



Graphically interpreting how incision thresholds influence topographic and scaling properties of modeled landscapes

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Abstract. We examine the influence of incision thresholds on topographic and scaling properties of landscapes that follow a landscape evolution model (LEM) with terms for stream-power incision, linear diffusion, and uniform uplift. Our analysis uses three main tools. First, we examine the graphical behavior of theoretical relationships between curvature and the steepness index (which depends on drainage area and slope). These relationships plot as straight lines for the case of steady-state landscapes that follow the LEM. These lines have slopes and intercepts that provide estimates of landscape characteristic scales. Such lines can be viewed as counterparts of slope–area relationships, which follow power laws in detachment-limited landscapes, but not in landscapes with diffusion. We illustrate the response of these curvature–steepness-index lines to changes in the values of parameters. Second, we define a Péclet number that quantifies the competition between incision and diffusion, while taking the incision threshold into account. We examine how this Péclet number captures the influence of the incision threshold on the degree of landscape dissection. Third, we characterize the influence of the incision threshold using a ratio between it and the steepness index. This ratio is a dimensionless number in the case of the LEM that we use, and reflects the fraction by which the incision rate is reduced due to the incision threshold; in this way, it quantifies the relative influence of the incision threshold across a landscape. These three tools can be used together to graphically illustrate how topography and process competition respond to incision thresholds.

1 Introduction

Processes that shape landscapes leave topographic signatures, which can often be visualized by plotting different topographic metrics against one another. An example is the relationship between river gradient and drainage area, which has been used to analyze landscapes and river profiles, and to diagnose the processes that shape them (e.g., Montgomery and Foufoula-Georgiou, 1993; Howard, 1994; Montgomery and Dietrich, 1994; Dietrich et al., 2003). For example, the stream-power incision model predicts that if tectonics, climate, and rock properties are uniform, bedrock rivers should approach a steady state in which their gradient scales as a power law of drainage area (e.g., Tucker, 2004; Lague, 2014). This power-law scaling implies that river gradient data should plot as a straight line against drainage area data on logarithmic axes. The properties of this line can give estimates of properties of the landscape, e.g., its slope gives the concavity index (Whipple, 2004). Plotting synthetic topographic data from landscape evolution models (LEMs) helps to illustrate the effects of different model formulations or parameterizations. For example, including a threshold in the incision term of an LEM affects the resulting slope–area line (e.g., Tucker, 2004; Lague et al., 2005; Deal et al., 2018).



In the case of landscapes that are influenced by diffusion, topographic slope does not scale as a power function of drainage area (e.g., Howard, 1994). Thus, slope and area data from these landscapes do not plot as straight lines. In Theodoratos et al. (2018), we presented a counterpart relationship for the case of such landscapes. This relationship predicts that in steady state, curvature and the steepness index (which depends on drainage area and slope; e.g., Whipple, 2001) plot as a straight line against each other on linear (i.e., non-logarithmic) axes. The slope and intercept of this line depend on the characteristic scales of length and height of the landscape, which in turn depend on the relative strengths of the processes that shape it. Thus, this relationship predicts a link between topographic and scaling properties of landscapes that follow the LEM.

Here, we demonstrate an example of the explanatory power of plots of curvature versus the steepness index. Specifically, we show that these plots reveal how incision thresholds affect the topography, the competition between processes, and key scales of the landscape, such as the smallest scales of dissection. These effects have been studied before (e.g., Montgomery and Dietrich, 1992; Howard, 1994; Tucker, 2004; Perron et al., 2008). Here, however, we present a novel, purely graphical method to identify, quantify, and interpret these effects based on the relationship between curvature and the steepness index.

2 Stream-power incision and linear diffusion LEMs

In Theodoratos et al. (2018), we dimensionally analyzed a frequently used LEM with terms for uplift, linear diffusion, and stream-power incision without an incision threshold. In Theodoratos and Kirchner (2020), we added an incision threshold to this LEM and dimensionally analyzed it. We begin this presentation by summarizing the governing equations of these two LEMs and the definitions of key quantities involved in their dimensional analyses.

2.1 Governing equations

The LEM without incision threshold follows the governing equation (e.g., Howard, 1994; Dietrich et al., 2003):

$$\frac{\partial z}{\partial t} = -K\sqrt{A}|\nabla z| + D\nabla^2 z + U \quad (1)$$

This equation gives the rate of elevation change $\partial z/\partial t$ as the sum of three terms, namely, a) stream-power incision $K\sqrt{A}|\nabla z|$, where K is the incision coefficient, A is drainage area, and $|\nabla z|$ is topographic slope, b) linear diffusion $D\nabla^2 z$, where D is the diffusion coefficient and $\nabla^2 z$ is the Laplacian curvature, and c) the uplift rate U . We assume that Eq. (1) has base dimensions of horizontal length L , height H (which we treat as dimensionally distinct from L), and time T . All quantities in Eq. (1) have dimensions that are combinations of L , H , and/or T , which we show in Table 1.

Note that the incision term $K\sqrt{A}|\nabla z|$ is a special case of the more general incision term $KA^m(|\nabla z|)^n$. As we explained in Theodoratos et al. (2018), dimensional analysis of an LEM with generic exponents m and n would lead to equivalent results as the analysis of Eq. (1), but these results would be expressed with much more complicated mathematical formulas.

Therefore, in Theodoratos et al. (2018) as well as in the present study, we focus on the case of LEMs with exponents $m = 0.5$ and $n = 1$.

Following Perron et al. (2008), we can add an incision threshold to the LEM by recasting the incision term as $K(\sqrt{A}|\nabla z| - \theta)$, where θ is the incision threshold. This formulation assumes that the incision rate $K\sqrt{A}|\nabla z|$ is reduced



everywhere by the constant quantity $K\theta$. Because a negative incision rate would not be meaningful, the incision term is set to zero where the term $K(\sqrt{A}|\nabla z| - \theta)$ would be negative, i.e., where $\sqrt{A}|\nabla z| \leq \theta$. Thus, the governing equation becomes

$$\frac{\partial z}{\partial t} = \begin{cases} D\nabla^2 z + U, & \sqrt{A}|\nabla z| \leq \theta \\ -K(\sqrt{A}|\nabla z| - \theta) + D\nabla^2 z + U, & \sqrt{A}|\nabla z| > \theta \end{cases} \quad (2)$$

The incision threshold θ has the same dimensions as $\sqrt{A}|\nabla z|$, i.e., dimensions of H.

- 5 Equation (2) assumes that precipitation is constant and uniform, and incorporates the control of climate on incision into the incision coefficient K . Thus, the incision threshold θ plays the role of a topographic limit. It defines a value of the quantity $\sqrt{A}|\nabla z|$ below which incision does not operate. Other LEMs use stochastic precipitation to drive their incision terms (e.g., Tucker, 2004, Whipple, 2004; Lague et al., 2005; DiBiase and Whipple, 2011; Deal et al., 2018). The incision thresholds of these LEMs define limiting values of shear stress or stream power, below which no incision occurs. At any given location in the landscape, these limiting values might be exceeded during some stochastic events and not exceeded during other events depending on their intensities. These LEMs allow a much more realistic time-integration of incision compared to the LEM that we examine here. However, our study focuses on using curvature–steepness-index lines to derive graphical interpretations of the effects of incision thresholds on topographic and spatial scaling properties of steady-state landscapes. For this task, the simplified formulation of the incision term of Eq. (2) is more practical.

15 2.2 Characteristic scales

The two governing equations (Eqs. 1 and 2) can be non-dimensionalized using characteristic scales of length, height, and time l_c , h_c , and t_c , defined as (Theodoratos et al., 2018; Theodoratos and Kirchner, 2020)

$$l_c := \sqrt{D/K} \quad , \quad (3)$$

$$h_c := U/K \quad , \quad (4)$$

$$t_c := 1/K \quad . \quad (5)$$

- We summarize these and other definitions of this presentation in Table 2. The characteristic scales l_c , h_c , and t_c can be viewed as intrinsic properties of a landscape, in the sense that they depend exclusively on the values of the parameters K , D , and U , and not on extensive properties of the landscape such as the size of its domain or its maximum relief. We present geomorphologic interpretations of these characteristic scales in Sect. 3.

By combining l_c , h_c , and t_c we can define additional characteristic scales (Theodoratos et al., 2018). For example, given that drainage areas A have dimensions L^2 , we can define a characteristic area A_c as the square of the characteristic length:

$$A_c := l_c^2 = D/K \quad . \quad (6)$$

- 25 Likewise, we can define a characteristic gradient G_c

$$G_c := h_c/l_c = U/\sqrt{DK} \quad , \quad (7)$$

and a characteristic curvature κ_c

$$\kappa_c := h_c/l_c^2 = U/D \quad . \quad (8)$$



2.3 Incision-threshold number N_θ

In Theodoratos and Kirchner (2020), we derived a dimensionless number, whose definition and interpretation we summarize here. Dimensional analysis of the governing equation with incision threshold θ (Eq. 2) yielded the dimensionless grouping of parameters $K\theta/U$. The quantity $K\theta$ gives the reduction in the rate of incision due to the threshold and, thus, it has dimensions of elevation change rate H T^{-1} . Therefore, the ratio of $K\theta$ to U is dimensionless. We defined this dimensionless ratio as an incision-threshold number N_θ

$$N_\theta := K\theta/U \quad . \quad (9)$$

Our analysis led to a dimensionless version of Eq. (2) that includes only one parameter, the incision-threshold number N_θ . This implies that N_θ is a control on the topography of landscapes that follow Eq. (2). Specifically, landscapes that have equal incision-threshold numbers N_θ can be set up such that they follow geometrically similar evolutions. Landscapes that have different N_θ cannot evolve geometrically similarly, and their topographies differ in ways that depend on their N_θ values. Simulation results illustrating these points are presented in Theodoratos and Kirchner (2020).

We proposed two interpretations of the incision-threshold number N_θ in Theodoratos and Kirchner (2020). First, N_θ is defined as the incision rate reduction $K\theta$ relative to the uplift rate U (Eq. 9). The uplift rate U can be viewed as a characteristic rate of elevation change because it is equal to the ratio of the characteristic height to the characteristic time, i.e., $U = h_c/t_c$ (Eqs. 4, 5). Consequently, N_θ is a normalized incision rate reduction with respect to U . Second, if we rearrange Eq. (9) as $N_\theta = \theta/(U/K)$, then we can interpret N_θ as giving the magnitude of θ relative to the parameter ratio U/K . Thus, the definition of N_θ shows that incision thresholds from different landscapes should not be compared to each other according to their own values, but instead according to their values relative to the ratio U/K of each landscape.

3 Graphical illustrations of topographic and scaling effects of the incision threshold

3.1 Defining a steady-state topographic relationship between the steepness index and curvature

In Theodoratos et al. (2018), we presented a relationship that describes the steady-state topography of landscapes that evolve according to Eq. (1). Specifically, if we set $\partial z/\partial t = 0$ and we solve the governing equation for curvature $\nabla^2 z$, we obtain

$$\partial z/\partial t = 0: \quad \nabla^2 z = (K/D)\sqrt{A}|\nabla z| - (U/D) \quad . \quad (10)$$

The quantity $\sqrt{A}|\nabla z|$ is equal to the steepness index (defined as $A^{m/n}|\nabla z|$ for drainage area and slope exponents m and n ; e.g., Whipple, 2001). For this reason, we refer to Eq. (10) as the curvature–steepness-index relationship.

In a coordinate system in which the steepness index ($\sqrt{A}|\nabla z|$) and curvature ($\nabla^2 z$) are plotted on the horizontal and vertical axes, respectively, Eq. (10) plots as a straight line (for example, see Fig. 1, which we describe in more detail further below). Equation (10) is a testable, quantitative prediction; if a landscape is in steady state and has evolved according to Eq. (1), then curvature should plot as a straight line against the steepness index. Furthermore, this line can give estimates of the parameters K , D , and U , because its slope is K/D , and its intercepts are $\nabla^2 z = -U/D$ and $\sqrt{A}|\nabla z| = U/K$. While we have not validated this prediction with data, Eq. (10) is a rearranged version of Eq. (5) in Perron et al. (2009), which has been tested with real-world landscape data and has been used to estimate model parameters.



3.2 Characteristic scales and the curvature–steepness-index relationship

If we substitute the characteristic scales l_c and κ_c for the parameter ratios K/D and U/D , then the curvature–steepness-index relationship (Eq. 10) becomes

$$\partial z / \partial t = 0: \quad \nabla^2 z = (1/l_c^2) \sqrt{A} |\nabla z| - \kappa_c \quad (11)$$

As this equation shows, an interpretation of l_c and h_c is that they control steady-state topography. Specifically, for a landscape to be in steady state, drainage area A , topographic slope $|\nabla z|$, and curvature $\nabla^2 z$ must obey Eq. (11), which is parameterized by the characteristic scales l_c and κ_c , or equivalently by l_c and h_c because $\kappa_c = h_c/l_c^2$ (Eq. 8). We can graphically illustrate the control of l_c and h_c on the topography by plotting the curvature–steepness-index line described by Eq. (11). As Fig. 1 shows, the properties of such a line are controlled by l_c and h_c , specifically, its slope is $1/l_c^2$, and its intercepts are $\nabla^2 z = -\kappa_c = -h_c/l_c^2$ and $\sqrt{A} |\nabla z| = h_c$. Note that the slope of this line can be represented either as $K/D = 1/l_c^2$ units of curvature per 1 unit of steepness index, or 1 unit of curvature per $D/K = l_c^2$ units of steepness index. For simplicity, we use the latter notation to express the slopes of the curvature–steepness-index lines in Figs. 2–4.

Likewise, the curvature–steepness-index relationship that corresponds to the LEM with incision threshold θ is controlled by the characteristic scales l_c and κ_c . This relationship, however, is also controlled by the incision-threshold number N_θ . To derive this relationship, we set $\partial z / \partial t = 0$ in Eq. (2) and we solve it for $\nabla^2 z$. When we do this for the second subdomain (where $\sqrt{A} |\nabla z| > \theta$), we encounter the ratio $K\theta/D$. This ratio can be rewritten as $K\theta/D = (K\theta U)/(U D) = N_\theta \kappa_c$ (Eqs. 8, 9). Thus, we obtain the curvature–steepness-index relationship:

$$\partial z / \partial t = 0: \quad \begin{cases} \nabla^2 z = -\kappa_c, & \sqrt{A} |\nabla z| \leq \theta \\ \nabla^2 z = (1/l_c^2) \sqrt{A} |\nabla z| - (1 + N_\theta) \kappa_c, & \sqrt{A} |\nabla z| > \theta \end{cases} \quad (12)$$

We plot this equation in Fig. 2 in black and, for comparison, we also plot the curvature–steepness-index line without incision threshold (Eq. 11) in gray. The black line consists of two segments that correspond to the two subdomains of Eqs. (2) and (12). The first segment is horizontal and describes a uniform steady-state curvature value of $\nabla^2 z = -\kappa_c$ for points with $\sqrt{A} |\nabla z| \leq \theta$, where incision is fully suppressed by the threshold and only diffusion and uplift operate. The second segment is inclined and corresponds to points with $\sqrt{A} |\nabla z| > \theta$ where all three processes operate.

Equations (11–12) and Figs. 1–2 show that the characteristic scales l_c , h_c , and κ_c describe the steady-state topography at points of special interest (see also Theodoratos et al., 2018). Furthermore, some effects of incision thresholds on landscape properties can be visualized by comparing the curvature–steepness-index lines with and without an incision threshold (black and gray lines of Fig. 2).

First, the vertical-axis intercept of the curvature–steepness-index line without incision threshold (Fig. 1, Eq. 11) corresponds to ridges and drainage divides, which have $A = 0$ and/or $|\nabla z| = 0$, i.e., $\sqrt{A} |\nabla z| = 0$. This intercept shows that the steady-state curvature of ridges and drainage divides is $\nabla^2 z = -\kappa_c = -U/D$ (see also Roering et al., 2007; Perron et al., 2009). Note that $-\kappa_c$ is the most negative value of curvature. The horizontal segment of the black line in Fig. 2 (described by the first subdomain of Eq. 12) expresses the fact that, in landscapes with an incision threshold θ , the points with $\sqrt{A} |\nabla z| \leq \theta$ have the same steady-state curvature as ridges and drainage divides, i.e., the most negative value of curvature. This shows that adding an incision threshold to the LEM results in more convex hillslopes (e.g., Howard, 1994; Theodoratos and Kirchner, 2020).



Second, the curvature–steepness-index line without incision threshold (Fig. 1, Eq. 11) has a horizontal-axis intercept of $\sqrt{A}|\nabla z| = h_c$. This intercept corresponds to points with curvature $\nabla^2 z = 0$, which can be viewed as defining the transition between hillslopes and valleys (e.g., Howard, 1994). Thus, points with steepness index equal to the characteristic height h_c can be used to map hillslope–valley transitions (Theodoratos et al., 2018). Adding an incision threshold θ to the LEM makes landscapes steeper and decreases the drainage density, i.e., makes first-order basins bigger, (e.g., Montgomery and Dietrich, 1992; Howard, 1994; Perron et al., 2008). These two effects lead to steeper gradients $|\nabla z|$ and larger drainage areas A at hillslope–valley transitions. Specifically, as Fig. 2 shows, the horizontal-axis intercept increases from $\sqrt{A}|\nabla z| = h_c$ (gray line) to $\sqrt{A}|\nabla z| = h_c + \theta$ (black line).

3.3 Quantifying and visualizing the effect of the incision threshold on the scales of landscape dissection

In Theodoratos et al. (2018), we derived an interpretation of the characteristic length l_c by analyzing the competition between the advection and diffusion of elevation perturbations (e.g., knickpoints), which gives rise to ridges and valleys, and controls their characteristic sizes (e.g., Smith and Bretherton, 1972; Howard, 1994; Perron et al., 2008). Following Perron et al. (2008, 2009, 2012), we quantified the relative strength of advection versus diffusion using a Péclet number Pe . The definition of our Péclet number differs somewhat from Perron et al.'s. Specifically, our definition includes a length scale l that we termed flow path length and that we defined as the distance along flow paths from a given point to the farthest ridge.

The Péclet number is defined (e.g., Perron et al., 2008) as the ratio of a diffusion timescale t_D to an incision timescale t_I , each of which gives a measure of the strength of the respective process. Specifically, a diffusion timescale can be defined as (e.g., Perron et al., 2008)

$$t_D := \frac{l^2}{D} \quad . \quad (13)$$

This timescale characterizes diffusive propagation over a distance l . In Theodoratos et al. (2018), to define t_I , we first calculated the celerity c that corresponds to the incision term of Eq. (1), which is a kinematic wave term (e.g., Whipple and Tucker, 1999). This celerity is equal to $c = K\sqrt{A}$. Perturbations can be assumed to be advected at this celerity (e.g., Berlin and Anderson, 2007; Perron et al., 2008). Lague (2014) has criticized this assumption because it does not take into account the effects of knickpoints on hydraulics (e.g., on stream width) and their feedbacks on the rate of knickpoint propagation, especially in the presence of incision thresholds. While we acknowledge this limitation, we nonetheless assume that the rate of knickpoint advection is equal to the celerity c of Eq. (17) because our current focus is on interpreting the characteristic scales l_c , h_c , and t_c , which pertain to Eqs. (1) and (2), which do not describe hydraulics explicitly. Therefore, in Theodoratos et al. (2018), we defined the incision timescale t_I as the ratio of the flow path length l , which characterizes the location of points within drainage basins, to the celerity c , which characterizes the strength of advection:

$$t_I := l/c = \frac{l}{K\sqrt{A}} \quad . \quad (14)$$

Note that small values of t_I and t_D correspond to strong advection and diffusion, respectively.



We can quantify the relative strengths of advection and diffusion using the ratio of the respective timescales, which defines the Péclet number (Theodoratos et al., 2018):

$$Pe := t_D/t_I = \frac{\sqrt{A} l}{l_c^2} = \frac{\sqrt{A}}{\sqrt{A_c}} \frac{l}{l_c} \quad (15)$$

Diffusive propagation is stronger at points with Péclet number smaller than 1 and advective propagation is stronger where the Péclet number is larger than 1. Where the Péclet number is roughly equal to one, diffusion and advection will be roughly equal (when measured by t_D and t_I). Equation (15) shows that if a point's flow path length l is roughly equal to the characteristic length l_c and its drainage area A is roughly equal to the characteristic area A_c , then its Péclet number will be roughly equal to one. i.e.,

$$l \approx l_c, \quad A \approx A_c \approx l_c^2 \quad \Rightarrow \quad Pe \approx 1 \quad (16)$$

Note that if the incision term has a slope exponent $n \neq 1$, then the condition $|\nabla z| \approx G_c$ must be included along with $l \approx l_c$ and $A \approx l_c^2$ for the Péclet number to be $Pe \approx 1$.

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The conditions $A \approx l_c^2$ and $l \approx l_c$ (Eq. 16) are not the only combination of A and l that give $Pe \approx 1$, but they are significant because they lead to an interpretation of l_c . Specifically, these conditions show that advective propagation, which promotes valley dissection, is dominant at points farther than l_c from the ridge and with drainage area greater than l_c^2 . Therefore, in Theodoratos et al. (2018) we interpreted the characteristic length l_c as giving a measure of the smallest scales of dissection.

15 This interpretation does not imply that valley heads are exactly $1 l_c$ away from ridges or that they have drainage areas exactly equal to $1 l_c^2$. Rather, it implies that flow path lengths and drainage areas of valley heads are of similar order of magnitude as l_c and l_c^2 , respectively. Furthermore, it implies that valley heads in different landscapes have l and A that scale with l_c and l_c^2 , respectively.

20 Adding the threshold θ to the incision term of the LEM changes the kinematic wave celerity c and, thus, the incision timescale t_I and the Péclet number Pe . Specifically, the celerity becomes

$$c = \begin{cases} 0, & \sqrt{A}|\nabla z| \leq \theta \\ K\sqrt{A} - K\theta/|\nabla z|, & \sqrt{A}|\nabla z| > \theta \end{cases} \quad (17)$$

and, thus, the incision timescale t_I becomes

$$t_I := l/c = \begin{cases} +\infty, & \sqrt{A}|\nabla z| \leq \theta \\ \frac{l}{K\sqrt{A} - K\theta/|\nabla z|}, & \sqrt{A}|\nabla z| > \theta \end{cases} \quad (18)$$

Note that the diffusion timescale t_D is not affected by the incision threshold. Thus, we can use Eqs. (13) and (18) to define a Péclet number Pe for the LEM with incision threshold θ (Eq. 2), specifically

$$Pe := t_D/t_I = \begin{cases} 0, & \sqrt{A}|\nabla z| \leq \theta \\ \frac{\sqrt{A} l - (\theta l/|\nabla z|)}{l_c^2}, & \sqrt{A}|\nabla z| > \theta \end{cases} \quad (19)$$

25 It can be shown that Eq. (19) can be rewritten as

$$Pe := t_D/t_I = \begin{cases} 0, & \sqrt{A}|\nabla z| \leq \theta \\ \frac{\sqrt{A}}{\sqrt{A_c}} \frac{l}{l_c} - N_\theta \frac{l}{l_c} \frac{G_c}{|\nabla z|}, & \sqrt{A}|\nabla z| > \theta \end{cases} \quad (20)$$



where N_θ is the incision-threshold number (Eq. 9). Equation (20) shows that adding an incision threshold θ to the LEM reduces the Péclet number relative to the Péclet number for the LEM without a threshold (Eq. 15). This agrees with the fact that the threshold weakens the incision term. More specifically, the Péclet number for the LEM with θ is reduced by the quantity $N_\theta(l/l_c)(G_c/|\nabla z|)$.

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Using Eq. (20) we see that the conditions $l \approx l_c$, $A \approx l_c^2$, and $|\nabla z| \approx G_c$, which lead to a Péclet number roughly equal to 1 for the case without incision threshold (Eq. 16), will lead to $Pe \approx 1 - N_\theta < 1$ when θ is included. The fact that the difference between Pe and 1 is equal to N_θ suggests that we could obtain the value $Pe \approx 1$ by adjusting the values of l , A , and $|\nabla z|$ such that they depend on N_θ . Indeed, we observe that

$$l \approx \sqrt{1 + N_\theta} l_c, \quad A \approx (1 + N_\theta) l_c^2, \quad |\nabla z| \approx \sqrt{1 + N_\theta} G_c \quad \Rightarrow \quad Pe \approx 1 \quad . \quad (21)$$

10 Note that $\sqrt{1 + N_\theta} l_c$ is larger than l_c , which agrees with observations that incision thresholds reduce landscape dissection (e.g., Montgomery and Dietrich, 1992; Howard, 1994; Perron et al., 2008).

Equation (21) shows that, in the case of a landscape that includes an incision threshold θ , the smallest scales of dissection are not characterized by the characteristic length l_c on its own, but rather jointly by l_c and the incision-threshold number N_θ

15 through the quantity $\sqrt{1 + N_\theta} l_c$. Consequently, the presence of θ changes the dependence of the scales of dissection on the LEM parameters. Without an incision threshold, the scales of landscape dissection depend on l_c , which depends on the incision and diffusion coefficients K and D (Eq. 3). On the other hand, when θ is included in the LEM, the scales of dissection depend on $\sqrt{1 + N_\theta} l_c$, which depends on K and D , but also on the uplift rate U and the incision threshold θ . We illustrate an example of the dependence on U in Fig. 4 b.

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The length scales l_c and $\sqrt{1 + N_\theta} l_c$ can be expressed graphically by the horizontal- and vertical-axis intercepts of curvature–steepness-index lines, specifically, by the ratio of these intercepts (or, more precisely, by the ratio of their absolute values). This ratio is equal to $h_c/\kappa_c = l_c^2$ in the case without incision threshold (see Fig. 1) and equal to $(h_c + \theta)/\kappa_c = (1 + N_\theta)l_c^2$ in the case that includes the incision threshold θ (see Fig. 2). Note that the first ratio is equal to the inverse of the slope of the curvature–steepness-index line, which is $1/l_c^2$. On the other hand, the second ratio is not the inverse of this slope, which remains $1/l_c^2$ when the threshold θ is included. Instead, it is the inverse of the slope of an auxiliary line connecting the two intercepts. In Fig. 2, we show this auxiliary line with a black dashed line style. The effect of the incision threshold on valley dissection can be visualized graphically by comparing the slope of the curvature–steepness-index line against the slope of the black dashed auxiliary line. We denote this comparison as a thick white arrow.

30 3.4 How the curvature–steepness-index line responds to parameter value changes

As we show in Figs. 3 and 4, differences in the properties of landscapes with different parameters K , D , U , and θ can be graphically summarized by curvature–steepness-index lines, because the slopes and intercepts of these lines depend on the characteristic scales l_c , h_c , and κ_c , and on the incision-threshold number N_θ , which in turn depend on the parameters.

35 Figure 3 shows curvature–steepness-index lines without incision thresholds. It consists of three panels, each showing how the lines respond to an increase in one of the three parameters U , K , and D . In panel (a), an increase in the uplift rate U shifts the curvature–steepness-index line downward and to the right without changing its slope. This illustrates that the



characteristic height and curvature h_c and κ_c , which control the intercepts of the line, are proportional to U (Eqs. 4, 8), while the characteristic length l_c , which controls the line's slope, is independent of U (Eq. 3). The parallel shift of the line corresponds to more convex ridges (so that diffusion can keep up with uplift), to steeper gradients (so that incision can keep up with uplift), and to unchanged landscape dissection. Analogously, panel (b) shows that an increase in the incision coefficient K leads to a counterclockwise rotation of the line around the vertical-axis intercept, which corresponds to a more dissected landscape (smaller l_c), milder gradients (smaller h_c), and unchanged ridge convexity (unchanged κ_c). Finally, in panel (c), an increase in the diffusion coefficient D results in a clockwise rotation of the line around the horizontal-axis intercept. This corresponds to a smoother landscape with less dissection (larger l_c) and less convex ridges (smaller κ_c), and to unchanged steepness index at hillslope–valley transitions (unchanged h_c).

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Figure 4 illustrates in four panels how curvature–steepness-index lines respond to increases in the value of either the incision threshold θ or one of the parameters U , K , and D . It is reminded that a curvature–steepness-index line with incision threshold consists of two segments, a horizontal and an inclined. Note that, as we explain in the previous subsection (Sect. 3.3), a curvature–steepness-index line that includes an incision threshold does not express landscape dissection through the slope of its inclined segment, which depends only on the characteristic length l_c , but rather through the ratio of the horizontal- and vertical-axis intercepts, which is equal to $\sqrt{1 + N_\theta} l_c$. This ratio can be graphically illustrated by the slope of an auxiliary line that connects the two intercepts, such as the dashed black line in Fig. 2. In each panel of Fig. 4, we show two dashed black auxiliary lines to illustrate how the ratio of intercepts responds to the parameter changes.

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In panel (a) of Fig. 4, we illustrate an increase in θ . The steepness index $\sqrt{A}|\nabla z|$ must reach a greater value before exceeding the increased θ and, thus, the horizontal segment of the curvature–steepness-index line becomes longer. The vertical position of this segment (along with the vertical-axis intercept) do not change, because the characteristic curvature κ_c does not depend on θ . The slope of the curvature–steepness-index line also does not change, because l_c does not depend on θ . Thus, the increase of θ parallel-shifts the inclined segment of the line to the right. Consequently, the horizontal-axis intercept increases, which expresses the steepening of gradients and the decrease of landscape dissection. The decrease of dissection is also expressed by the fact that the ratio of the horizontal- to the vertical-axis intercept increases, as shown by the clockwise rotation of the dashed auxiliary lines.

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In panel (b) of Fig. 4, we show that an increase in the uplift rate U parallel-shifts the curvature–steepness-index line downward and to the right. Furthermore, the horizontal- and vertical-axis intercepts move to the right and downward, respectively (κ_c and h_c are proportional to U), and the slope of the inclined segment remains unchanged (l_c does not depend on U). As we explain in Sect. 3.3, the value of U affects the value of $\sqrt{1 + N_\theta} l_c$, which expresses the scales of landscape dissection. Specifically, the increase of U leads to a decrease of N_θ . This reflects the fact that θ becomes less important relative to the increased U . Thus, the decrease of dissection due to the threshold is somewhat moderated by the increase of U . This moderation is graphically illustrated by the slopes of auxiliary lines connecting the intercepts of the curvature–steepness-index lines. These auxiliary lines do not intersect and, thus, their slopes cannot be readily compared visually. Therefore, we plot them again in an inset such that they start from the same point. In this way, we can see that the increase of U leads to a counterclockwise rotation of the auxiliary lines, which expresses the increase of dissection.

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In panel (c) of Fig. 4, we illustrate the response of the curvature–steepness-index line to an increase in the incision coefficient K . The horizontal segment of the line remains unchanged and the inclined segment is rotated counterclockwise around the point of transition between the two segments. Likewise, the dashed auxiliary line connecting the horizontal- and vertical-axis intercepts is rotated counterclockwise. These responses express that dissection is decreased and that gradients become milder when K is increased. Finally, in panel (d), we show that increasing the diffusion coefficient D leads to a clockwise rotation of the inclined segment of the line around its horizontal-axis intercept, which remains unchanged. The rotation results in moving the horizontal segment up and in rotating the dashed auxiliary line clockwise. These changes express the reduction in landscape dissection and the reduction in the convexity of ridges and hillslopes.

4 Quantifying how the influence of the incision threshold varies within a landscape

Thus far, we have examined how the influence of the incision threshold θ varies between different landscapes with different parameters using the incision-threshold number N_θ (Eq. 9). This number is constant for any given landscape if the parameters of the landscape are constant. Now, we turn our attention to how the influence of the incision threshold θ varies within a given landscape.

We can quantify the relative influence of the threshold θ on the rate of incision using the fraction $\theta/(\sqrt{A}|\nabla z|)$. This fraction is equal to $K\theta$, the reduction in the incision rate due to the threshold, divided by $K\sqrt{A}|\nabla z|$, the incision rate if there would be no threshold. Therefore, $\theta/(\sqrt{A}|\nabla z|)$ shows by what fraction the incision rate is reduced due to the threshold. Where $\sqrt{A}|\nabla z| = \theta$, the fraction $\theta/(\sqrt{A}|\nabla z|)$ is equal to 1, which agrees with the incision rate being reduced by 100% (i.e., being reduced to zero). At points with $\sqrt{A}|\nabla z|$ smaller than θ , calculating the fraction $\theta/(\sqrt{A}|\nabla z|)$ would not be meaningful; instead, because the threshold completely suppresses incision under these conditions, we assign a value of 1 to the fractional reduction in incision rate.

We can associate the fractional reduction in incision rate to Tucker’s (2004) threshold factor Φ . Tucker (2004) defined Φ to quantify the fraction of precipitation events leading to shear stress above a threshold value, i.e., the fraction of events that lead to erosion. Tucker (2004) used Φ to express the incision term of his LEM as $KA^{m_b}S^{n_b}\Phi$. In the case of the LEM examined here (Eq. 2), following Tucker’s notation, we can express the incision term as $K\sqrt{A}|\nabla z|\Phi$, where the threshold factor Φ is equal to $1 - \theta/(\sqrt{A}|\nabla z|)$ for $\sqrt{A}|\nabla z| > \theta$ and to 0 for $\sqrt{A}|\nabla z| \leq \theta$. Thus, the quantity $1 - \Phi$ is equal to the fractional reduction in incision rate, i.e.,

$$1 - \Phi = \begin{cases} 1, & \sqrt{A}|\nabla z| \leq \theta \\ \frac{\theta}{\sqrt{A}|\nabla z|}, & \sqrt{A}|\nabla z| > \theta \end{cases} \quad (22)$$

Consequently, in what follows we denote the fractional reduction in incision rate as $1 - \Phi$. We illustrate the properties of the quantity $1 - \Phi$ with plots and maps in Figs. 5–7.

In Fig. 5 we plot $1 - \Phi$ versus the steepness index $\sqrt{A}|\nabla z|$ according to Eq. (22). The curve consists of two parts. The first is a horizontal segment that describes the value $1 - \Phi = 1$ and corresponds to points with $\sqrt{A}|\nabla z| \leq \theta$, where incision is fully suppressed by the threshold. The second part corresponds to points with $\sqrt{A}|\nabla z| > \theta$, forming part of a hyperbola that



asymptotically approaches 0. This asymptotic approach expresses the fact that, at points with steepness index $\sqrt{A}|\nabla z|$ much larger than θ , the incision threshold has a very small relative influence on the incision rate.

To indicate how different parts of the $1 - \Phi$ curve of Fig. 5 correspond to different regimes of a landscape, we identify the point that corresponds to hillslope–valley transitions. As explained in Sect. 3.2, hillslope–valley transitions can be defined as points with zero curvature and, therefore, with a steady-state steepness index of $\sqrt{A}|\nabla z| = h_c + \theta$. Consequently, the fractional reduction in incision rates $\theta/(\sqrt{A}|\nabla z|)$ at these points is $\theta/(h_c + \theta)$. We can rewrite this value in terms of the incision-threshold number N_θ as $N_\theta/(1 + N_\theta)$. Thus, in Fig. 5, hillslope–valley transitions correspond to the point with coordinates $(\sqrt{A}|\nabla z|, 1 - \Phi) = (h_c + \theta, N_\theta/(1 + N_\theta))$, which we mark with a black dot. The part of the curve above and to the left of this dot corresponds to hillslopes, and the part below and to the right corresponds to the valley network.

With Fig. 6, we examine how the value of the incision-threshold number N_θ of a landscape controls the relationship between the quantity $1 - \Phi$ and the steepness index $\sqrt{A}|\nabla z|$. Specifically, in Fig. 6 we show curves of $1 - \Phi$ versus $\sqrt{A}|\nabla z|$ for four landscapes with incision-threshold numbers N_θ equal to 0.2, 0.4, 1, and 2. The landscapes are assumed to have equal parameters K , D , and U , and therefore to have equal characteristic scales. The curves with greater values of N_θ also have greater incision thresholds θ and, thus, they have longer horizontal segments. Furthermore, the curves with greater values of N_θ go towards zero more slowly. On each curve, we show the hillslope–valley transition using a black dot. The value of the quantity $1 - \Phi$ corresponding to each dot becomes larger as N_θ increases. Thus, in landscapes with smaller N_θ , the incision rate is reduced by large fractions only on the hillslopes, and in valleys it is reduced by small fractions. By contrast, in landscapes with greater N_θ , incision can be reduced by large fractions both on hillslopes and in valleys.

Figure 7 shows maps of the quantity $1 - \Phi$ across four steady-state landscapes. We simulated these landscapes with the CHILD numerical model (Channel-Hillslope Integrated Landscape Development model; Tucker et al., 2001). Details about these simulations and additional results are presented in Theodoratos and Kirchner (2020). Here, we provide brief information about the parameters and setup of these simulations in Appendix A. To illustrate how the spatial distribution of $1 - \Phi$ depends on the incision-threshold number N_θ , we ran four simulations with N_θ values of 0.2, 0.4, 1, and 2, i.e., the same N_θ values as in Fig. 6. The pixels of the four maps are colored according to their values of $1 - \Phi$ using a grayscale that ranges from white to black. Lighter colors correspond to larger values of $1 - \Phi$, i.e., to stronger influence of the incision threshold. As expected, lighter colors appear near ridges and on hillslopes, where the incision threshold has a stronger influence.

The fractional reduction in incision rate as $1 - \Phi$ and the threshold factor Φ can be used to simplify the definition of the Péclet number Pe . Specifically, we can rearrange the definition of Pe (Eq. 19) such that it includes the fraction $\theta/(\sqrt{A}|\nabla z|)$:

$$Pe = \begin{cases} 0, & \sqrt{A}|\nabla z| \leq \theta \\ \left(1 - \frac{\theta}{\sqrt{A}|\nabla z|}\right) \frac{\sqrt{A}}{\sqrt{A_c}} \frac{l}{l_c}, & \sqrt{A}|\nabla z| > \theta \end{cases} \quad (23)$$

If this equation is combined with the definition of $1 - \Phi$ (Eq. 22), then we can rewrite the definition of Pe in compact form

$$Pe = \Phi \cdot Pe_{\theta=0} \quad (24)$$



where $Pe_{\theta=0}$ is the Péclet number for the LEM without incision threshold (see Eq. 15). Equations (23) and (24) reveal that the influence of the incision threshold on the Péclet number varies across the landscape. Specifically, larger values of Pe , which correspond to larger values of the steepness index $\sqrt{A}|\nabla z|$, are less sensitive to the incision threshold.

5 Summary and conclusions

- 5 We present graphical methods that summarize topographic and scaling properties of landscapes following a simple stream-power incision and linear diffusion LEM (Eq. 1), and that illustrate the effects of adding an incision threshold θ (Eq. 2). Our results referring to the LEM without incision threshold (Eq. 1) have been presented before (Theodoratos et al., 2018), but we show them here again to contrast them against those referring to the LEM with the threshold θ (Eq. 2).
- 10 For the first graphical method, we plot steady-state relationships between curvature $\nabla^2 z$ and the steepness index $\sqrt{A}|\nabla z|$ (Eqs. 10, 11, 12), which we obtain from the governing equations Eq. (1) and (2). These relationships can be viewed as counterparts of the relationship between topographic slope and drainage area, which is typically assumed to follow a power law in detachment-limited landscapes, but not in landscapes that are also influenced by hillslope diffusion. These relationships plot as straight lines (Figs. 1 and 2), whose properties (slope and intercepts) depend on the incision threshold θ
- 15 and on the characteristic scales of the landscape, which in turn depend on the parameters of the LEM, i.e., on the incision coefficient K , the diffusion coefficient D , and the uplift rate U . (Eqs. 3, 4, and 8).

With Fig. 2, we show that curvature–steepness-index lines can graphically illustrate effects of incision thresholds on landscapes. Specifically, the ways in which curvature–steepness-index lines with and without threshold differ from each other illustrate that thresholds make hillslopes more convex and gradients steeper, and reduce the drainage density. These effects have been presented elsewhere (e.g., Montgomery and Dietrich, 1992; Howard, 1994; Perron et al., 2008), but the curvature–steepness-index lines offer new ways to visualize them graphically. In Figs. 3 and 4, we illustrate the dependence of these properties on the parameters K , D , U , and θ by showing how curvature–steepness-index lines respond to increases in these parameters, one at a time. These figures demonstrate an advantage of curvature–steepness-index lines: the topographic effects of model parameter changes are expressed as simple shifts and rotations of these lines.

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In Sect. 3.3, we examine in more detail the effects of the incision threshold θ on drainage density and the scales of landscape dissection, and how these effects can be visualized with curvature–steepness-index lines. We assume that dissection is controlled by the competition between the advection and diffusion of perturbations (e.g., Smith and Bretherton, 1972; Howard, 1994; Perron et al., 2008) and, thus, we examine the effects of θ using a Péclet number Pe (Eqs. 15, 19; see also Perron et al., 2008, 2012; Theodoratos et al., 2018). For the LEM that does not include an incision threshold, we found in Theodoratos et al. (2018) that the characteristic length l_c characterizes the smallest scales of dissection. Note that the slope of curvature–steepness-index lines is $1/l_c^2$; therefore, this slope graphically expresses the scales of dissection of landscapes without incision thresholds. Adding the incision threshold θ , we find that the smallest scales of dissection are characterized

30 by the length scale $\sqrt{1 + N_\theta} l_c$, where N_θ is a dimensionless incision-threshold number defined as $N_\theta = K\theta/U$ (Eq. 9). This length scale is longer than l_c , which expresses the fact that incision thresholds reduce the drainage density. The square of this length scale is $(1 + N_\theta) l_c^2$ and is equal to the ratio between the horizontal- and vertical-axis intercepts of the curvature–steepness-index line. As we show in Fig. 2, an auxiliary line connecting these two intercepts would have a slope of

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$1/((1 + N_\theta) l_c^2)$. Thus, we can graphically visualize the effect of the incision threshold on landscape dissection by comparing the slope of this auxiliary line with the slope of the curvature–steepness-index line.

5 The second graphical method consists of plots of the dimensionless fraction $\theta/\sqrt{A} |\nabla z|$, which gives the fraction by which the incision rate is reduced due to the threshold (see the governing equation Eq. 2). We found that this fraction is equal to $1 - \Phi$ (Eq. 22), where Φ is a threshold factor (see Tucker, 2004) that subsumes the effect of the incision threshold θ on the incision term of the LEM (see Eqs. 2, 22). Thus, we denote the fractional reduction in the incision rate as $1 - \Phi$. In Figs. 5–7, we present plots and maps of $1 - \Phi$ that illustrate how the relative influence of incision thresholds will vary across a given landscape, and how the variation of this relative influence depends on the landscape’s incision-threshold number N_θ .

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The two dimensionless numbers examined here, N_θ and $1 - \Phi$, quantify the relative influence of the incision threshold θ , the first with respect to the parameters K and U , and the second with respect to the steepness index. Thus, N_θ quantifies how θ affects different landscapes with different parameters, and $1 - \Phi$ quantifies how the influence of θ varies across different points of a given landscape. We find that the definition of the Péclet number Pe can be rewritten in two equivalent forms (Eqs. 20, 24), which reveal how Pe depends on N_θ and on Φ , respectively.

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The three dimensionless numbers, Pe , N_θ , and Φ , along with the characteristic scales l_c , h_c , and t_c , and the curvature–steepness-index relationship, provide a thorough characterization of landscapes that follow the governing equation Eq. (2). The specific definitions of these quantities and relationships refer only to the LEMs examined here (Eqs. 1, 2). However, the approach that we follow to derive these definitions may be more generally applicable. Therefore, our approach could potentially be helpful for the analysis of a broader range of models.

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Appendix A: Setup of numerical simulations

We prepared the maps of Fig. 7 with results from numerical simulations that we performed using the CHILD model, originally for the work discussed in Theodoratos and Kirchner (2020). In that work, we present much more information about these simulations and their results. Here, we summarize their setup and parameterization.

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All four landscapes in Fig. 7 have incision coefficient $K = 2 \times 10^{-6} \text{ a}^{-1}$, diffusion coefficient $D = 0.5 \times 10^{-2} \text{ m}^2 \text{ a}^{-1}$, and uplift rate $U = 0.5 \times 10^{-4} \text{ m a}^{-1}$. Each landscape's incision threshold θ depends on the value of its incision-threshold number N_θ according to $\theta = N_\theta \cdot (U/K)$ (see Eq. 9), where $U/K = 25 \text{ m}$ for all landscapes. Therefore, the landscapes have the incision thresholds seen in Table A1.

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We simulated the four landscapes on triangular irregular networks (TINs) with total extent of $7.5 \text{ km} \times 11.25 \text{ km}$ and average TIN edge length of 20 m , which resulted in around a quarter million TIN points. Each map in the left column of Fig. 7, shows a part of the TIN, specifically, a rectangular region with size of $5 \text{ km} \times 4 \text{ km}$, centered around the largest drainage basin of the corresponding landscape.

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Details about the implementation of the governing equation (Eq. 2) in CHILD (Tucker et al., 2001) can be found in Theodoratos et al. (2018) and in Theodoratos and Kirchner (2020).

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Table A1: Incision-threshold numbers N_θ and corresponding incision thresholds θ of the four landscapes illustrated in Fig. 7. The parameter ratio U/K is equal to 25 m for all landscapes.

Incision-threshold number N_θ (-)	Incision threshold $\theta = N_\theta \cdot (U/K)$ (m)
0.2	5
0.4	10
1	25
2	50



Data availability

The data presented here were synthesized using the CHILD model (Tucker et al., 2001). The input files needed to reproduce them are available by the corresponding author upon request.

Author contribution

- 5 NT derived and analyzed the theoretical, numerical, and graphical results, and NT and JWK interpreted them. NT drafted the paper, and NT and JWK edited it.

Competing interests

The authors declare that they have no conflict of interest.

Acknowledgments

- 10 This study was made possible by financial support from ETH Zurich. We thank Eric Deal for helpful discussions.

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Tables

Table 1: Descriptions and dimensions of the terms, variables, and parameters in the governing equations Eq. (1) and Eq. (2). Dimensions are expressed in terms of the model's fundamental dimensions of horizontal length L , vertical length (height) H , and time T .

Symbol	Description	Dimensions
$\partial z / \partial t$	Total rate of elevation change at a point (x, y)	$H T^{-1}$
Rates of elevation change due to:		
$-K\sqrt{A} \nabla z $	stream-power incision (in Eq. 1)	$H T^{-1}$
$-K(\sqrt{A} \nabla z - \theta)$	threshold-limited stream-power incision (in Eq. 2)	$H T^{-1}$
$D\nabla^2 z$	linear diffusion	$H T^{-1}$
U	uplift	$H T^{-1}$
(x, y)	Horizontal coordinates	L
z	Elevation	H
t	Time	T
A	Drainage area	L^2
$ \nabla z $	Topographic slope	$H L^{-1}$
$\nabla^2 z$	Laplacian curvature	$H L^{-2}$
K	Incision coefficient	T^{-1}
D	Diffusion coefficient	$L^2 T^{-1}$
U	Uplift rate	$H T^{-1}$
θ	Incision threshold	H
$\sqrt{A} \nabla z $	Steepness index	H



Table 2: Summary of definitions and formulas used in this study.

Description	Definition	Equation
Characteristic length	$l_c := \sqrt{D/K}$	(3)
Characteristic height	$h_c := U/K$	(4)
Characteristic time	$t_c := 1/K$	(5)
Characteristic area	$A_c := l_c^2 = D/K$	(6)
Characteristic gradient	$G_c := h_c/l_c = U/\sqrt{DK}$	(7)
Characteristic curvature	$\kappa_c := h_c/l_c^2 = U/D$	(8)
Incision-threshold number	$N_\theta := K\theta/U$	(9)
Curvature–steepness-index relationship, without θ	$\nabla^2 z = (K/D)\sqrt{A} \nabla z - (U/D)$	(10)
	$\nabla^2 z = (1/l_c^2)\sqrt{A} \nabla z - \kappa_c$	(11)
Curvature–steepness-index relationship, with θ	$\begin{cases} \nabla^2 z = -\kappa_c, & \sqrt{A} \nabla z \leq \theta \\ \nabla^2 z = (1/l_c^2)\sqrt{A} \nabla z - (1 + N_\theta)\kappa_c, & \sqrt{A} \nabla z > \theta \end{cases}$	(12)
Threshold factor	$\Phi = \begin{cases} 0, & \sqrt{A} \nabla z \leq \theta \\ 1 - \frac{\theta}{\sqrt{A} \nabla z }, & \sqrt{A} \nabla z > \theta \end{cases}$	(22)
Fraction of incision rate reduction	$1 - \Phi = \begin{cases} 1, & \sqrt{A} \nabla z \leq \theta \\ \frac{\theta}{\sqrt{A} \nabla z }, & \sqrt{A} \nabla z > \theta \end{cases}$	(22)
Flow path length	l : the distance along flow paths from a point to the farthest ridge	N/A
Diffusion timescale	$t_D := \frac{l^2}{D}$	(13)
Kinematic wave celerity, without θ	$c = K\sqrt{A}$	N/A
Incision timescale, without θ	$t_I := l/c = l/(K\sqrt{A})$	(14)
Péclet number, without θ	$Pe_{\theta=0} := t_D/t_I = \frac{\sqrt{A}l}{l_c^2} = \frac{\sqrt{A}}{\sqrt{A_c}} \frac{l}{l_c}$	(15)
Kinematic wave celerity, with θ	$c = \begin{cases} 0, & \sqrt{A} \nabla z \leq \theta \\ K\sqrt{A} - K\theta/ \nabla z , & \sqrt{A} \nabla z > \theta \end{cases}$	(17)
Incision timescale, with θ	$t_I := l/c = \begin{cases} +\infty, & \sqrt{A} \nabla z \leq \theta \\ l/(K\sqrt{A} - K\theta/ \nabla z), & \sqrt{A} \nabla z > \theta \end{cases}$	(18)
Péclet number, with θ	$Pe := \begin{cases} 0, & \sqrt{A} \nabla z \leq \theta \\ \frac{\sqrt{A}}{\sqrt{A_c}} \frac{l}{l_c} - N_\theta \frac{l}{l_c} \frac{G_c}{ \nabla z }, & \sqrt{A} \nabla z > \theta \end{cases}$	(20)
	$Pe = \begin{cases} 0, & \sqrt{A} \nabla z \leq \theta \\ \left(1 - \frac{\theta}{\sqrt{A} \nabla z }\right) \frac{\sqrt{A}l}{l_c^2}, & \sqrt{A} \nabla z > \theta \end{cases}$	(23)



Figures

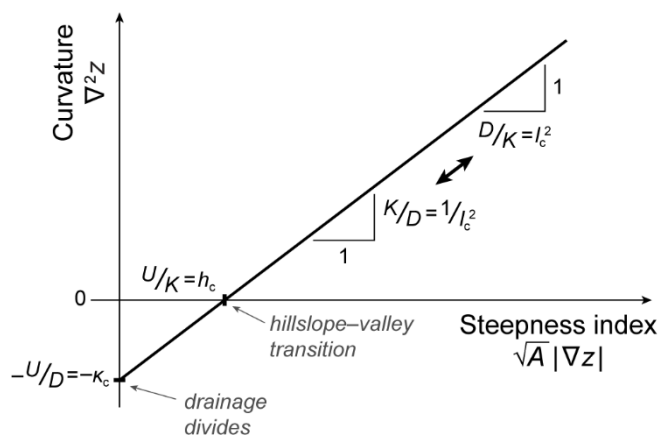


Figure 1: **Relationship between curvature and the steepness index in steady-state topography without incision threshold.** We plot a straight line defined by Eqs. (10) or (11), which describes how curvature should be related to the steepness index if the landscape follows the LEM (Eq. 1) and is in steady state. This line is parameterized by the characteristic scales of length and height l_c and h_c (Eqs. 3, 4); its slope is $1/l_c^2$, its horizontal-axis intercept is $\sqrt{A} |\nabla z| = h_c$, and its vertical-axis intercept is $\nabla^2 z = -\kappa_c$ (where κ_c is a characteristic curvature defined as l_c^2/h_c ; Eq. 8). These intercepts reveal topographic properties of special points in a landscape, namely, the steady-state curvature of drainage divides and the steady-state steepness index of hillslope–valley transitions. The characteristic length l_c quantifies the competition between knickpoint advection and diffusion and predicts how landscape dissection scales with the parameters. Thus, the slope of the curvature–steepness-index line expresses visually how dissected a landscape is. Note that the line's slope can be represented either as $K/D = 1/l_c^2$ units of curvature per 1 unit of steepness index, or 1 unit of curvature per $D/K = l_c^2$ units of steepness index. For simplicity, we use the latter notation to express the slopes of the lines in Figs. 2–4.

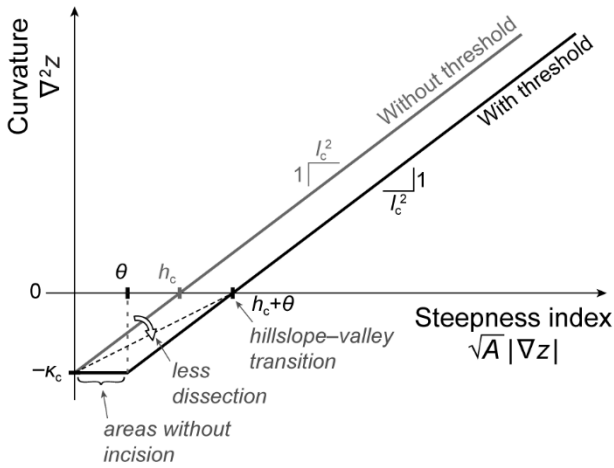


Figure 2: **Effects of incision threshold on steady-state topography as reflected in the curvature–steepness-index line.** We show curvature–steepness-index lines of landscapes with and without incision threshold using black and gray colors, respectively (see Eqs. 11, 12). The gray line in this figure is identical to the line in Fig. 1. Adding an incision threshold to the LEM changes the resulting steady-state topography, as indicated by the differences between the gray and black lines. The black line consists of two segments. The horizontal segment corresponds to points where incision is fully suppressed by the threshold. This horizontal segment is at $\nabla^2 z = -\kappa_c$, the vertical-axis intercept of the gray line. This shows that the hilltop curvature (the most negative curvature value in the landscape) spreads to points on hillslopes beyond drainage divides. Thus, hillslopes become more convex due to the threshold. The inclined segment of the black line is parallel to the gray line, and at a horizontal distance θ to its right. Thus, the horizontal-axis intercept is increased from h_c to $h_c + \theta$ due to the threshold, i.e., the hillslope–valley transition occurs at a larger steepness index value. This increase corresponds to larger drainage area A and/or steeper slope $|\nabla z|$, both of which are consistent with the steepening of landscapes and the decrease of their drainage density by the incision threshold. In the case of the LEM that includes an incision threshold, the degree of landscape dissection is expressed by the length scale $\sqrt{1 + N_\theta} l_c$ (see Eq. 21), where N_θ is a dimensionless incision-threshold number (Eq. 9). The square of this length scale is $(1 + N_\theta) l_c^2$, which is equal to the ratio of the two intercepts of the black line. The quantity $(1 + N_\theta) l_c^2$ is the reciprocal of the slope of the black dashed line that connects the two intercepts. Thus, by comparing the slope of this auxiliary line and of the curvature–steepness-index line, we can graphically express the effect of the incision threshold on landscape dissection, as shown by the white arrow.

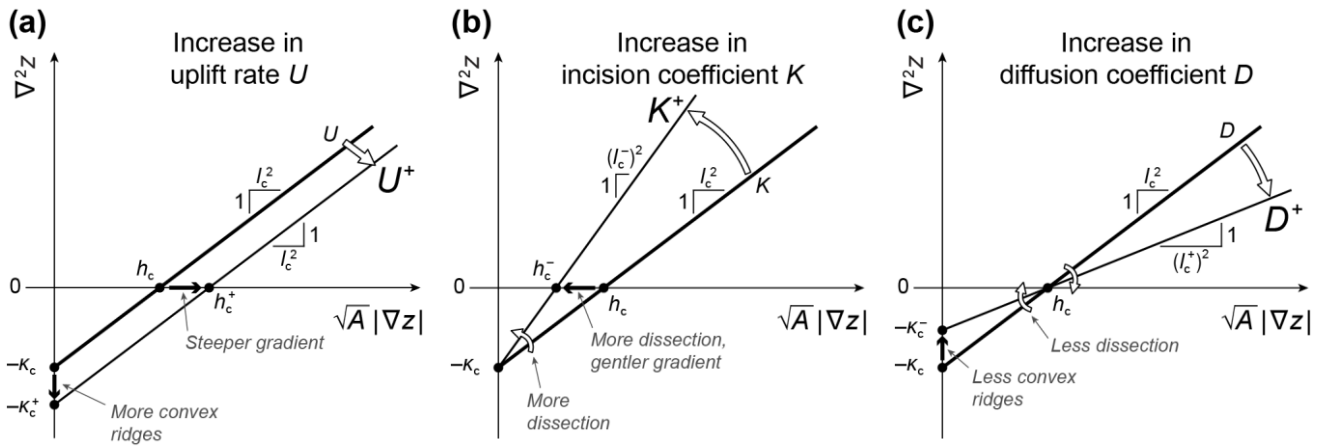


Figure 3: **Graphical illustration, using curvature–steepness-index lines, of how parameters influence landscape properties.** The three plots show how curvature–steepness index lines respond to increases in the uplift rate U , incision coefficient K , and diffusion coefficient D . (a) An increase in U parallel-shifts the line to the right and downward. This makes the vertical-axis intercept smaller (more negative) and the horizontal-axis intercept bigger, showing that ridges become more convex and that gradients become steeper (i.e., relief becomes higher). The line’s slope remains $1/l_c^2$, indicating that the scale of dissection does not change. (b) An increase of K rotates the line counterclockwise around the vertical-axis intercept. This makes the horizontal-axis intercept smaller and the line’s slope bigger, showing that gradients become gentler (i.e., relief becomes lower) and that the landscape becomes more dissected (i.e., the scales of dissection become smaller). (c) An increase of D rotates the line clockwise around the horizontal-axis intercept. This moves the vertical-axis intercept closer to zero and decreases the line’s slope, showing that ridges become less convex and that the landscape becomes less dissected (i.e., the scales of dissection become larger).

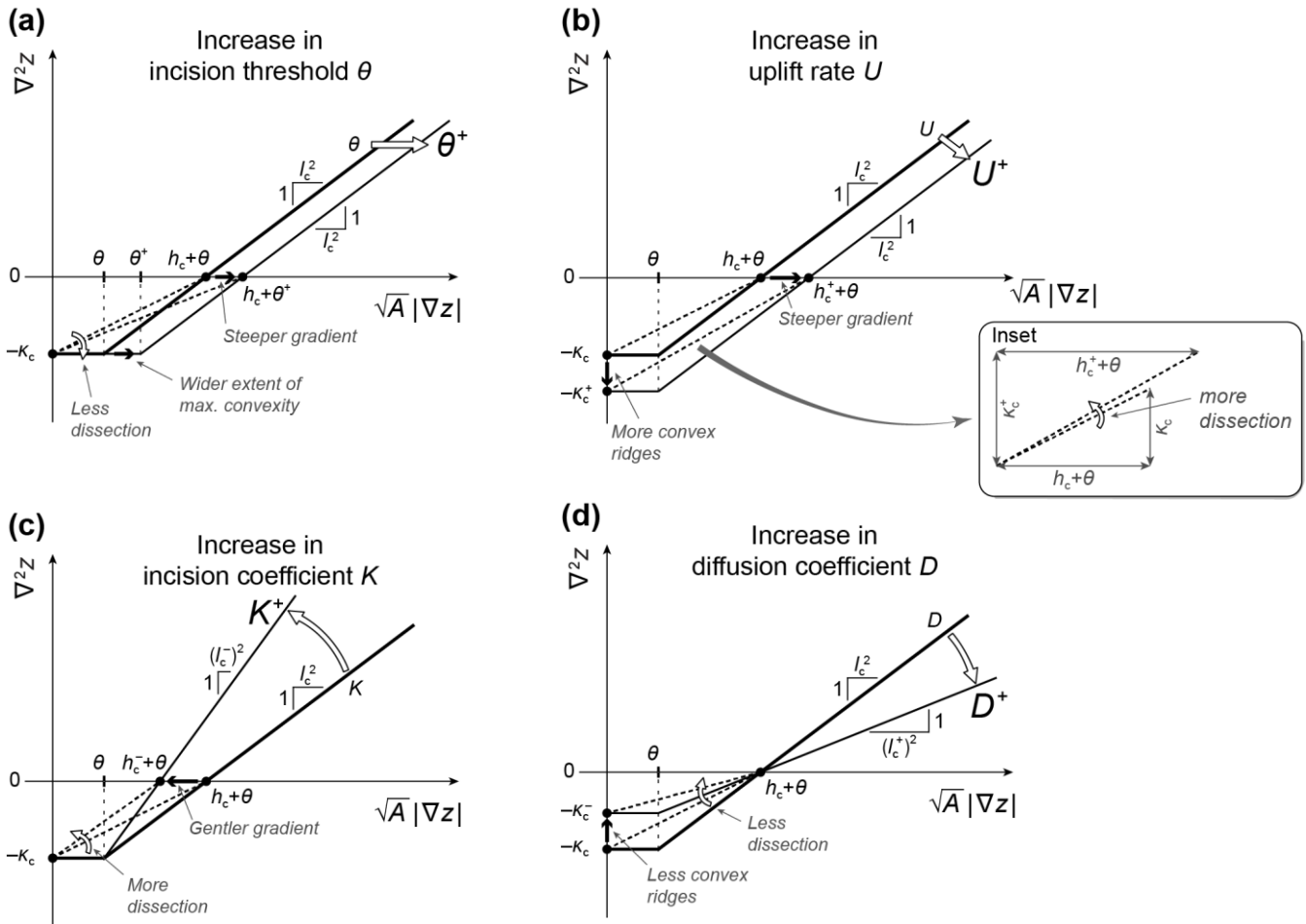


Figure 4: **Graphical illustration, using curvature–steepness-index lines, of how incision threshold and parameters control landscape properties.** The four plots show how curvature–steepness index lines respond to increases in the incision threshold θ , uplift rate U , incision coefficient K , and diffusion coefficient D . (a) An increase in the incision threshold θ parallel-shifts the line to the right. Note the difference with the shift in (b), which is to the right and downward. The shift in (a) makes the horizontal segment of the line longer and the horizontal-axis intercept bigger, showing that the zones of maximum convexity become wider, gradients become steeper and drainage areas of valley heads become smaller. The curvature value of the horizontal segments and the line’s slope remain unchanged. The increase in the horizontal-axis intercept changes its ratio to the vertical-axis intercept, which expresses the degree of landscape dissection as explained in Sect. 3.3. This ratio can be visualized by the dashed auxiliary lines that connect the horizontal- and vertical-axis intercepts and the change in the value of the ratio can be visualized by the rotation of these lines. (b) An increase in the uplift rate U shifts the line to the right and downward. This makes the vertical-axis intercept smaller (more negative) and the horizontal-axis intercept bigger, showing that ridges become more convex and that gradients become steeper (i.e., relief becomes higher). The changes of these two intercepts are not proportional and, thus, their ratio changes. This change can be visualized in the inset, where we plot the auxiliary lines such that they share the same starting point. This shows that the degree of landscape dissection changes when U is increased, whereas it did not change in the case of the LEM without incision threshold (see Fig. 3). (c) An increase in the incision coefficient K rotates the inclined segment of the line counterclockwise around its intersection with the horizontal segment. The horizontal segment remains unchanged. Thus, the horizontal-axis intercept becomes smaller, which shows that gradients become gentler and the landscape becomes more dissected. (d) An increase in the diffusion coefficient D rotates the inclined segment line clockwise around the horizontal-axis intercept. This moves the horizontal segment and the vertical-axis intercept closer to zero, and changes the ratio of the two intercepts, showing that ridges become less convex and that the landscape becomes less dissected.

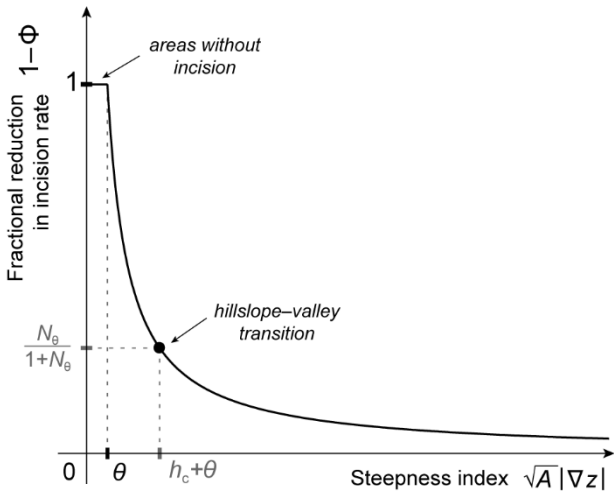


Figure 5: **How the relative influence of the incision threshold changes across a landscape.** We plot the quantity $1 - \Phi$ versus the steepness index $\sqrt{A}|\nabla z|$, where Φ is a threshold factor that can subsume the incision threshold θ (definitions in Eq. 22 and Sect. 4). The quantity $1 - \Phi$ is dimensionless and expresses the fractional reduction in incision rate due to the incision threshold θ . The $1 - \Phi$ curve presented here shows how this fraction varies across the landscape. The value $1 - \Phi = 1$ corresponds to points where incision is fully suppressed by the threshold, i.e., where the incision rate is reduced by 100%. Thus, the horizontal segment of the $1 - \Phi$ curve corresponds to the horizontal segment of the curvature–steepness-index line in Fig. 2. At points with $\sqrt{A}|\nabla z|$ much larger than θ (the far right of the plot), the incision rate is reduced by a very small fraction, and the $1 - \Phi$ curve asymptotically approaches 0. The black dot on the $1 - \Phi$ curve corresponds to the steepness index value $h_c + \theta$, which corresponds to hillslope–valley transitions, as shown in Fig. 2. The position of the black dot on the curve helps us visualize how large the incision rate reduction fraction is across different regimes of a landscape. This position depends on the characteristic height h_c , on θ , and on the dimensionless ratio θ/h_c . We define this ratio as the incision-threshold number N_θ (Eq. 9).

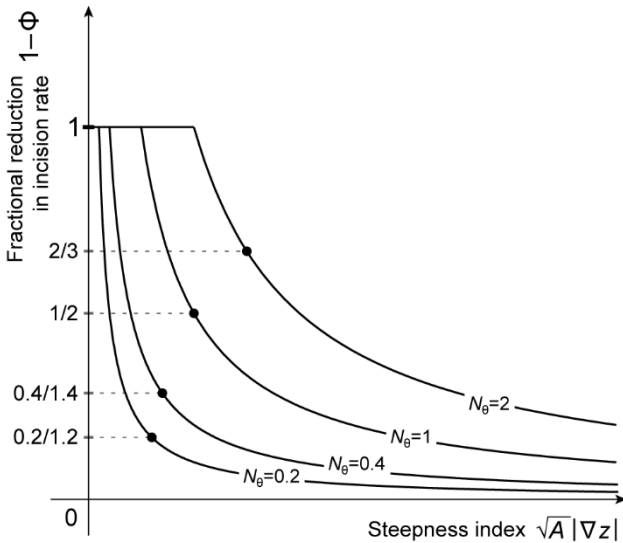


Figure 6: **Comparison of the relative influence of incision thresholds with different magnitudes.** We present curves of the quantity $1 - \Phi$ versus the steepness index $\sqrt{A}|\nabla z|$ for four different values of N_θ . The black dots show the values of $\sqrt{A}|\nabla z|$ and $1 - \Phi$ that correspond to hillslope–valley transitions. The curve with $N_\theta = 0.2$, the smallest of the four values of N_θ , starts with a short horizontal segment, and then descends steeply and approaches 0 rapidly. Furthermore, its black dot corresponds to the value $1 - \Phi = 0.2/1.2 = 1/6$. By contrast, the curve with the largest value, $N_\theta = 2$, starts with a long horizontal segment, descends gradually, approaches 0 slowly, and has a black dot with $1 - \Phi = 1/3 = 0.333$. These differences show that as N_θ increases, a) incision is fully suppressed by the threshold in bigger portions of hillslopes, b) the steepness index must reach greater values for the influence of the threshold to start becoming negligible; and c) the hillslope–valley transition occurs at larger values of $1 - \Phi$, i.e., the threshold has a strong influence not

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 10 only on hillslopes, but also on the valley network.

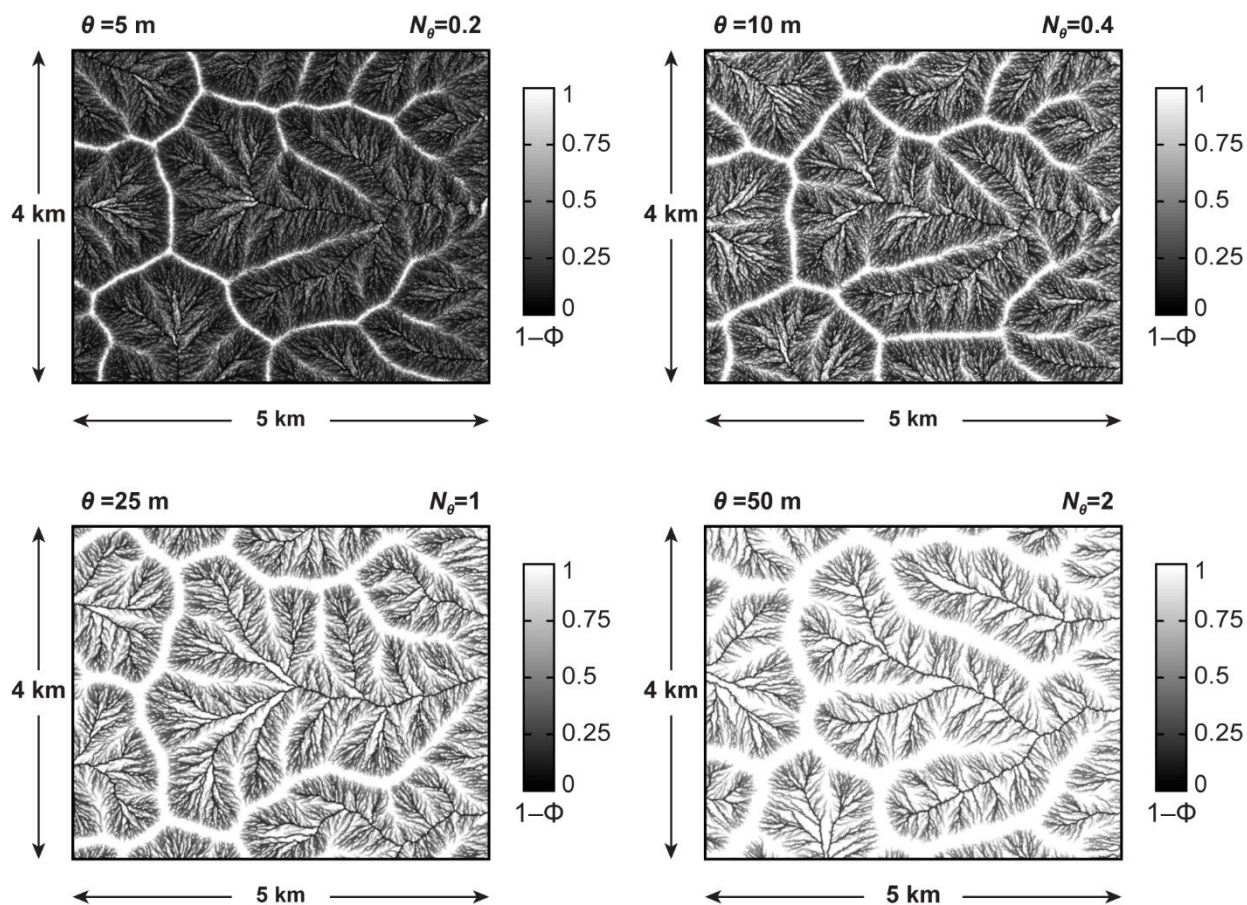


Figure 7: **Control of the incision-threshold number N_θ on the spatial distribution of the fractional reduction in incision rate.** We map the quantity $1 - \Phi$ across four steady-state simulated landscapes with different values of N_θ . We use the same values of N_θ as in Fig. 6. Details about the setup and parameters of these simulations are presented in Appendix A. Lighter colors correspond to larger values of $1 - \Phi$, i.e., to stronger influence of the incision threshold. The spatial distribution of $1 - \Phi$ follows the dendritic pattern of the valley network. As N_θ increases, the maps become lighter, i.e., areas with strong influence of the incision threshold become more widespread, both on hillslopes and in valleys.