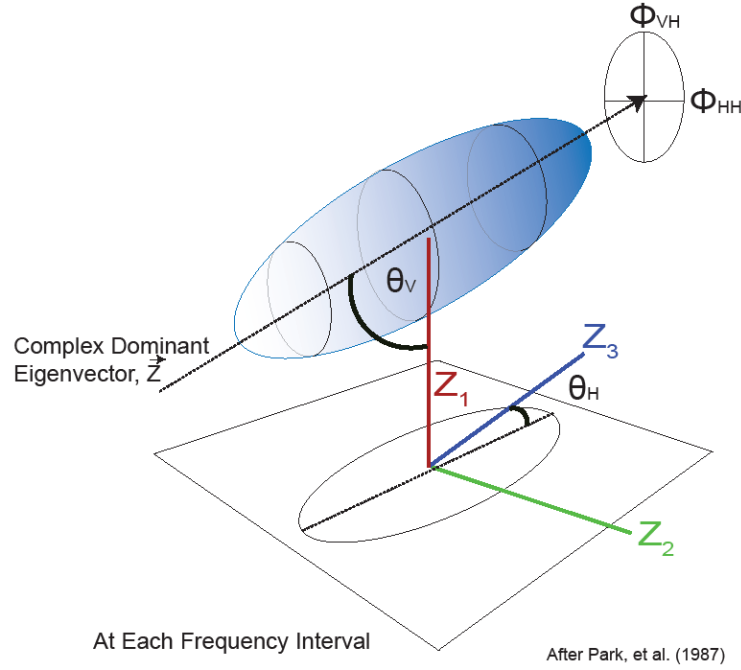


Figure 3: Diagram of particle motion defined by the dominant eigenvector. The particle motion at each frequency is analyzed by considering the dominant eigenvector of the spectral covariance matrix; the complex-valued components of this eigenvector can be visualized as describing a particle motion in an ellipsoid (Park, et al.,1987). The orientation of the eigenvector and the phase relationships between the components of the eigenvector yield the polarization attributes.

We compute the polarization attributes used in this paper from the complex components of the dominant eigenvector, $\vec{Z} [z_1, z_2, z_3]$ (Fig. 3). For the benefit of the reader, we briefly summarize their computation below and refer the reader to Park et al. (1987) for additional discussion. Each complex component of \vec{Z} can be thought of as describing the particle motion at a particular frequency in each of the three orthogonal directions. The azimuth (θ_H) of the ellipsoid, measured clockwise-from-north, is computed-determined fromby calculating the angle between the horizontal components of z_2 and z_3 on the real plane when their horizontal acceleration is maximized:

$$\theta_H = \tan^{-1} \left[\frac{\text{Re}(z_3 e^{i\theta_h})}{\text{Re}(z_2 e^{i\theta_h})} \right] \frac{\text{Re}(z_3 e^{i\theta_h})}{\text{Re}(z_2 e^{i\theta_h})}, \quad (1)$$

where θ_h is the phase angle at which the horizontal acceleration is maximized:

$$\theta_h = -\frac{1}{2} \arg(z_2^2 + z_3^2) + \frac{l\pi}{2} \quad (2)$$

and which is determined bywhere- l - is corresponds to the lowest-smallest non-negative integer value that maximizes the expression:

$$|z_2|^2 \cos^2(\theta_h + \arg(z_2)) + |z_3|^2 \cos^2(\theta_h + \arg(z_3)) \quad (3)$$

The range of Θ_H is restricted such that $0^\circ < \Theta_H \leq 180^\circ$ if $Re(z_1 z_3^*) < 0$ and $180^\circ < \Theta_H \leq 360^\circ$ if $Re(z_1 z_3^*) \geq 0$.

Analogously, the angle of incidence (Θ_V), measured from the vertical, is computed from the major axis of the particle motion ellipsoid by finding the angle on the real plane between the vertical axis, z_1 , and the total horizontal acceleration, z_H as:

$$\Theta_V = \tan^{-1} \left[\left| \frac{Re(z_1 e^{i\theta_v})}{Re(z_H e^{i\theta_v})} \right| \right] \left| \frac{Re(z_1 e^{i\theta_v})}{Re(z_H e^{i\theta_v})} \right|, \quad (4)$$

where: $z_H = \sqrt{z_2^2 + z_3^2}$ (5)

where θ_v is the phase angle at which total acceleration is maximized:

$$\theta_v = -\frac{1}{2} \arg(z_1^2 + z_2^2 + z_3^2) + \frac{m\pi}{2} \quad (56)$$

and which is determined by where m_i corresponds to the lowest-smallest non-negative integer that maximizes the expression:

$$|z_1|^2 \cos^2(\theta_v + \arg(z_1)) + |z_2|^2 \cos^2(\theta_v + \arg(z_2)) + |z_3|^2 \cos^2(\theta_v + \arg(z_3)) \quad (67)$$

If $Im(\sqrt{z_2^2 + z_3^2}) < 0^\circ$, the sign is reversed to restrict Θ_V such that $0^\circ < \Theta_V \leq 90^\circ$.

We consider two additional angles to describe the particle motion. First, the phase angle difference between the two horizontal components z_2 and z_3 (ϕ_{hh}) of the primary eigenvector, restricted to within -180° and 180° ; and second, the vertical-horizontal phase angle difference (ϕ_{vh}), computed from the phase angle difference between θ_h (Eq. 2) and z_1 , restricted to lie between -90° and 90° . Following Koper and Hawley (2010), we also compute the degree of polarization (β^2) defined by Samson (1983), which is zero when the three component eigenvalues are equal, and is one when the data are described by a single non-zero eigenvalue, such as for a single propagating seismic wave. We emphasize that FDPA methods characterize the dominant seismic source rather than describing the distribution-particle motion associated with of all sources of seismic energy.

4 Results

In the following analysis, we present the polarization attributes in one hour intervals aligned with the hourly discharge data and assume each hour has a consistent seismic character. We then evaluate the variability of all of the hourly polarization attributes within each constant discharge time interval and throughout the dam erosion crisis.

4.1 Seismic power variation with changing spillway discharge

We expect the seismic power generated by the flood control spillway to vary with spillway discharge. The power associated with the principal-dominant eigenvector of the FDPA polarization ellipsoid during the five constant-discharge time intervals is shown in fig 4. In the figure, the mean hourly power values within each time interval are plotted with a one-

standard-deviation envelope representing the variability in power within each constant-discharge interval. In all five time intervals of interest, a microseismic peak between 0.1 and 0.3 Hz is visible, consistent with the ocean-generated microseism (McNamara and Buland, 2004). Interestingly, there is greater “Pre-Chasm” power at frequencies below 0.05 Hz and around 0.25 Hz than the three time intervals after the chasm has developed. This may be attributable to variability in wave heights in the northern Pacific Ocean. The greatest difference between the “Zero Discharge” and all other time intervals is in the 0.5-5 Hz frequency range, with differences of up to ~30 dB between the “Zero Discharge” and “High Discharge” intervals. Spillway turbulence is therefore observable in this frequency band, even before the beginning of the erosion crisis. Between 0.5 and 1 Hz, the difference in power between the approximately equal discharge “Pre-Chasm” and “Post-Chasm” time interval is greatest, suggesting that increased turbulence resulting from the spillway damage is observable in this frequency band. In the rest of this study, we focus on this frequency range (0.5 to 1 Hz) to evaluate scaling in seismic power and discharge, though differences in the signal are visible across a broad frequency band (0.2 and 12 Hz). At 0.7 Hz, a peak is prominent in the “Post-Chasm” power, possibly reflecting that the “Post-Chasm” time interval has the most eroded and incised channel shape~~complex channel geometry~~. These observations indicate seismic power during the five constant-discharge time intervals is sensitive to the turbulent intensity, as inferred from channel geometry.

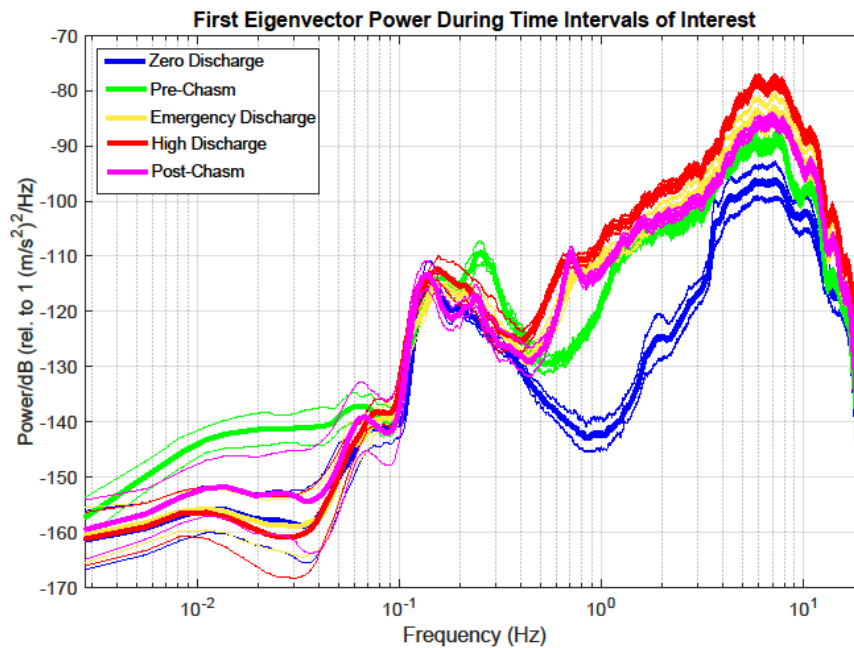
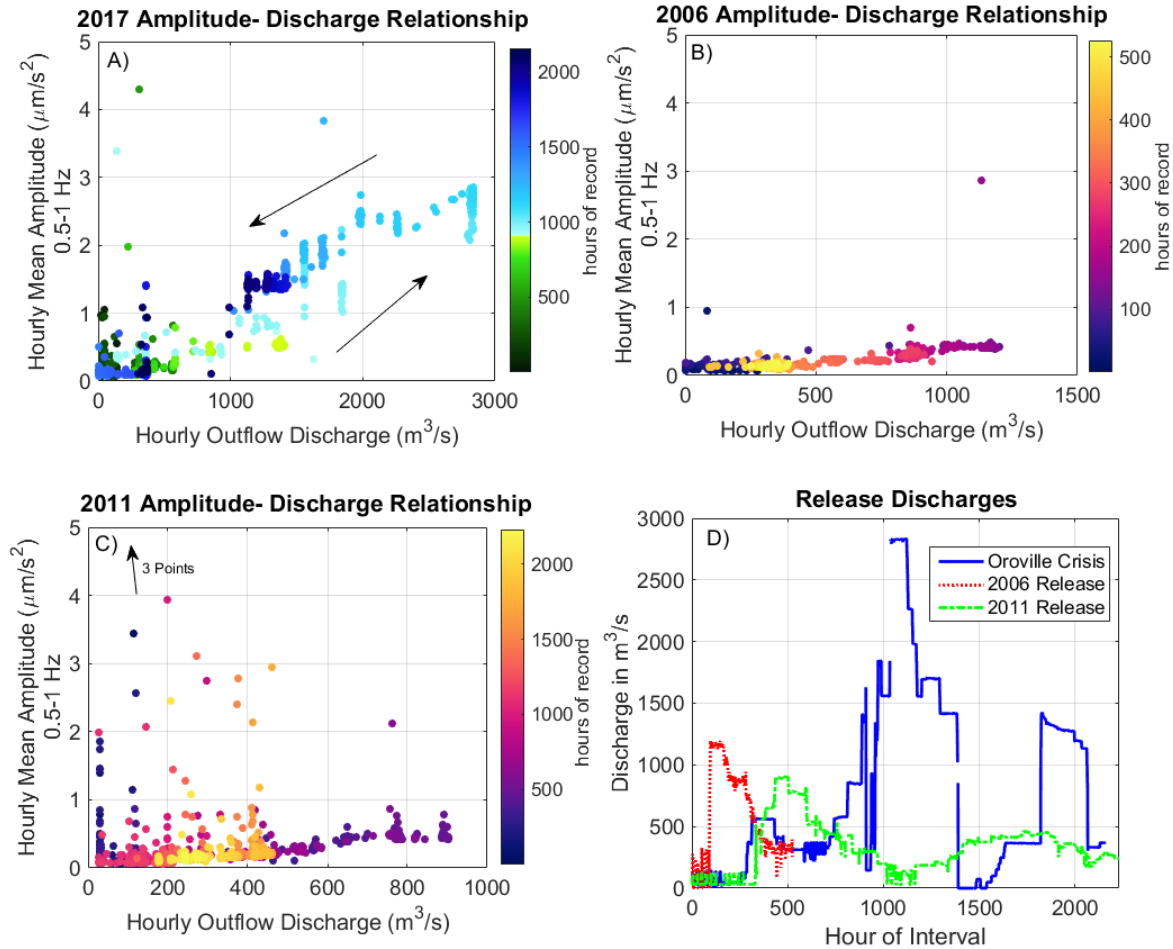


Figure 4: Power-per-frequency output for each of the five studied intervals, shown with one standard deviation error bars. There is a significant increase (up to 30dB) in the average power of this eigenvector during the four time intervals with discharge, particularly between 0.5 and 12 Hz. The power during three time intervals following spillway damage exceeds the ‘Pre-Chasm’ at frequencies above 0.5 Hz.

To further investigate the relationship between seismic power and variations in spillway discharge, we compute the hourly mean amplitude in the 0.5 to 1 Hz frequency band and compare it to discharge. In ~~fig~~Fig. 5, the hourly mean amplitude of the first-dominant eigenvector is shown for the 2017 crisis period (Fig. 5a) and the 2006 and 2011 release periods (Fig. 5b and Fig. 5c). Figure 5d shows the release discharges of the 2017, 2006, and 2011 releases. Counterclockwise hysteresis is present in the 2017 period containing the erosion crisis, which is not present in 2006 or 2011 periods which maintain a consistent channel form.



10 **Figure 5: The plot of mean hourly amplitude of the dominant eigenvector in the 0.5-1 Hz frequency band vs hourly discharge shows that the two correlate strongly. The abrupt change in the colorbar coincides with the timing of the Oroville Dam crisis, and allows two distinct regimes to be identified. Seismic amplitudes are greater by $\sim 0.5 \mu\text{m s}^{-1}$ after the uncontrolled channel erosion begins on February 7th, and remains greater even as discharge decreases to earlier levels, demonstrating that hysteresis is observed. This hysteresis is greatest in the 0.5-1 Hz frequency band. Note the changing x axis range in panels a through c.**

In figure 6a, the hourly mean power of the first-dominant eigenvector is shown for the entire 2017 interval of record as a function of discharge. There is significant variability in hourly mean power for intervals with low discharge, possibly related to other sources of noise including anthropogenic noise created during spillway repair efforts, wind noise, or distant fluvial or marine sources. The scaling of first eigenvector power appears to have a break in slope for low discharge. Below a discharge of approximately 200 m³ s⁻¹, there does not appear to be a relationship between dominant eigenvector power and discharge, which we interpret as the threshold discharge above which signals emanating from the Oroville spillway become the dominant source of seismic energy (i.e. the principal eigenvector of the particle motion ellipsoid in the FDPA). Figure S2 in the supplemental materials shows the dominant eigenvector power for all discharges. We limit our analysis of scaling between discharge and mean hourly eigenvector power to hours when discharge exceeded 200 m³ s⁻¹, and to hours with spillway use as reported by the California Department of Water Resources. In figure 6a, the scaling relationship between discharge (Q) and power before the crisis is: $P_w \propto Q^{1.75}$. After the spillway defect occurs, the scaling exponent is greater, with $P_w \propto Q^{3.26}$. Figures 6b and 6c display the power-discharge relationships for the 2006 and 2011 release periods. The scaling exponent for these release events is similar ($P_w \propto Q^{1.7069-1.887}$) to the pre-crisis scaling, though there is more scatter in the 2011 seismic record. The coefficients, exponents, and estimates of uncertainty are provided in Table 1. The change in the scaling relationship between discharge and seismic power is consistent with the inferred change in turbulent intensity/increase in turbulent energy dissipation following the damage to the flood control spillway (see discussion).

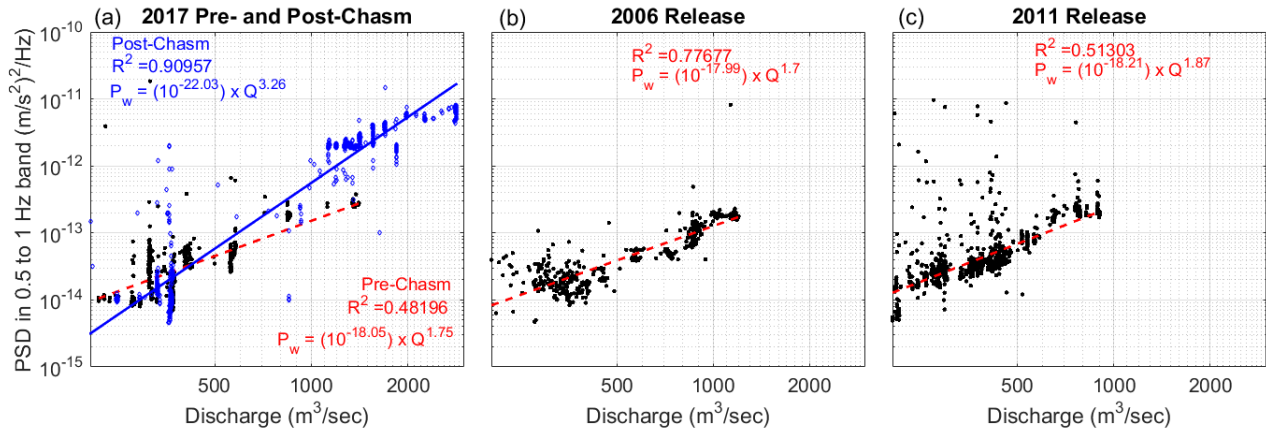


Figure 6: Analysis of the relationship between mean dominant eigenvector power and discharge for the current analysis and two previous flood control release events is shown in 6a-6c. The discharge of each interval is shown in Figure 5d. The scaling exponent of seismic power with discharge before the flood control spillway erosion, $Q^{1.75}$, is more similar to the scaling observed with two prior release events with $Q^{1.70}$ and $Q^{1.87}$ in 2006 and 2011, respectively, as compared to a power scaling of $Q^{3.26}$ following the development of the chasm from erosion.

<u>Time Interval</u>	<u>Logarithm of Coefficient (Base 10)</u>	<u>95% Confidence Intervals</u>		<u>Exponent</u>	<u>95% Confidence Intervals</u>	
		<u>Lower Bound</u>	<u>Upper Bound</u>		<u>Lower Bound</u>	<u>Upper Bound</u>
<u>2017 Pre-Crisis</u>	<u>-18.055</u>	<u>-18.438</u>	<u>-17.671</u>	<u>1.7452</u>	<u>1.6016</u>	<u>1.8888</u>
<u>2017 Post-Crisis</u>	<u>-22.033</u>	<u>-22.225</u>	<u>-21.841</u>	<u>3.2602</u>	<u>3.1965</u>	<u>3.3238</u>
<u>2006 Release</u>	<u>-17.994</u>	<u>-18.225</u>	<u>-17.763</u>	<u>1.6994</u>	<u>1.6157</u>	<u>1.783</u>
<u>2011 Release</u>	<u>-18.207</u>	<u>-18.448</u>	<u>-17.967</u>	<u>1.8698</u>	<u>1.7776</u>	<u>1.962</u>

Table 1: Coefficients, exponents, and uncertainty for power functions fit by least-square regression (shown in Fig. 6).

4.2 Polarization attributes

To examine the potential source of seismic waves across a range of frequencies, we display the azimuth and vertical-horizontal phase difference in fig. 7 for the five time intervals of interest. All five polarization attributes are provided in the supplemental materials. To evaluate the variability of polarization within each constant discharge interval, the probability density functions (PDFs) of all the hourly polarization results are plotted together in fig. 7. In the figure, the polarization attributes are binned into 100 evenly-spaced frequency bins from 0.1 to 15 Hz and the PDFs are normalized so that within in each frequency bin, the probability sums to one. The brighter colors indicate highly focused attributes and the darker colors indicate broadly distributed attributes. When ground motion is insufficiently polarized, polarization attributes are not interpretable (Samson, 1983). We select a cutoff β^2 at 0.5 as our threshold criterion for interpreting polarization attributes; Koper and Hawley (2010) selected a β^2 cutoff value of 0.6. Frequency ranges that are not interpretable by this criterion are shaded grey in figure 7.

The three time intervals after the spillway damage occurred (‘Emergency Discharge’, ‘High Discharge’, and ‘Post-Chasm Discharge’) display similar polarization attributes. The discharge through the emergency spillway weir, which reached a maximum of $360 \text{ m}^3 \text{ s}^{-1}$, is masked by the $\sim 1500 \text{ m}^3 \text{ s}^{-1}$ discharge in the primary spillway during this time (California Department of Water Resources, 2017d). When compared to the time intervals with discharge, the ‘Zero Discharge’ time interval contains less polarized three-component motion. Based on our threshold criterion, polarization attributes are not interpretable for a broad range of frequencies. At zero discharge, only polarization attributes at frequencies near 1 Hz, 4 Hz, and 10 Hz are interpretable, representing the ambient noise environment of the station. During the four intervals with non-zero discharge, a broad range of frequencies below 12 Hz are interpretable. There is a significant increase in polarization after the flood control spillway damage in a narrow frequency band around 0.7 Hz. From 1 to 5 Hz, the β^2 decreases from the “Pre-Chasm” discharge to the three “Post-Chasm” discharge intervals. The decrease in β^2 may be attributable to a mixing of seismic sources contributing to the ground motion (see discussion).

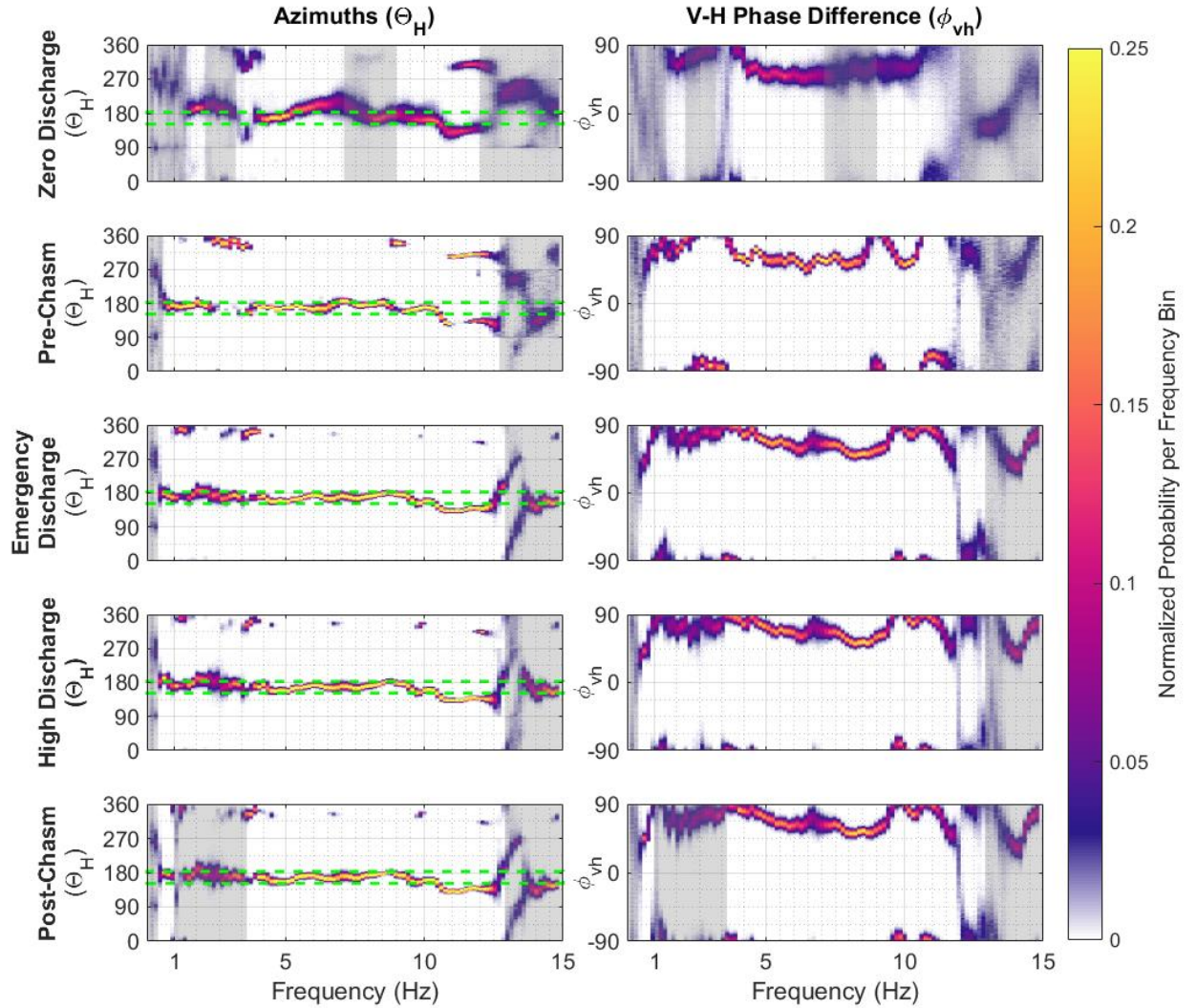


Figure 7: Two polarization attributes for the five time intervals of interest are presented in two dimensional histograms. Dashed green lines in the first column of figures indicates the azimuth range of the spillway relative to the seismometer (See Fig. 1). Each hour within the time interval of interest has a polarization value at 7201 frequencies. These are distributed among 100 bins evenly spaced in frequency, and are shaded by normalized probability. The polarization attributes for the three intervals of interest after the spillway damage are similar, and differ dramatically from the attributes in the pre-crisis interval. Polarization attributes are interpretable only when the degree of polarization is sufficiently great ($\beta^2 > 0.5$). Regions shaded grey indicate frequencies at which $\beta^2 < 0.5$ and the values are not interpretable.

4.3 Horizontal azimuth

To resolve the potential changes in seismic source location resulting from the flood control spillway damage, we evaluate the horizontal azimuth, which is computed for each frequency bin in fig. 7. The horizontal azimuth (Θ_H) of ~~the~~ the first eigenvector of the dominant particle motion ellipsoid represents the azimuth of the incoming wave if the motion is

Rayleigh-like or a P-wave. Park et al. (1987) and Koper and Hawley (2010) caution interpreting Θ_H as the azimuth if the horizontal-horizontal (ϕ_{hh}) phase difference is within 20° of $\pm 90^\circ$, because the ~~incidence-azimuth of a~~ is not defined for a horizontal circular motion ~~is not defined~~. At zero discharge, the horizontal azimuth is ~~highly-somewhat~~ variable; multiple sources of seismic energy with equal amplitudes may be present in the absence of spillway discharge (Fig. 7). During the time intervals with spillway discharge, horizontal azimuth is generally consistent from 5-8 Hz, then it stair-steps to lower azimuths at frequencies near 10 Hz.

In order to compute summary statistics of the horizontal azimuth, we select a frequency band of 5-10 Hz. This band has a degree of polarization above 0.5 for all time intervals with discharge and has a horizontal phase angle difference (ϕ_{hh}) outside of 20° from $90^\circ/-90^\circ$ (for which the azimuth is not defined). As directional data such as azimuth require special statistical treatment, we employ the CircStat Matlab toolbox for circular statistics to compute an hourly mean azimuth with 95% confidence intervals (Berens, 2009). Due to the 180° ambiguity in azimuth estimates, we consider valid any mean azimuths that lie between 90° and 270° , and add or subtract 180° from the mean azimuths that lie outside these bounds. This choice is supported by the strong relationship observed between power and changes in discharge which indicate that the flood control spillway channel (between 152° and 183°) is the primary seismic source across a broad range of frequencies (See Fig. 1c). We compute the uncertainty on the mean using 2000 random bootstrap samples with replacement. Table ~~1~~2 displays the mean 5-10 Hz azimuth within each time interval, with 95% confidence interval error bars. Figure 8a displays the average hourly 5-10 Hz Θ_H as a function of flood control spillway discharge, with hourly 95% confidence intervals for the 2017 period. For comparison, fig. 8b and 8c display the same data for the 2006 and 2011 release periods.

	5-10	Lower	Upper
Time Interval	Hz Mean	95% CI	95% CI
	Θ_H (deg.)	(deg.)	(deg.)
Zero Discharge	186.76	186.67	186.87
Pre-Chasm	174.28	174.16	174.38
Emergency Discharge	169.11	169.05	169.17
High Discharge	169.78	169.73	169.82
Post-Chasm	168.96	168.92	169.00

Table 12: Distribution statistics for the mean azimuth within the five time intervals of interest. The 95% confidence intervals (CI) on the mean are determined by collecting 2000 random bootstrap samples with replacement.

At low spillway discharges, the horizontal azimuth values are variable but generally point southward towards the Feather River and town of Oroville (183° to 250°), whereas during time intervals with elevated discharge the azimuth values point more consistently toward the flood control spillway channel, centered at 171° . During times when the spillway is undamaged, the hourly mean azimuth ~~is sensitive to~~ changes systematically with spillway discharge above about $500 \text{ m}^3 \text{ s}^{-1}$.

The hourly mean azimuth moves from the base of the flood control spillway towards the middle of the spillway with increasing discharge. After the erosion damage begins (Fig. 8a), the azimuths point more towards the top of the chasm, where a large waterfall develops as a result of the erosion damage. Above $1000 \text{ m}^3 \text{ s}^{-1}$, the azimuths point consistently to the middle of the outflow channel. The azimuths around a discharge of $1400 \text{ m}^3 \text{ s}^{-1}$ are different before the erosion crisis occurred (bright green shading) and after a chasm is present (dark blue shading). This distinction indicates that the FDPA-derived azimuths are sensitive to changes in the turbulence regime under normal spillway operation and when erosion damage is present (see discussion in section 5).

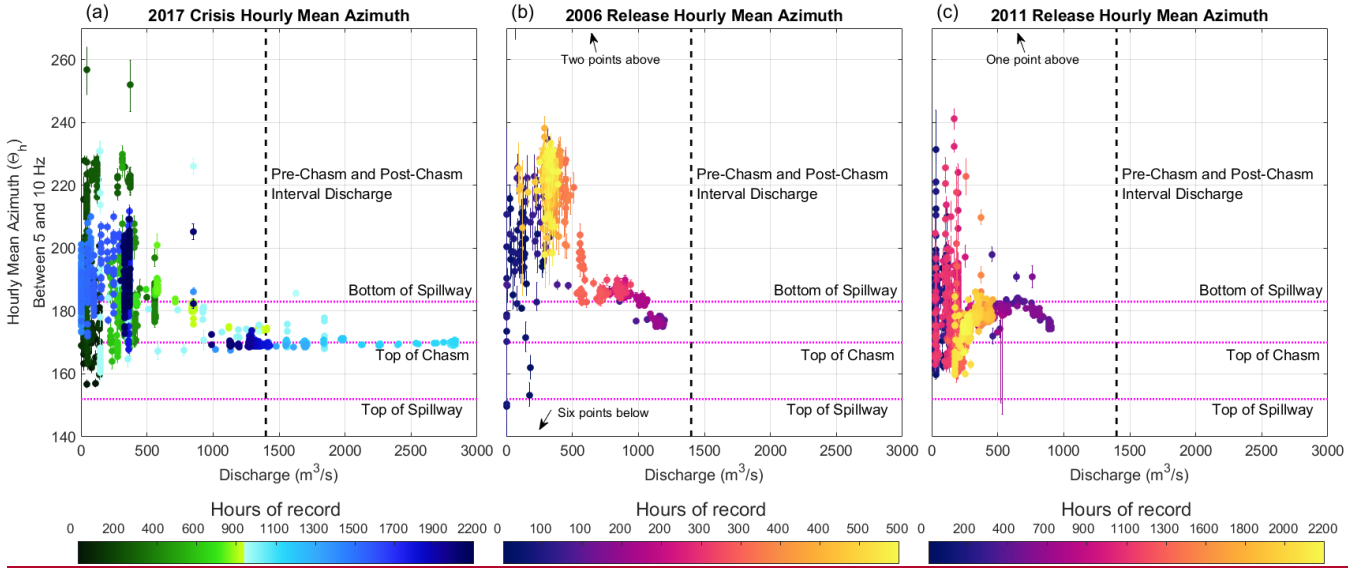


Figure 8: In the 5-10 Hz band, hourly mean azimuth (Θ_H) is displayed in Fig. 8a-c, with 95% error bars. The mean azimuth is highly variable for discharge less than $500 \text{ m}^3 \text{ s}^{-1}$ for the flood control releases in 2017 (Fig. 8a), 2006 (Fig. 8b) and 2011 (Fig. 8c). In Figure 8a, during the “Pre-Chasm” time interval shaded green, the mean horizontal azimuth values point to the bottom of the flood control spillway (183° , see Figure 1c). After the high releases have formed a chasm that starts in the middle of the flood control spillway, the azimuths consistently point to the channel midpoint. The “Post-Chasm” azimuth when discharge is approximately $1400 \text{ m}^3 \text{ s}^{-1}$ is noticeably distinct from the “Pre-Chasm” flows around $1400 \text{ m}^3 \text{ s}^{-1}$. During times when the channel is undamaged (Fig. 8b and Fig. 8c), the mean azimuth is sensitive to changes in discharge as turbulence develops in the middle of the flood control spillway. Due to the 180° indeterminacy, Θ_H shown in this figure is constrained between 90° and 270° , the direction of the outflow channel.

4.4 Incident angle

The vertical angle of the first dominant eigenvector ~~of the particle motion ellipsoid~~ represents the incidence angle of the incoming wave for body waves or tilt of elliptical motion for Rayleigh waves. Park et al. (1987) and Koper and Hawley (2010) caution interpreting this metric if ϕ_{vh} is within 20° of $\pm 90^\circ$, because the vertical incidence angle of vertical circular motion is not defined. At a broad range of frequencies this criterion is not met during time intervals with discharge (see section 4.5). In all five time intervals of interest, the Θ_V values are highly variable (see supplemental material).

4.5 Vertical-horizontal phase difference

To evaluate the possible surface wave type (i.e. Rayleigh or Love), we ~~rely on~~assess the vertical-horizontal phase difference. For a Rayleigh wave in an isotropic medium, the vertical-horizontal phase difference will be $\pm 90^\circ$. In certain anisotropic structures, the vertical-horizontal phase difference for a Rayleigh wave will deviate from $\pm 90^\circ$ (Crampin, 1975).

5 In fig. 7, the vertical-horizontal phase angle (ϕ_{vh}) is consistently near $\pm 90^\circ$ for frequencies below 5 Hz when discharge is occurring, which is consistent with a Rayleigh-like wave. At frequencies of up to 8 Hz, which account for most of the power, there is a ~~declining-decreasing~~ vertical-horizontal phase angle to approximately 50° . At 8 Hz, the vertical-horizontal phase angle is 50° in the “Pre-Chasm” time interval and near 90° in the “Post-Chasm” time interval. These deviations from $\pm 90^\circ$ are unexpected and explored in Sect. 4.7.

10 4.6 Horizontal phase difference

For all of the time intervals of interest, the ϕ_{hh} is between $\pm 180^\circ$ and $\pm 90^\circ$ for most frequencies, suggesting horizontal elliptical particle motion. At 8 Hz, the “Pre-Chasm” and “Post-Chasm” time intervals seem to change from near -180° to near -115° phase difference, suggesting a change from linear horizontal motion to more elliptical horizontal motion at frequencies near 8 Hz.

15 4.7 Topographic effects on vertical-horizontal phase angle

We observe consistent deviations from the expected vertical-horizontal phase difference of $\pm 90^\circ$ between 5 and 10 Hz, even during the “Pre-Chasm” interval (Fig. 7). To investigate the possible reasons behind ~~these~~ deviations, ~~from the expected vertical horizontal phase difference of $\pm 90^\circ$,~~ we consider the effect of the irregular hillside topography on the polarization results. ~~To evaluate the influence of local topography on the polarization results, we by~~ computing 2D synthetic
20 seismograms using the 2D spectral-element solver package SPECFEM2D 7.0.0 (Tromp et al., 2008; Komatitsch et al., 2012). All geospatial data were processed in ESRI ArcMap 10.4. First, a 2013 $\frac{1}{3}$ arc-second resolution digital elevation model was acquired from the USGS National Elevation Dataset at www.nationalmap.gov. The raster was reprojected to Universal Transverse Mercator Zone 10N to acquire northing and easting coordinates in a conformal (angle-preserving) coordinate system. Elevation data (in m, NAVD 88) were extracted from each grid cell along a profile line between top of the spillway
25 erosion damage and the seismometer in this study. The topographic profile was meshed into the model domain using the built-in xmeshfem2d program. To minimize model boundary effects, the lower model boundary extends over ~~1000-m~~ 4 km below the surface. We also generated a rectangular model grid with a flat surface in SPECFEM2D for comparison. We select a density of 2700 kg m^{-3} , increase P wave velocity linearly with depth of from 3000 m s^{-1} at the surface to 6 km s^{-1} at 4 km depth, and assume a Poisson solid.

30 In both the topographic and flat surface simulations, ~~a continuous signals was were~~ used as the seismic source, and ~~was were~~ applied independently at ~~the five~~ locations spaced 100 meters apart and representing a spatially distributed source

along the projection of the of the midpoint of the Oroville flood control spillway channel projected onto a 2D profile line (See Supplemental Materials Fig. S3). A-Each independent source consists of a sixfour-minute random signal varying between 0 and 1 was filtered using a second order Butterworth filter between 0.5-5 and 5-10 Hz, re-presenting the frequencies across which Deviations from Rayleigh-like wave frequencies polarizations are observed at these frequencies the greatest increases at the BK ORV seismometer with discharge were found (fig. 47). The angle of incidence of the continuous seismic source was varied between 0°, 45°, and 90° with respect to the vertical. Synthetic 2D-seismograms were simulated at the location of the BK ORV seismometer, with random noise added to the resulting synthetic seismograms to approximate background seismic sources. As theis simulations is-are carried out in a 2D geometry, the results may only be used to evaluate the effect of topography on vertical-horizontal phase differences. The results of theis simulations show that for-a vertically incident fluctuating forces applied at-along the Oroville flood control spillway midpoint, the particle motion is Rayleigh-like (vertical-horizontal phase difference is near $\pm 90^\circ$) for a flat topography surface (Fig. 9a). As the fluctuating force is applied at angles of 45° and 90° to the surface, the vertical-horizontal phase becomes less Rayleigh-like below 5 Hz. Realistic topography also appears to significantly affect the particle motion, which becomes less Rayleigh-like, as vertical-horizontal phase differences decrease from $\pm 90^\circ$ to $\pm 45^\circ$ across a range of frequencies between 5 and 10 Hz (Fig. 9c). This is consistent with the conversion of Rayleigh energy to body-waves as the seismic waves propagate up-slope up a non-uniform slope (e.g. McLaughlin and Jih, 1986).

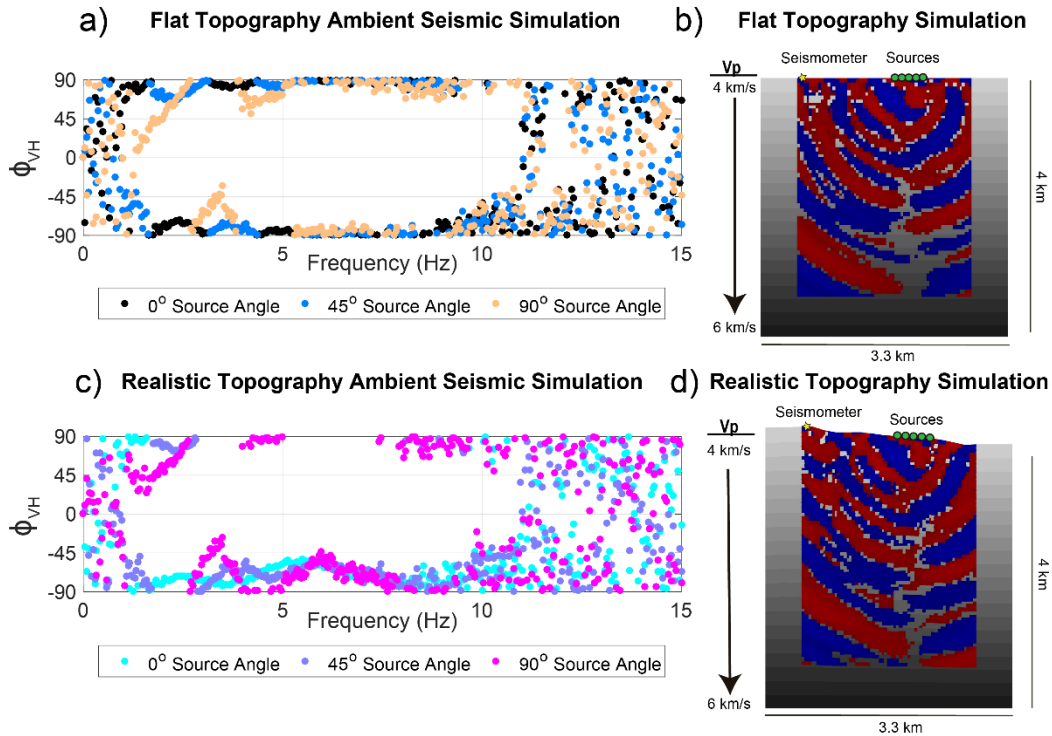


Figure 9: Polarization attributes computed using FDPA of synthetic seismograms computed using SPEC2D are shown in 9a and 9c; with corresponding simulated topographies. The distributed source of the spillway is approximated by five sources spaced 100 meters apart with a source frequency of 5-10 Hz. Random noise was added to the results of the simulation to approximate background seismic noise. Fig 9a and 9b display the horizontal component seismic wavefield during a single time step in each simulation. In the flat surface-topography simulation (Fig. 9a), the vertical-horizontal phase difference is closer to $\pm 90^\circ$ than in the simulation that includes the realistic hillslope topography (Fig. 9c). With a vertically incident force (0° source angle), the phase difference is lowest, while with increasing incidence angles, the vertical motion becomes less like a classical Rayleigh wave below 5 Hz.

5 Discussion

The changing geometry of the flood control spillway and the increase in flow turbulence during the Oroville Dam Erosion Crisis are reflected in the FDPA results, most notably in dominant~~first~~ eigenvector power and horizontal azimuth. During the crisis, large volumes of material ($1.3 \times 10^6 \text{ m}^3$ according to our analysis of LiDAR data) were transported, which previous work has shown can contribute to the overall seismic signal (Tsai, et al., 2012). Therefore, one might expect bedload transport to be the dominant source of seismic energy. Yet, there are compelling lines of evidence that suggest that the majority of the signal is flow-generated. First, the fastest rate of material transport on the Oroville flood control spillway was likely during the early part of the crisis timeline. Water entering the flood control spillway is from the surface of the reservoir. Unlike a natural river, it does not carry bedload or coarse suspended sediment, so any transported material must be entrained from the spillway itself or the adjacent hillside. Early in the Oroville dam crisis, weathered saprolite and concrete blocks were undercut and eroded, while later in the crisis, the water from the spillway flowed over harder volcanic rocks. If the seismic signal was generated by a transient transport pulse, we would expect a rapid jump and decay in the amplitude of the seismic waves coming from the spillway. If greater erosion occurred at the beginning of the crisis and if transported material were the primary source of the seismic energy, we would expect clockwise power-discharge hysteresis in this system. Instead, we observe counterclockwise hysteresis in this relationship. Although our analysis does not enable us rule out all other seismic sources such as material transport, we think that the changes in FDPA results are consistent with changes in the turbulent flow regime caused by erosional changes in channel geometry.

Counterclockwise hysteresis in the discharge-power relationship is consistent with the increased channel roughness and larger scaling of macroturbulent eddies as induced by~~resulting from~~ the Oroville Dam erosion crisis. Because of the dissimilarity of the system to a natural channel, we are unable fully to implement theoretical models of fluvial seismic energy generation, but we are able to examine whether the scaling relationships within these models are consistent with our data. The theoretical scaling relationship between water-generated vertical component power (P_W) and discharge (Q) for water turbulence alone with a simple channel geometry is $P_W \propto Q^{1.25}$ (Gimbert et al., 2014; Gimbert et al., 2016). Roth et al. 2017, found a $P_W \propto Q^{1.49-1.93}$ in the 35 - 55 Hz band. In the 0.5 to 1 Hz band for the smooth channel (2006, 2011, and pre-crisis 2017) the observed scaling of ~~first-dominant~~ eigenvector power and turbulence is $P_W \propto Q^{1.69-1.88}$, similar to the scaling observed by Roth et al. 2017. After the spillway erosion crisis, the scaling exponent is much higher ($P_W \propto Q^{3.28}$). We observe

similar scaling relationships for the vertical component power (without polarization analysis), with 2006, 2011, and pre-crisis 2017 scaling as $P_W \propto Q^{1.74-1.98}$ and post-crisis 2017 scaling as $P_W \propto Q^{3.26}$.

The increased scaling exponent following the crisis likely corresponds to the ~~substantially greater turbulence generated from~~ addition of new sources of turbulent energy dissipation generated ~~the from the~~ rougher channel morphology ~~comprised associated with of exposed bedrock~~ and waterfall. For a uniform turbulent flow, as expected in the hydraulically smooth, constant-width channel geometry present during the 2005-2006 flood, discharge is log-linearly related to flow depth according to the Law of the Wall and ground motion is generated by fluctuating forces applied by scaled eddies within the flow, analogous to the processes described by Gimbert et al. (2014). After damage is created in the channel, several mechanisms likely increase the energy dissipated by the flow for at a given discharge. The first is that the erosion damage introduced a steep vertical drop in the base of the channel, developing a waterfall. A waterfall will violate assumptions in the Gimbert et al. (2014) model formulation and lead to greater water velocities (from free fall) impacting the bed than would be found in a continuous turbulent channel flow. Second, the irregular channel shape resulting from erosion provides obstructions to the flowing water that create local pressure gradients around the obstacles. These pressure gradients cause a deflection in the flow and an increase in the shearing between flows of different velocities, increasing the energy dissipated by the turbulence in the flow. For a hydraulically rough channel geometry with variable width, the flow depth is a function of discharge, channel shape, and flow resistance (Leopold et al., 1960). Therefore, determining the causes of the scaling exponent change is difficult. Third, erosion during the 2017 event incised a 47-meter-deep, V-shaped channel, which increased flow depths from at for the same discharge and changed the distribution of shear stresses applied to the bed. Greater flow depths would also allow for larger eddies to form. Our results suggest that the additional energy dissipated by these forms of turbulence is observed as an increase in the scaling relationship between discharge and seismic power. Our observations support the use of the exponent in the $P_W \propto Q$ power function to observe changing channel geometries in supply-limited fluvial systems (as in Gimbert et al., 2016), but are unable to ~~ascribe a more detailed~~ identify a particular source mechanism.

The FDPA polarization attributes reveal the seismic character of open channel turbulent flow, which is distinct from the background seismic character ('Zero Discharge' interval) across a broad range of frequencies (fig. 7; supplemental material). The three time intervals with discharge following the flood control spillway damage have similar polarization attributes, while the "Pre-Chasm" time interval is identifiable by a higher degree of polarization at frequencies below 3 Hz, and the absence of a 0.7 Hz sharp peak in first-dominant eigenvector power (fig. 4) and degree of polarization. The decrease in degree of polarization is consistent with mixed seismic waveforms from multiple sources (Rayleigh, Love, P, and S) being introduced by the chasm channel complexity and increased turbulent ~~intensity~~ energy dissipation. We are unable to attribute a source to the 0.7 Hz anomaly, but we note that around 0.7 Hz we observe azimuths of about 180°, an incidence angle of about 25° from vertical, a vertical-horizontal phase difference about 45°, and broadly distributed horizontal-horizontal phase difference. The azimuth is consistent with the base of the flood control spillway, though the vertical incidence is steeper than the 13° slope of the hillside.

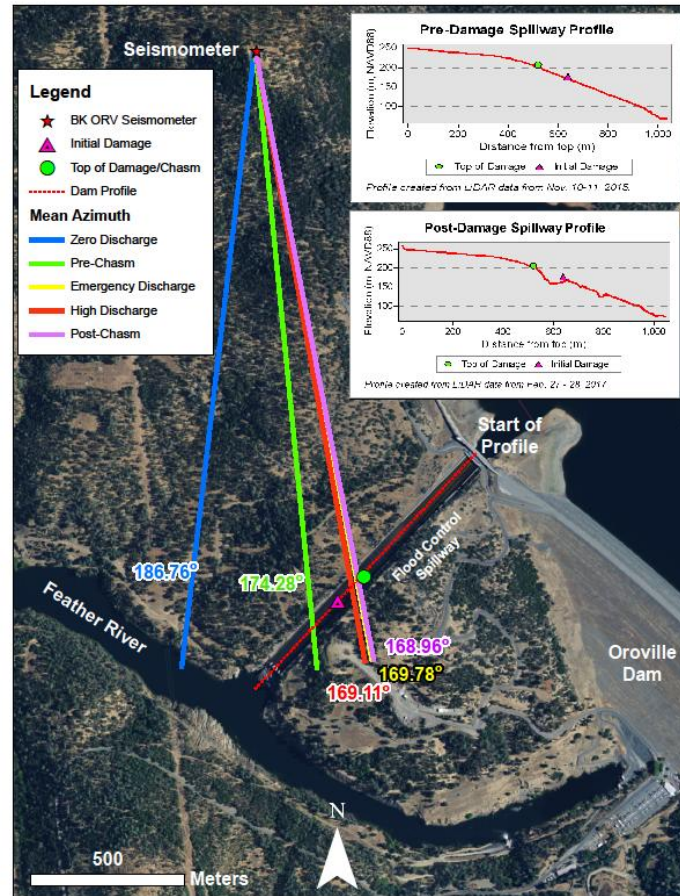
The greatest hysteresis in the power and discharge relationship is observed at low frequencies (0.5 to 1 Hz), however, the greatest hysteresis in azimuth is observed at higher frequencies (5-10 Hz). This ~~change-difference~~ may be due to the greater sensitivity to source location that is provided by the higher frequencies, which have shorter wavelengths. For a Rayleigh wave traveling through rock at approximately 3 km s^{-1} , the wavelength of a 0.5-1 Hz wave is 6 km to 3 km, significantly longer than the 1 km long flood control spillway, meaning that changes in source location along the spillway may not be observable in azimuths computed at low frequencies. However, at 5 to 10 Hz, the wavelength is 0.6 to 0.3 km, which is sufficient to identify distinct segments of the flood control spillway.

The hourly 5-10 Hz mean azimuths (fig. 8) are sensitive to changes in discharge even when no damage is present (fig 8b and 8c). Aerial photographs of the spillway at a range of discharges reveal that the location of the transition from smooth to visibly white and aerated turbulent flow in the bottom half the spillway is sensitive to changes in discharge (See fig. S5 in the supplement). In the dam engineering literature, the onset of surface turbulence is referred to as the inception point and represents where the turbulent boundary layer reaches the free surface (Hunt and Kadavy, 2010). The aerated flow region downstream of the inception point indicates ~~an increase~~ increased ~~in turbulence and~~ energy dissipation. Due to the geometry of the spillway channel with respect to the seismometer, as the inception point moves up the spillway channel it approaches the seismometer. We expect the closest portion of the aerated flow region to be the largest source of seismic energy under undamaged conditions; seismic energy excited further from the seismometer will be subject to more geometrical spreading and attenuation.

The hourly 5-10 Hz mean azimuths are also sensitive to changes throughout the dam erosion crisis. During the 2017 period, the ‘Pre-Chasm’ and ‘Post-Chasm’ time intervals have a statistically significant difference in mean azimuth of 5.32° . The ‘Emergency Discharge’, ‘High Discharge’, and ‘Post-Chasm’ time intervals have mean azimuths within a 1° range. To interpret these results, we reviewed available aerial photography throughout the Oroville Crisis and extracted an elevation profile along the length of the flood control spillway using the LiDAR measurements provided by the CADWR. The imagery review reveals that the top of the erosion damage propagated upstream a distance of approximately 120 meters (approx. 2.8° azimuth) between February 7th and February 27th-28th (fig. 10). The upstream end of the erosion damage forms a waterfall. FDPA results from the ‘Emergency Discharge’, ‘High Discharge’, and ‘Post-Chasm’ time intervals are able to identify the waterfall at the top of the erosion damage. The ‘Emergency Discharge’ time interval has an azimuth within 1° of the immediately following ‘High Discharge’ interval, indicating that $360 \text{ m}^3 \text{ s}^{-1}$ released through the emergency spillway did not generate sufficient energy to mask the concurrent flood control spillway releases at that time.

The particle motion of seismic waves produced by the Oroville dam spillway is mostly Rayleigh-like, particularly at frequencies below 3 Hz, though we also observe consistent deviation from the expected Rayleigh ϕ_{vh} values (-90° and 90°) at frequencies from 5-10 Hz. This could be explained by the presence of anisotropy (Crampin, 1975) or Love and/or body waves, which induce shifts in ϕ_{vh} but our SPECFEM2D modeling indicates that realistic topography likely influences is also a viable explanation for the polarization attributes we observe, noticeably ϕ_{vh} . Therefore, our analysis is limited to time-varying changes in polarization attributes rather than interpreting the surface and/or body waveforms created by the flood

control spillway. We see the greatest difference in ϕ_{vh} and ϕ_{hh} between the “Pre-Chasm” and “Post-Chasm” time intervals below 3 Hz and in the 9-11 Hz band, potentially indicating that more Rayleigh energy is produced at these frequencies after the channel geometry becomes more ~~complex~~eroded and incised.



5 **Figure 10: Mean azimuths for the five time intervals of interest mapped onto aerial imagery reveal the Emergency Discharge, High Discharge, and Post-Chasm mean azimuths point to the top of the spillway damage, where a steep drop creates a waterfall. The location of the initial damage, shown as a triangle, is estimated from photographs of the damage (see supplement). The location of the damage top, shown as a circle, is estimated from aerial photography and high-resolution LiDAR points collected after most of the damage occurred.**

10 6 Conclusion

Our analysis of the seismic data collected during the Oroville Dam erosion crisis identified several techniques that are potentially useful for dam spillway monitoring and can be applied to fluvial studies. We evaluated the single-station FDPA method to locate the region of greatest flow turbulence. To our knowledge, this is the first application of FDPA methods to analysis of a hydrodynamic signal. We were able to resolve changes in the mean ~~5-10 Hz~~ azimuth of the turbulence-generated

~~5-10 Hz seismic waves~~~~source~~ under normal spillway conditions (2006 and 2011 release periods) when varying discharge and velocity generate changes in the location of the aeration zone inception point. During high spillway discharges and the onset of spillway damage (2017 crisis), the data analysis techniques were used to pinpoint the upstream location of spillway erosion as identified by the increased turbulence. This technique is promising for fluvial studies to identify potential seismic energy interference from nearby waterfalls (i.e. Roth et al. 2016) or in otherwise noisy study environments. The vertical-horizontal phase difference of the spillway-generated energy is consistent with a Rayleigh wave propagating up the dam ~~embankment~~ non-uniform hillslope.

~~This study indicated~~We find that for constant discharge conditions and varying amounts of spillway damage and associated macroturbulence, counter-clockwise hysteresis in the discharge-seismic power relationship indicates that ~~an~~ increase in turbulence generates the turbulent structures created by the spillway damage excite more seismic energy more effectively. This observation is consistent with the increased energy dissipation by macroturbulent eddies and stepped flows considered in spillway design (Hunt and Kadavy, 2010a). This observation is also consistent with the fluvial geomorphology literature that indicates-argues a significant proportion of total energy dissipation is caused by macroturbulent eddies in natural rivers (Leopold et al., 1960; Bathurst, 1980; Prestegard, 1983; Powell, 2014). Therefore, seismic monitoring may be a tool to quantify macroturbulent eddies and associated flow resistance in complex natural channels. The results of this study are consistent with those of Roth et al. (2017), who suggested changes in channel morphology as a ~~source-for~~cause of water turbulence-associated hysteresis in natural channels. This study also implies that the Gimbert et al. (2014) model will under-predict seismic energy released in rivers with ~~complex irregularly-shaped~~ channels, waterfalls, and macroturbulent eddies. In this study, we observed that the generation of ~~irregulare~~complex channel morphology by damage to the spillway produced greater scaling exponents in the seismic power ~~-~~discharge relationship than the pre-damaged spillway, which produced scaling exponents similar to those predicted by the Gimbert et al. (2014) model.

Although results of this work can be applied to spillway monitoring and natural channel observations, we highlight several limitations of the methods used in this study. The long intervals of constant or known discharge in spillway operations are dissimilar from the sharp increases and decreases in discharge observed in most rivers hydrographs. In this study, we assumed that during intervals of constant discharge flow turbulence generated seismic motions with the same polarization attributes. Therefore, uncertainty was estimated by documenting the variability of polarization attributes during these time intervals of constant discharge. Due to the hazardous conditions surrounding the spillway channel, inferences on the mechanisms and degree of turbulence are limited to interpretations of aerial photography. This study was limited to the hourly resolution of reported discharge and the sampling frequency and sensitivity of the broadband seismometer in the study. For natural rivers, further research is needed to understand the appropriate time window length and sampling frequency to characterize turbulence at various scales.

Code availability

The authors provide a MATLAB implementation of the polarization analysis described in the paper, with an example dataset included in the supplemental material.

Data availability

- 5 The flood control spillway discharge data is available on the California Data Exchange Center (<https://cdec.water.ca.gov/>). The seismic data used in this study is available through the Northern California Earthquake Data Center (ncedc.org). The LiDAR elevation points and associated metadata provided by the California Department of Water Resources are provided in the supplemental materials.

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- 15 Seismological Laboratory, which is archived at the Northern California Earthquake Data Center (NCEDC), doi: 10.7932/NCEDC. The continuous color scales used in this paper are perceptually uniform and developed by Peter Kovesi and licensed under a Creative Commons license (Kovesi, 2015). We thank our reviewers for their careful reading of our manuscript and their insightful comments, which strengthened this paper.

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Lidar Acquisition and Processing

LiDAR data were provided by the California Department of Water Resources (CADWR) following an information request on June 30th, 2017. The raw data is provided below with CADWR permission granted 10/19/2017.

November 10th and 11th LiDAR Acquisition: The LiDAR survey was accomplished using an Optech Orion M300 LiDAR system operating from a fixed wing aircraft (Cessna 310 Tail # N7516Q). The mission was completed over two days (November 10 and 11, 2015). A Trimble R8-3 GPS receiver was set up and operating at the Oroville Municipal Airport for the duration of the mission, recording data at 2 Hz.

The March 23rd merged LiDAR dataset provided by the California Department of Water Resources consists of the following datasets. From the metadata associated with the files and information provided by the CADWR, the main spillway damage area surveyed on February 27th and 28th.

- Towill, Inc. 2/24/2017 LiDAR (Additional metadata in file included in .zip file folder)



Oroville_Spillway_02
-24-2017_Project_Me

- CADWR 2/27/2017 Drone Point Cloud (Gated Spillway with no water)
- Towill Inc. 2/28/2017 LiDAR (Additional metadata in file included in .zip file folder)



Oroville_Spillway_02
-28-2017_Project_Me

- CADWR 3/13/2017 Drone Point Cloud (DF1223 upper spillway)
- CADWR 3/19/2017 Drone Point Cloud (DF1300 spoils near Hyatt Powerplant)
- CADWR 3/19/2017 Drone Point Cloud (DF1151 spoils on hillside near auxiliary spillway)

The surveys were conducted with horizontal control in California Coordinate System (CCS) State Plan Zone II (US Feet) and vertical control in North American Vertical Datum (NAVD) 1988 (US Feet).

The raw data is available file included in .zip file folder:



20170323_Oroville_LiDAR.TXT



20151111_Oroville_LiDAR.txt

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In this data, the first column is the easting, the second column is the northing, and the third column is vertical elevation (all in US feet). To create a difference map, a triangle irregular network (TIN) was created from each point dataset. Using nearest neighbor interpolation, a 1-meter resolution digital elevation model (DEM) was created. A difference raster dataset was created by subtracting the 2015 DEM from the 2017 DEM, and converting the result to meters. The volume change in the main spillway damage zone is the sum of each cell's volume (cell area x vertical change). All processing was completed in ArcMap 10.4 (ESRI).

Polarization Attributes

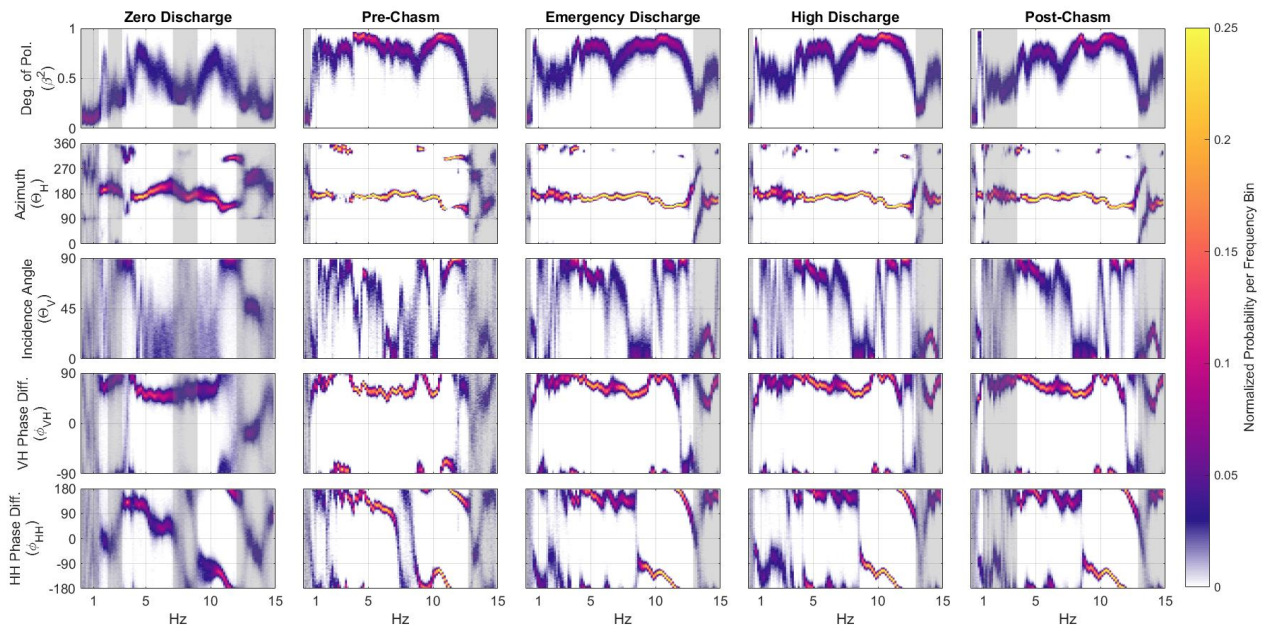


Figure S1- The four polarization attributes and degree of polarization (β^2) for the five time periods of interest. Grey shading indicates frequencies at which the polarization attributes are not interpretable ($\beta^2 < 0.5$). The Azimuth (θ_H) and vertical-horizontal phase difference (ϕ_{vh}) are shown in Figure 7 of the main text.

Scaling of Dominant Eigenvector Power and Discharge

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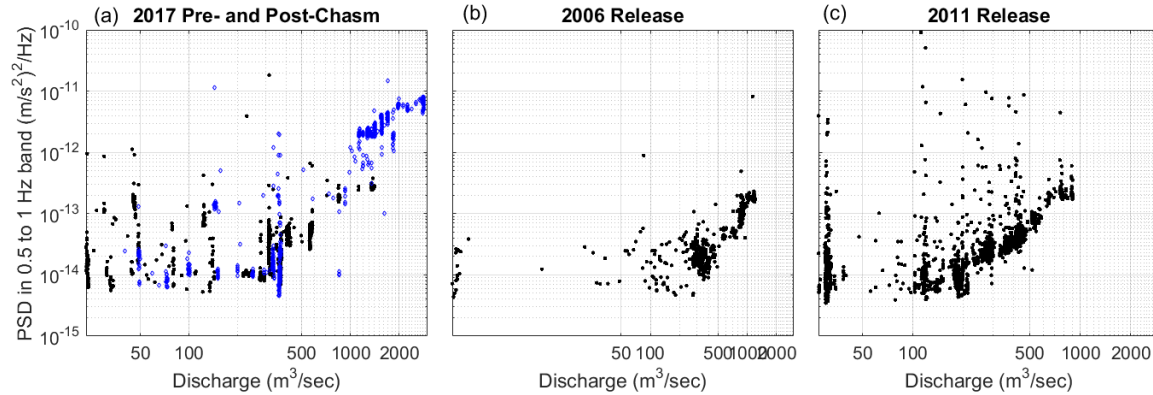


Figure S2- The hourly relationship between dominant eigenvector power and discharge has an apparent break in slope at approximately 200 cubic meters per second of discharge. We interpret this to be the threshold for which the seismometer is sensitive to flood control spillway discharge, and complete the scaling analysis in the main text only for hours with discharge greater than 200 cubic meters per second.

SPECFEM2D Simulation

Topographic model domain for the SPECFEM2D simulation was created by extracting the elevation profile along a transect extending through the BK ORV seismometer and the center of the Oroville Dam Spillway. To create the model domain, 1000 meters were added to the lowest elevation, so that the model boundary did not interfere with the topography.

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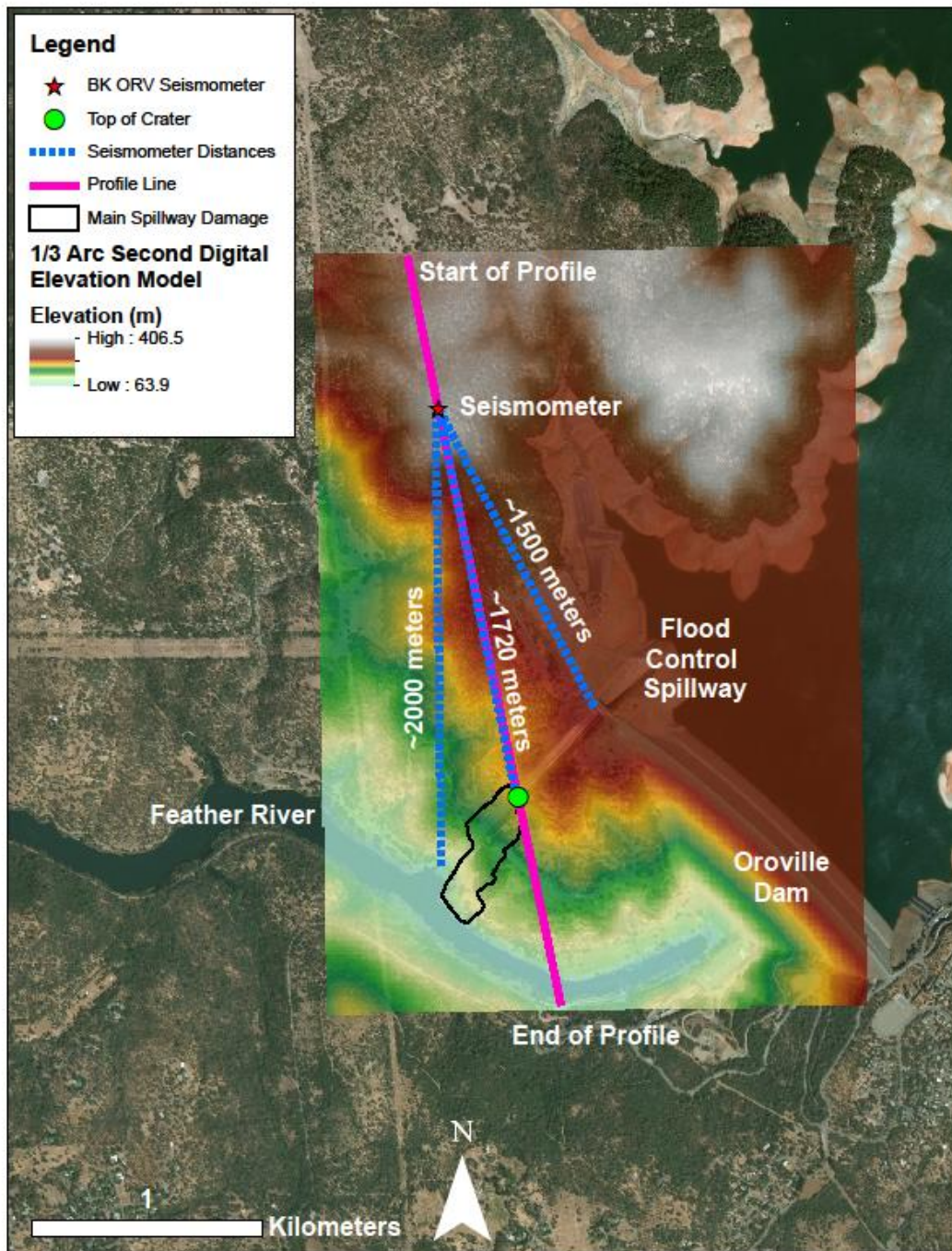


Figure S3- The hillside topography extracted for the SPEC2D simulation. If the entire length of the flood control spillway is considered an ambient seismic source, then the seismic waves travel a range of approximately 500 meters to the seismometer. In our simulation, we simplify this by simulating five sources spaced 100 meter apart along a profile line to the middle of the flood control spillway.

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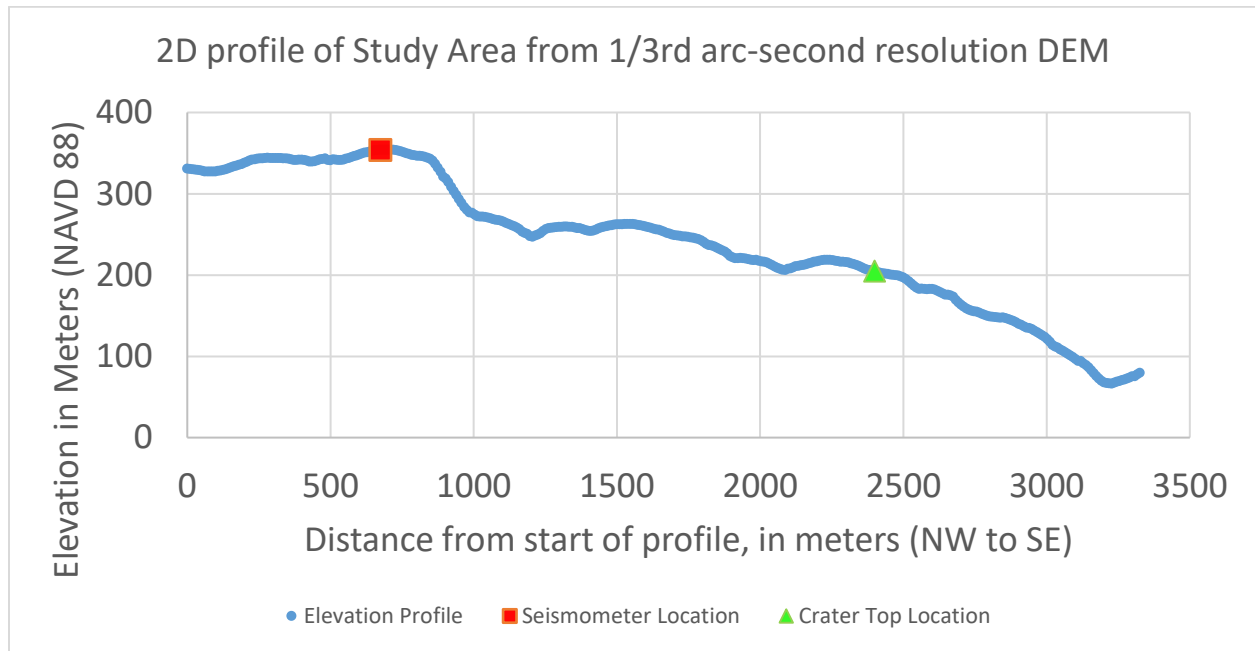


Figure S4- The elevation profile extracted for the SPECFEM2D simulation.

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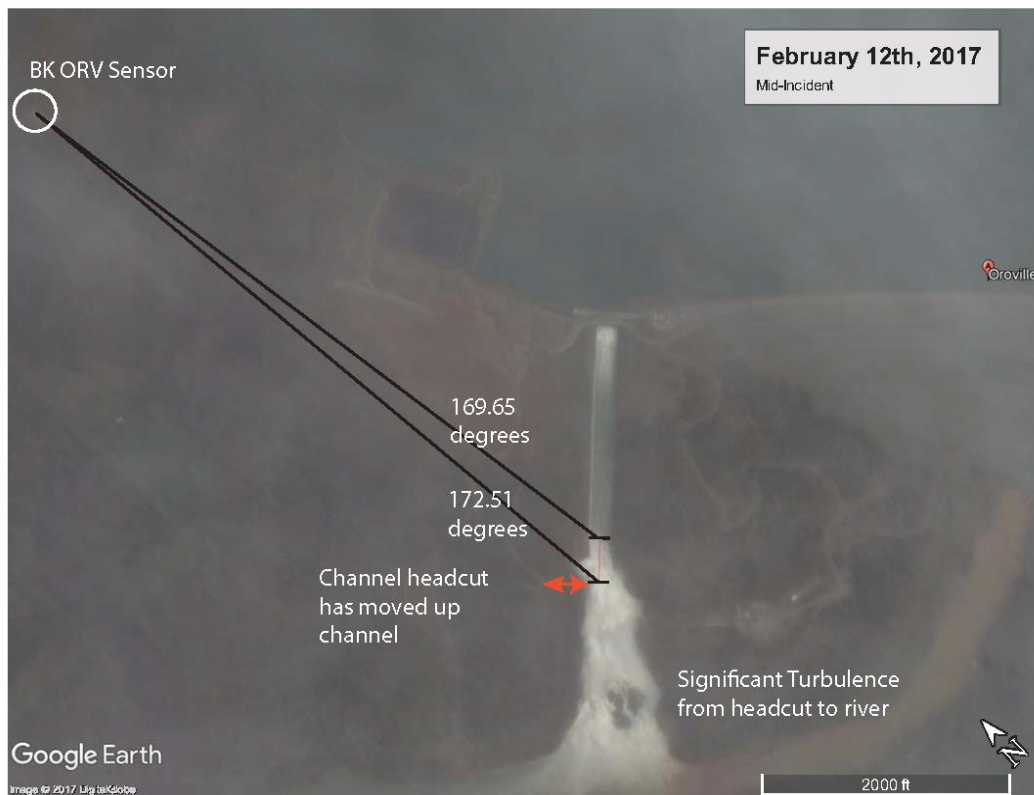
a)



b)



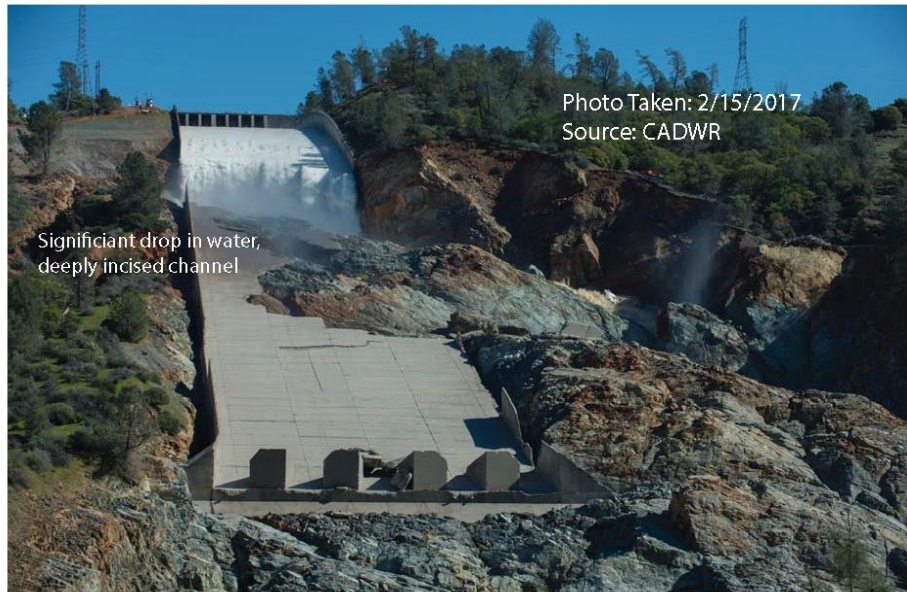
c)



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g)



h)



Seismic signature of turbulence during the 2017 Oroville Dam spillway erosion crisis (Supplemental Materials)

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Figure S5 (a-f)- Aerial photographs collected during the time period of interest showing the evolution of the spillway erosion damage.

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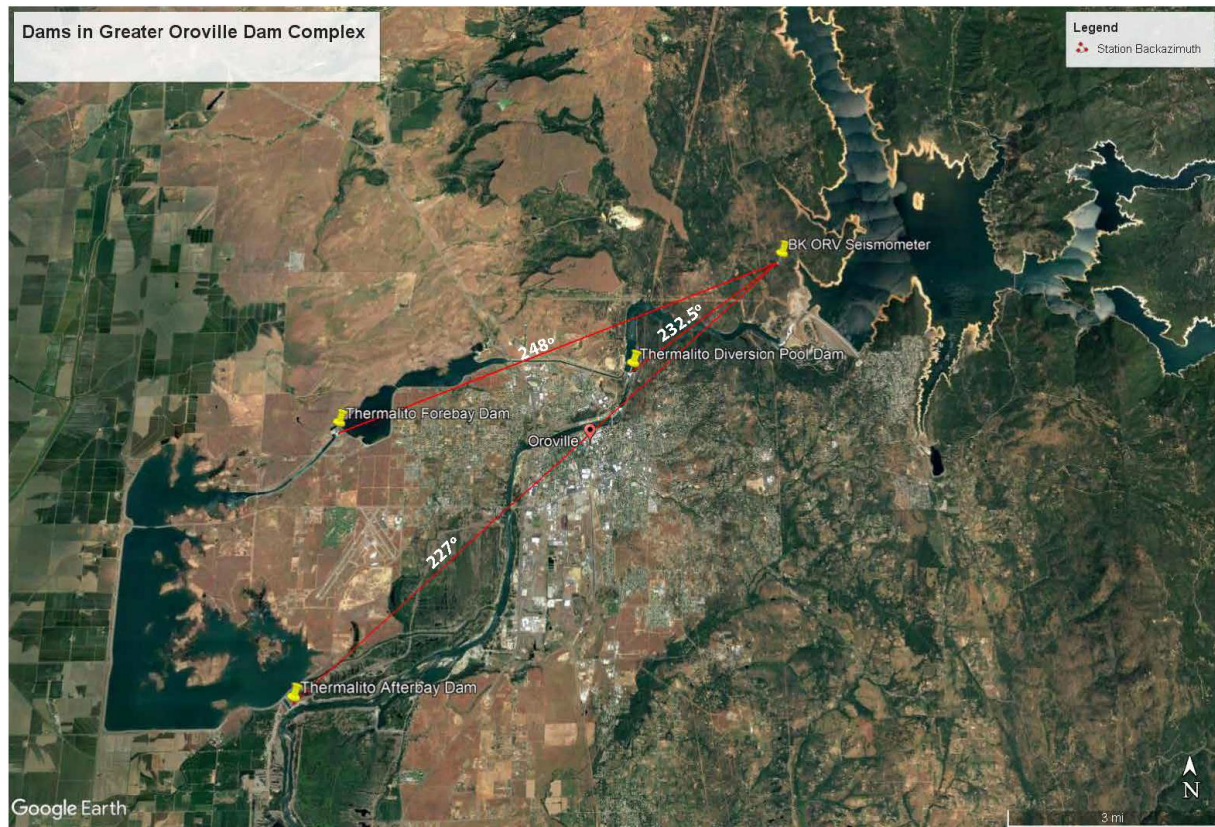


Figure S6- Three other dams- Thermalito Forebay Dam, Thermalito Diversion Pool Dam, and Thermalito Afterbay Dam- are a part of the Oroville Dam Complex and are at backazimuths of 248°, 232.5°, and 227°, respectively. The town of Oroville, California is located between station backazimuths of approximately 248° and 217°.