

# Short communication: Potential of Sentinel 1 InSAR and offset tracking in monitoring post-cyclonic landslides activities in Reunion Island.

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## Abstract

This study examines the results of an interferometric Synthetic Aperture Radar (InSAR) and SAR Offset Tracking (OT) study on Cirque de Salazie (CdS), Reunion Island, France, within the context of the RENOVRISK project, a multidisciplinary programme to study the cyclonic risks in the South-West Indian Ocean. Despite numerous landslides on this territory, CdS is one of the denser populated areas in Reunion Island. One of the aims of the project is to assess whether Sentinel 1 SAR methods can be used to measure landslide motion and/or accelerations due to post cyclonic activity on CdS. We concentrate on the post 2017 cyclonic activity. We use the Copernicus Sentinel 1 data, acquired between 30/10/2017 and 06/11 2018. Sentinel 1 is a C-band SAR, and its signal can be severely affected by the presence of changing vegetation between two SAR acquisitions, particularly in CdS, where the vegetation canopy is well developed. This is why C-band radars such as the ones onboard Radarsat or Envisat, characterized by low acquisition frequency (24 and 36 days, respectively), could not be routinely used on CdS to measure landslide motion with InSAR in the past. In this study, we use InSAR and OT techniques applied to Sentinel 1 SAR. We find that C-band SAR onboard Sentinel 1 can be used to monitor landslide motion in densely vegetated areas, thanks to its high acquisition frequency (12 days). OT stacking reveals a useful complement to InSAR, especially in mapping fast moving areas. In particular, we can highlight ground motion in the Hell-Bourg, Ile à Vidot, Grand Ilet, Camp Pierrot, and Belier landslides.

## 1. Introduction and study area

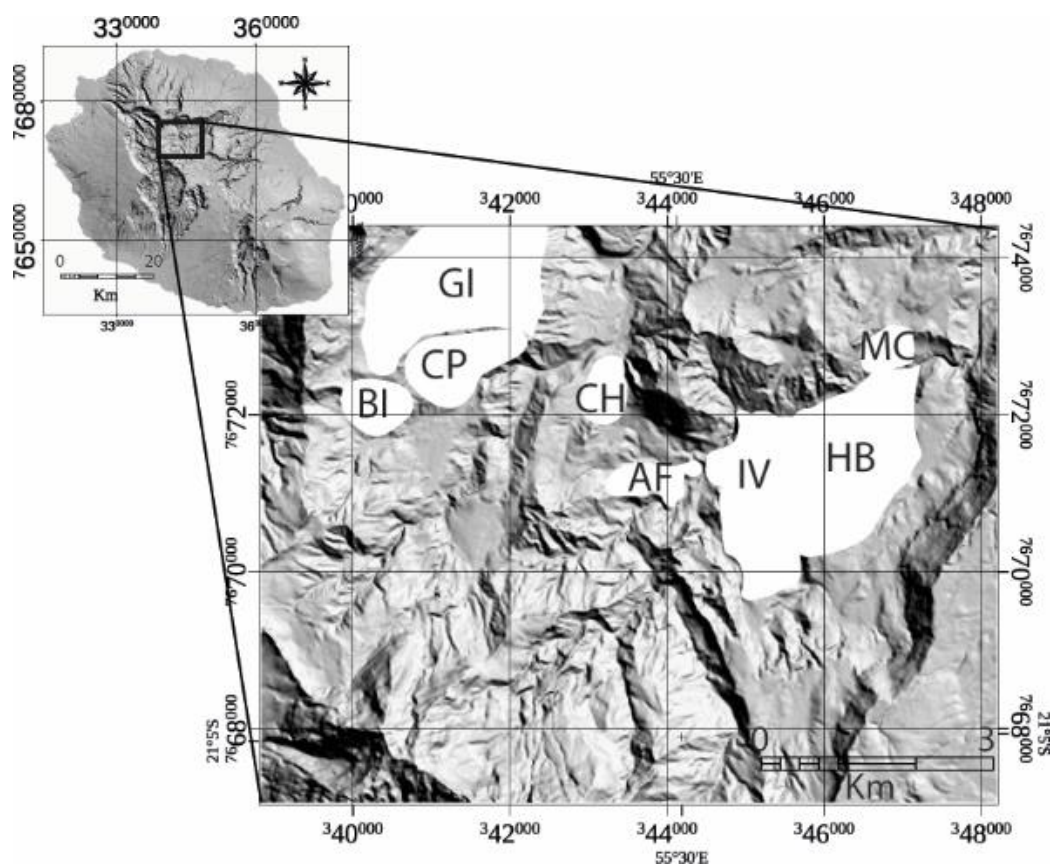
Landslide and erosion processes are causes of major concern to population and infrastructures on Reunion Island. These processes are led by the tropical climate of the island. The hydrological regime of the rivers is distinct owing to the coexistence of several major parameters that predispose it to extreme vulnerability. Holding almost all the world records for rainfall between 12 h (1170 mm) and 15 days (6083 mm), the island has a marked relief with a peak at 3,069 m, with exceptional cliffs that reach 1500 m in height.

35 CdS is the rainiest of the large erosional depressions on Reunion Island (Pohl et al., 2016) with an average annual  
36 cumulative rainfall of approximately 3,100 mm since 1963; a minimum of 698 mm was recorded in 1990, and a  
37 maximum of 5,893 mm was recorded in 1980.

38 This depression is surrounded by steep rock cliffs and filled with epiclastic material. Intense river erosion incises  
39 deep valleys and has produced several isolated plateaus across the cirque.

40 The morphology, geology, and climate make CdS prone to erosion and ground movements. At least 19% of its  
41 slope is affected by landslides (Rault et al., 2022). The active landslides range from a large slow-moving landslide  
42 of hundred million cubic meters to rapid and catastrophic slope failure with a volume exceeding one million cubic  
43 meters.

44 Eleven slow moving landslides are identified in CdS (Figure 1). Their displacement rates range from a few cm/yr  
45 to 1.15 m/yr and can accelerate after intense rainfall events, particularly because of cyclonic activity (e.g Belle et  
46 al., 2014). These landslides are commonly observed on plateaus. They cover areas that vary from tens of thousands  
47 of square m to several square km. Hell-Bourg (HB) and Grand-Ilet (GI) are the largest inhabited slow-moving  
48 landslides in the cirque with volumes of  $225 \times 10^6 \text{ m}^3$  and  $215 \times 10^6 \text{ m}^3$ , respectively (e.g. Rault et al, 2022).



49  
50 **Figure 1. Map of the study area. Slow moving landslides in the area, from existing catalogues, are highlighted in white.**  
51 **MC : Mare à citron, HB: Hell-Bourg, IV: Ilet à Vidot, AF: Affouche, CH: Chemin Henry, BI: Belier, CP: Camp**  
52 **Pierrot, and GI: Grand-Ilet. Modified form Rault et al. (2022).**

53

54 Slow-moving landslides can trigger secondary landslides along their steep scarps that eventually border rivers,  
55 leading to increased solid loads. Therefore, slow-moving landslides are not only responsible for significant damage  
56 to houses and infrastructure but are also involved in the formation of torrential flows and river dams (Liébault et  
57 al. 2010, Tulet et al., 2021). Thus, understanding their kinematics/dynamics is essential for hazard and risk  
58 mitigation at the scale of Reunion Island.

59 SAR methods has already demonstrated useful in highlighting landslides kinematics from space (e.g. Aslan et al.,  
60 2020 –and references therein). While C band SAR can be used to comprehensively measure ground displacement,  
61 our study area is particularly challenging for C band SAR since it is densely vegetated. In this study, we test  
62 whether InSAR and OT techniques can be used to measure landslide kinematics in densely vegetated areas. Both  
63 techniques require temporal signal coherence and therefore are usually not adapted for densely vegetated areas.  
64 Particularly, C-band SAR signal can be severely affected by the presence of changing vegetation between two  
65 SAR acquisitions, particularly in CdS, where the vegetation canopy is well developed. This is why C-band radars  
66 such as the ones onboard Radarsat or Envisat, characterized by low acquisition frequency (24 and 36 days,  
67 respectively), could not be routinely used on CdS to measure landslide motion with InSAR in the past. This  
68 limitation can be palliated under certain circumstances, for instance improving repetition frequency between two  
69 or more satellite acquisitions. In this study, we exploit the improved repetition frequency of Sentinel-1 SAR to test  
70 InSAR and OT techniques in CdS after a cyclonic event in 2018. If successful, this study can serve as a  
71 demonstrator.

72

### 73 **1.1 Past studies regarding ground motion from space in CdS**

74 Few studies have used spaceborne remote sensing techniques to report on ground instabilities in CdS. Delacourt  
75 *et al.* (2009) used a combination of optical (Spot 5 and aerial imagery) and synthetic aperture radar (SAR) data  
76 (JERS-1 and Radarsat data) to measure ground motion on the Hell Bourg landslide. They applied the two  
77 techniques to assess their performance and quantify ground motion associated with this landslide. They found an  
78 average displacement of approximately 0.5 m/yr from 1997–2002. Le Bivic *et al.* (2017) used two pairs of ortho-  
79 rectified SPOT-5 images at 2.5 m resolution on the Hell Bourg landslide. The first pair of images spanned the  
80 period between 2002 and 2005. The second pair of images spanned the period 2006–2008. They reported that  
81 during 2002–2005, the OT method yielded ground motion within the signal noise; they deduced that landslide  
82 activity was low. From 2006–2008, they measured a maximum displacement of  $8.5 \pm 2$  m (possibly due to the  
83 storm Gamede).

84 Raucoules *et al.* (2016) used high resolution X-band SAR data from the TerraSAR-X satellite from 2010–2011.  
85 They combined ascending and descending OT maps to extract the three dimensional displacement field of the HB  
86 and GI landslides. They reported that ground displacement reached  $1 \pm 0.25$  m/y vertically and  $0.65 \pm 0.25$  m/y  
87 horizontally. They also used InSAR combined with X-band data from the Cosmo-SKYMED satellite to measure  
88 centimetric displacements on the borders of the HB and GI landslides. The X-band InSAR signal was incoherent  
89 elsewhere.

90 Raucoules *et al.* (2018a,b; 2020) used space-borne high-resolution L-band SAR (ALOS-2/PALSAR2 data in  
91 StripMap SM1 mode) both with interferometric synthetic aperture radar (InSAR) and OT. They derived two  
92 components of the displacement field for the HB landslide. The displacement reached approximately 1 m/y from

93 2014–2016. They reported that L-band SAR performed significantly better than the C-band SAR available at the  
94 time of the study.

95

## 96 **1.2 Aim of this study**

97 Landslides displacement rates in CdS can accelerate after intense rainfall events, particularly during cyclonic  
98 activity. Their kinematic might change during such extreme events; new landslides might appear. Global  
99 Navigation Satellite System (GNSS) in the study area yields precise time series at the measurement stations. SAR  
100 methods are potentially able to spatialize the ground motion information and might reveal ground motion in  
101 unexpected areas. The aim of this study is to assess whether Sentinel 1 SAR methods – both InSAR and OT- could  
102 be used to measure landslide motion and accelerations caused by post cyclonic activity in a densely vegetated area  
103 such as CdS. This study complements the one by Raucoules *et al.* (2018a,b ; 2020), who used L-band InSAR and  
104 OT to measure ground motion in CdS. The measurement of ground motion with C band SAR in densely vegetated  
105 areas is challenging because the radar waves interact with the vegetation canopy and may yield an incoherent  
106 InSAR signal if temporal changes occur between the two SAR scenes. Therefore, InSAR signal coherence largely  
107 depends on the revisit time of the satellite. The shorter the revisit time is, the higher the InSAR signal coherence,  
108 and the faster the ground motion has to be in order to be measured by InSAR. The history of C-band SAR data  
109 over la Réunion island is non-linear. The European Space Agency (ESA) Earth Remote Sensing Satellite (ERS-  
110 1 and ERS-2) SAR platforms did not cover La Réunion Island owing to orbit incompatibilities. The Canadian Space  
111 Agency Radarsat 1-2 has flown over la Réunion, but they acquired data every 24 days (Delacourt *et al.*, 2009),  
112 which makes the InSAR signal incoherent in densely vegetated areas such as the CdS. Similarly, the ESA Advance  
113 SAR (ASAR) sensor onboard the ENVISAT satellite acquired data every 35 days. Therefore, the SAR  
114 interferometric signal was incoherent for this C-band radar with a quasi-monthly repeat cycle. The Copernicus  
115 Sentinel 1 satellite can resolve these problems. Sentinel 1 hosts a C-band SAR (wavelength = 5.5 cm) whose  
116 interferometric signal is usually incoherent over densely vegetated areas; however, the high repetition frequency  
117 of Sentinel 1 (12 days in La Réunion, 6 days in mainland Europe until 2021) makes the InSAR signal potentially  
118 suitable for measuring land displacements in densely vegetated areas (e.g. Aslan *et al.*, 2020). It could be  
119 complementary or alternative to L-band SAR interferometry (Delacourt *et al.*, 2009; Raucoules *et al.* 2020) and  
120 *in-situ* techniques in La Réunion.

121

## 122 **1.3 InSAR and Offset Tracking techniques**

123 In this study, we design the experiment as follows. We apply two SAR methods, InSAR and OT. These two  
124 methods could be complementary because InSAR can measure slow moving landslides, typically a small fraction  
125 of the employed wavelength, while OT can measure large ground motions, higher than the pixel size of the SAR  
126 scene. In contrast, OT may be limited in the measurement of small ground motions, depending on the pixel size,  
127 because the nominal lower bound precision is  $1/10^{\text{th}}$  of the pixel size of the image employed on a single  
128 correlogram.

129 InSAR methods rely on the measurement of the changes in SAR phases among multiple SAR scenes using  
130 interferometric processing (e.g. Massonnet and Feigl, 1998). It is a widely used methodology to measure ground

131 displacements from space, in many disciplines related to tectonics (e.g. Elliot et al., 2020), volcanology (e.g.  
132 Doubre et al., 2017) and gravitational failures (e.g. Aslan et al., 2020). Here, we used the stacking procedure  
133 implemented in the Gamma processing chain (GAMMA, 2015). The stacking procedure combines multiple SAR  
134 scenes and yields ground displacement rate in the form of ground velocity map. It is used to estimate the linear  
135 rate of differential phases starting from a set of unwrapped differential interferograms. The individual  
136 interferogram phases are weighted by the time interval in estimating the phase rate. The underlying assumption is  
137 that atmospheric statistics are stationary for the set of interferograms. Stacking can be applied to unwrapped  
138 interferometric phases as well as to a set of OT correlograms.

139 OT is a sub-pixel image correlation technique. This technique matches two or more images at each point on a grid,  
140 analyzing the degrees of local correlation at each step. Differences in the local instantaneous frequency of the  
141 images result in sub-pixel spatial differences in ground patterns. Measurements must be performed with subpixel  
142 accuracy because the amplitude of the ground displacement is often lower than the resolution of the images,  
143 depending on the sensor used.

144 Sub-pixel image correlation technique for measuring ground surface displacements can be applied to optical (e.g.  
145 Michel et al., 1999; de Michele and Briole, 2007) and SAR amplitude images (e.g. Michel and Rignot, 1999; de  
146 Michele et al., 2010a, 2010b). The main differences between optical and SAR images are caused by the oblique  
147 SAR acquisition geometry. Therefore, instead of having east-west and north-south offsets as in optical OT, SAR  
148 OT yields slant range and azimuth offsets. Slant range is the line of sight (LOS) direction, or look angle of the  
149 satellite. The azimuth is the flying direction of the satellite (nominally  $98^\circ$  for Sentinel 1; nearly North-South).  
150 Moreover, azimuth offsets are «topography free», and slant range offsets are calculated in the LOS and, therefore,  
151 contain a contribution from vertical offsets, depending on the viewing angle. Thus, OT yields two components of  
152 the deformation field for one SAR scene. For details on this methodology, please refer to Michel & Rignot (1999)  
153 and Michel et al., (1999), who used it with shuttle imaging radar (SIR-C) and ERS radar amplitude images, and  
154 Raucoules et al. (2013), who applied the OT method to multi temporal SAR images at La Vallette landslide. The  
155 OT technique provides a measurement of the ground displacement from the analysis of the geometrical  
156 deformation between the two SAR amplitude images. Usually SAR images with a small baseline are chosen to  
157 reduce the stereoscopic effect and geometric decorrelation. For Sentinel 1, the orbit tubes are steered within 100  
158 m maximum. Therefore, the topographic contribution to the OT in the LOS direction is negligible. In this study,  
159 we estimate the range and azimuth offset fields using cross correlation optimization of the input intensity images.  
160 This algorithm is implemented in the GAMMA software with the name of “offsets tracking” (e.g. Strozzi et al.,  
161 2002). GAMMA is a standard SAR processing software, which results have been validated among other available  
162 SAR processing chains (e.g. Raucoules et al., 2009).

163

## 164 **2. Data and processing steps**

165 At the time of this study experimental design, the Sentinel-1 mission comprised a constellation of two polar-  
166 orbiting satellites, operating day and night, hosting a C-band synthetic aperture radar, enabling them to acquire  
167 imagery regardless of the weather. We used 26 Sentinel 1 data in descending, stripmap mode, acquired every 12  
168 days from October 30, 2017, to November 06, 2018. Sentinel 1 data are provided by the European Space Agency,

169 within the Copernicus Program of the European Union. Technically, we downloaded them as Single Look  
170 Complex (SLC) data from the Copernicus Scientific Data Hub (<https://scihub.copernicus.eu>). We did not use the  
171 ascending mode, as it is less sensitive to ground motion in CdS given the SAR shadow and the unfavorable relative  
172 geometry between the SAR orbit and ground motion (e.g. Raucoules et al., 2020).

173 First, we co-registered the SAR data. Then, we created differential interferograms with data pairs spanning 12 days  
174 intervals. The topographic contribution to the interferometric phase was modelled using a DEM from the Shuttle  
175 Radar Topography Mission (SRTM). We unwrapped the differential interferograms with the minimum cost flow  
176 algorithm (Constantini, 1998). Depending on the water vapor content in the air, there may be an interferometric  
177 phase delay due to the SAR signal crossing multiple tropospheric layers. To a first approximation, this delay is  
178 proportional to the topographic slope. Therefore, we corrected the tropospheric contribution to the interferometric  
179 phase by linear regression with the DEM. At this point, we performed the stacking procedure, producing a velocity  
180 map. The stacking procedure starts from a set of unwrapped interferometric phases along with the time interval in  
181 days of the SLC-2 relative to the reference SLC-1. The individual unwrapped interferograms are weighted by the  
182 time interval in estimating the rate. The underlying assumption is that atmospheric statistics are stationary for the  
183 set of  $N$  interferograms. The formula for the estimated phase rate, in radians per year, is given by (Le Mouelic et  
184 al., 2005; GAMMA, 2015):

$$185 \quad \text{phase rate} = \frac{\sum_{j=1}^N \Delta t_j \varphi_j}{\sum_{j=1}^N \Delta t_j^2} \quad (1)$$

186 Where  $N$  is the number of interferograms,  $\varphi_j$  is one given interferogram,  $t$  is the time interval inherent with each  
187 interferogram (SLC-2 relative to the reference SLC-1). If the matching is not found (low signal coherence), that  
188 particular interferogram value is not used in the stacking procedure. So that the same scatterers are identified on  
189 many images, but not all the images are used. It follows that the more the images, the more the stacking  
190 redundancy, the more the precision of the results. The phase rates are converted into velocity values, in meters per  
191 year. Afterwards, we orthorectified the velocity map. The results are shown in Figure 2.

192 For the OT procedure, we began from the co-registered SAR data. Instead of the phases, we used the amplitude of  
193 the SAR signal and extracted multi look complex images (MLI) for each acquisition date. Multi look processing  
194 degrades the image resolution but reduces the image speckle. Because OT sensitivity to ground motion depends  
195 on the pixel resolution, we required a tradeoff between image noise and multi looking. For this study, our choice  
196 was multi looking with a factor of 3 in azimuth and 2 in range directions. This led to pixel sizes of 8.2 m in the  
197 azimuth direction and 7.9 m in the range directions. We used a correlation window of 128X128 pixels and searched  
198 for 1024 measures in range and azimuth respectively. The OT technique is nominally less affected by temporal  
199 signal decorrelation than the InSAR technique. Therefore, we used all possible image couples, leading to the  
200 creation of 351 correlograms in both range and azimuth directions. Then, we applied the stacking procedure  
201 described above, to create one velocity map in the range direction and one in the azimuth direction. Instead of the  
202 unwrapped InSAR phases in equation (1), we used the pixel offset values found in the OT correlograms (in meters).  
203 As for the InSAR phases, if the matching is not found, that particular correlogram value is not used in the stacking  
204 procedure. So that the same ground patterns are identified on many images, but not all the images are used. Finally,  
205 we orthorectified the results. The orthorectification implies spatial resampling via interpolation –in order to keep  
206 the regular sampling on the final map.

207

208

### 209 **3. Results**

210 We recognized and mapped three landslide areas in Salazie, active during the study period. Hell Bourg, Ilet à Vidot  
211 and an area that was considered stabilized or dormant, possibly corresponding to Crete de Salaze.

212 Hell Bourg and Ilet a Vidot are two major inhabited compound landslides of Salazie. These landslides move  
213 continuously and typically accelerate following heavy rainfall. They occupy approximately 10% of the CdS surface  
214 area. They all stand on volcanoclastic material interpreted as volcanic debris-avalanche deposits or as debris-  
215 flow/mud-flow deposits by Rault et al. (2022). Hell Bourg is a compound landslide covering a surface of  
216 approximately 2.8 km<sup>2</sup>. Ilet a Vidot is an active plateau located northwest of Hell Bourg and covers an area of 2.3  
217 km<sup>2</sup>.

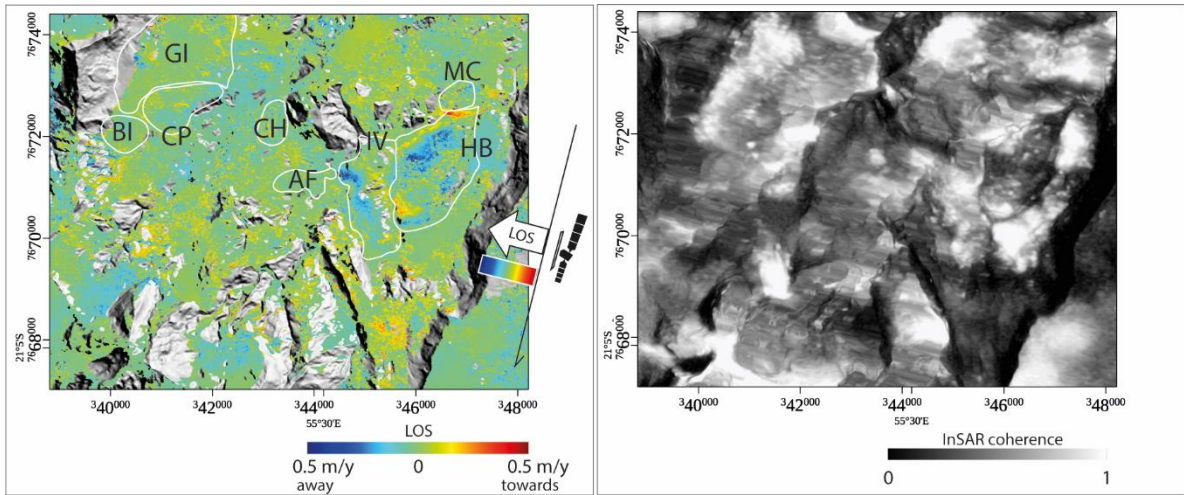
218 In the next paragraph we describe both InSAR and OT results in more details.

219

#### 220 **3.1 InSAR**

221 The stacking InSAR results are shown in Figure 2. They are presented as a mean velocity map, where ground  
222 motion is measured in the LOS of the satellite. InSAR is only sensitive to ground motion occurring in the LOS  
223 direction. Motion away from the satellite is represented in blue. Motion towards the satellite is represented in red.  
224 Complex combinations of those two directions of motion may lead to zero apparent motion on the InSAR velocity  
225 map. From Figure 2, we observe manifold improvements with respect to velocity maps produced from former C-  
226 band InSAR missions (Delacourt *et al.*, 2009). First, we noticed that the InSAR signal is coherent over the study  
227 area, which was not expected given the densely vegetated tropical area (Figure 2, right). Second, we can see a  
228 clear pattern of ground motion in the Hell-Bourg area, approximately in the interval of values  $\pm 0.5$  m/yr and  
229 spatially consistent with ground observations. Figure 2 also shows ground motion on the Ilet à Vidot (IV) landslide.  
230 The InSAR signal direction on both HB and IV landslides is quite complex. This suggests the existence of complex  
231 internal landslides kinematics such as stretching of the main landslide body in HB and dismantling of IV plateau  
232 on both sides by landslides moving either eastward or westward, as expected for a compound slide and identified  
233 in the field by Rault et al. (2022). It also suggests a rotational component of ground motion. In this study, the  
234 InSAR signal is surprisingly coherent with a certain level of noise. We calculated the noise as  $\pm 2$  cm/yr on the  
235 InSAR velocity map. To minimize coherence loss, we used interferograms with 12 days times span only, excluding  
236 larger time-span interferograms. Owing to these limitations, we were unable to capture very slow ground motions  
237 ( $< 2$  cm/yr).

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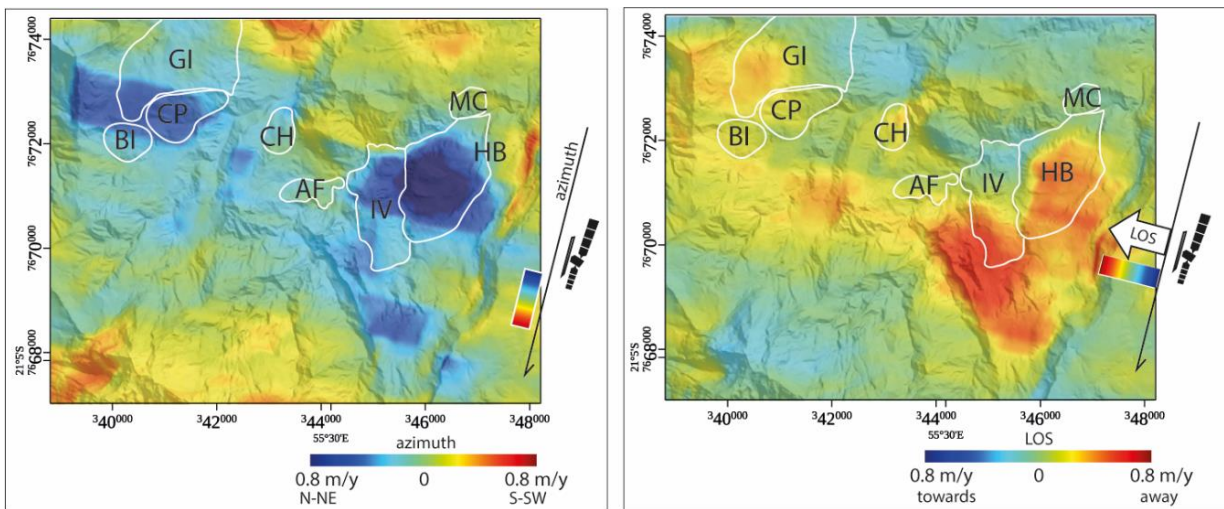
240 **Figure 2.** Left: InSAR velocity map in the LOS of the satellite, using the descending mode. A ground displacement  
 241 pattern is clearly visible in the Hell-Bourg area. Right: InSAR signal coherence. Coherence values lower than 0.3 are  
 242 masked in the left panel.

243

244 **3.2 Offset tracking Azimuth and Range**

245 We show the OT results in Figure 3. Because OT is a subpixel correlation technique, its precision depends on the  
 246 image pixel size. Nominally, the correlator implemented into the GAMMA processing chain is as precise as 1/10<sup>th</sup>  
 247 of the pixel size (e.g. Raucoules *et al.*, 2019). Therefore, because the MLI pixel size is 8.2 m in the azimuth  
 248 direction and 7.9 m in the range directions, we can expect precisions of the orders of 0.8 m in a single correlogram.  
 249 Thus, we cannot use OT to measure ground motions smaller than 0.8 m on a single correlogram. The precision  
 250 increases by applying the stacking procedure. Moreover, the stacking procedure can compensate the component  
 251 of the pixel offsets that may be caused by non-zero baselines between Sentinel 1 orbits, which is proportional to  
 252 topography. Furthermore, OT does not have higher limits for ground motion detection. This latter characteristic is  
 253 particularly helpful in CdS, where metric ground motion is expected, particularly within the HB area.

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255

256

*Figure 3. Azimuth (left) and LOS (right) OT velocity maps.*



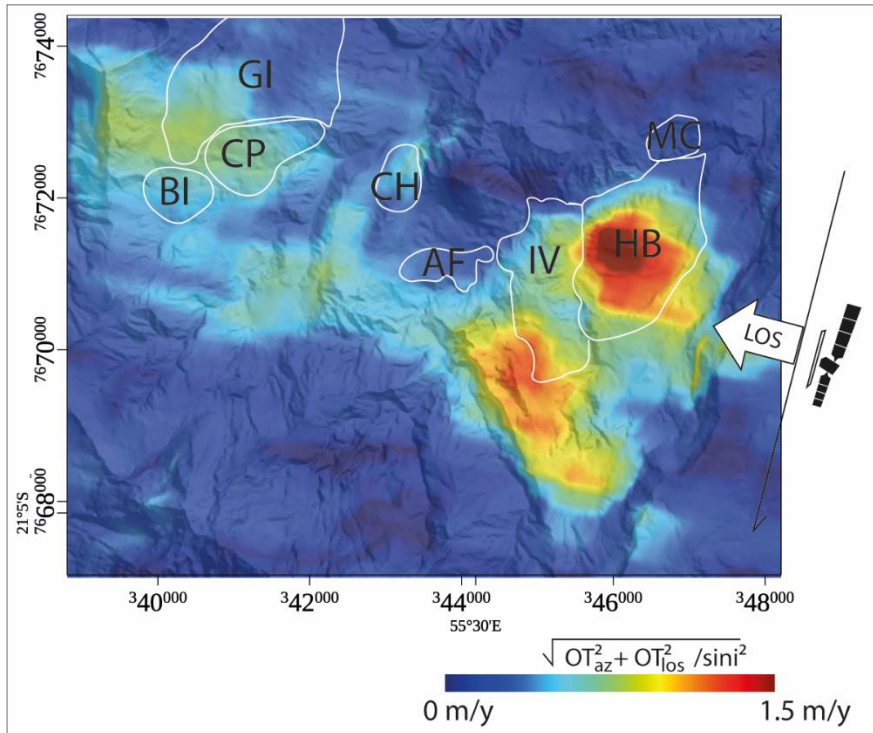
257 The first observation from Figure 3 is that the OT stacking procedure applied to Sentinel 1 MLIs provides  
 258 meaningful results, both in the azimuth and slant range directions. From Figure 3, we find that the fastest ground  
 259 motion in the azimuth direction is localized on the Hell Bourg landslide, N-NW section of the IV landslide, and  
 260 Camp Pierrot (CP) landslide. Ground motion in Hell Bourg can reach 1 m/yr in the azimuth direction. The OT  
 261 signal in the azimuth direction is also visible on a central section of the CP and IV landslides, as fast as 0.7 m/yr.  
 262 In the slant range direction, the OT ground motion signal is localized in the HB landslide, reaching 0.8 m/yr, away  
 263 from the satellite. Figure 3 highlights motion on the S-SE sections of the GI and IV landslides. We also observe  
 264 an unexpected pattern of ground motion S-SE of HB and south of IV, that was consistent with the geomorphology  
 265 of the area but situated in a non-instrumented, uninhabited area on the ground. This signal is intriguing and must  
 266 be validated against *in situ* observations.

267 To further investigate this latter signal, we considered the horizontal component of LOS motion only, combined  
 268 with the azimuth velocities, to extract OT horizontal ground velocities regardless of the motion direction. The  
 269 hypothesis holds in CdS because the horizontal motion (in HB for instance) is almost 7 times larger than the  
 270 vertical velocity. Therefore, we applied :

$$271 \quad |v_h| = \sqrt{OT_{az}^2 + (OT_{LOS}/\sin i)^2}, \quad (2)$$

272 to extract the horizontal velocity map,  $|v_h|$ , where  $i$  is the satellite viewing angle ( $37^\circ$  in this case study),  $OT_{AZ}$  is  
 273 the azimuth OT and  $OT_{LOS}$  is the range OT (Figure 4). Figure 4 shows that the OT detectable ground motion is  
 274 concentrated in the HB, IV, and south of IV landslides. There is also a weaker but noticeable ground motion signal  
 275 at the GI and CP landslides. Moreover, there is a marked signal S-SE of IV.

276



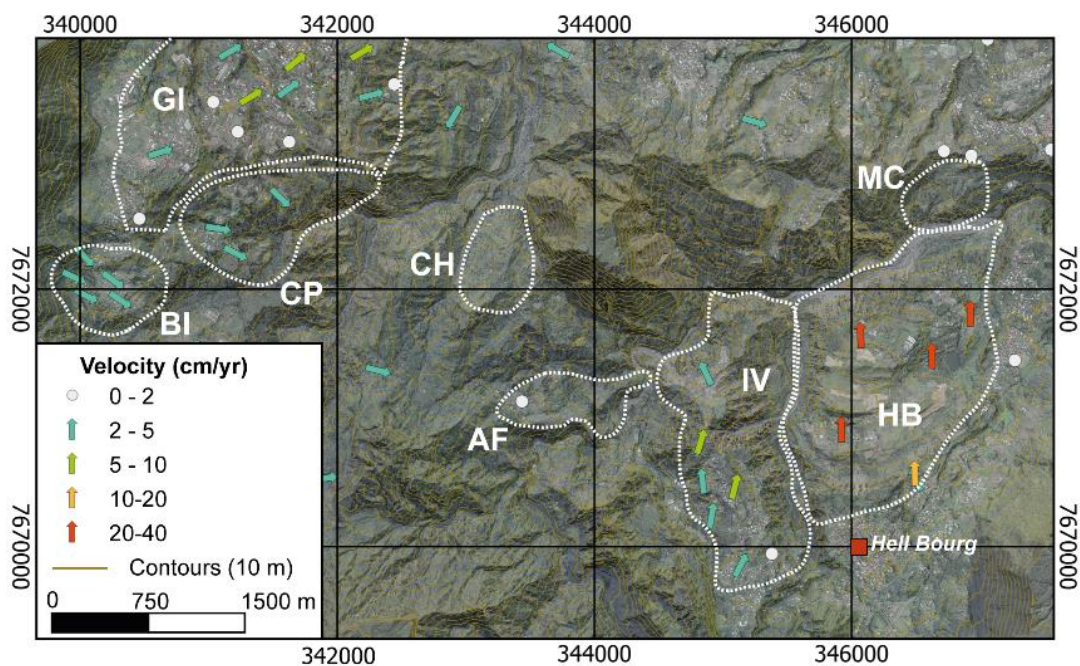
277

278 **Figure 4. Amplitude of the OT horizontal ground velocities independent of direction. We consider only the horizontal**  
 279 **component of LOS :  $\sqrt{OT_{az}^2 + OT_{los}^2 / \sin^2 i}$ .  $i$  is the LOS viewing angle ( $37^\circ$ ). The hypothesis is that the horizontal**  
 280 **motion in CdS (in HB for instance) is almost 7 times larger than the vertical velocity.**

281

282 **4. Comparison with global navigation satellite system (GNSS) data**

283 To gain some insight into the accuracy of SAR velocities maps, we performed a cross-comparison with GNSS  
 284 campaigns available at CdS. In this exercise, we compared SAR velocities with GNSS velocities acquired over  
 285 the time span May 2018 - February 2020. The GNSS velocities were calculated using 93 geodetic markers across  
 286 the cirque (Figure 5). They were obtained from the position of the markers measured with a differential GNSS  
 287 during two campaigns of measurements: May 2018 and January 2020.



288

289 **Figure 5. Locations and horizontal velocities of GNSS campaigns. Velocities refers to campaigns in May 2008 and**  
 290 **January 2020.**

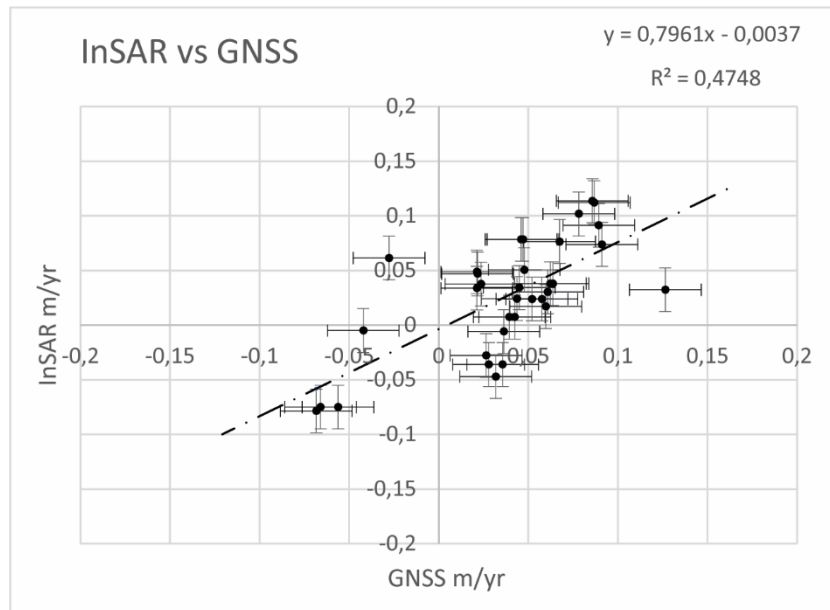
291

292 GNSS measurement accuracy varies from one site to another depending on environmental factors (e.g., vegetation,  
 293 proximity to buildings, cirque cliffs, and steep ramparts). For each campaign of measurement, the position of a  
 294 benchmark was measured four successive times. The final position of the benchmark is the average of these four  
 295 measurements. Measurements with deviations of more than 5 cm in altimetry and 3 cm in planimetry were removed  
 296 from the dataset. The positioning accuracies are of the order of 2 cm in planimetry and less than 5 cm in altimetry  
 297 (Mazué et al., 2013).

298 To compare GNSS and SAR velocities (both InSAR and OT), we must project the GNSS x, y, and z values into  
 299 LOS (= OT range) and OT azimuth direction, by considering that Sentinel 1 has a heading of  $-167.66^\circ$  South with  
 300 a look angle of  $36.93^\circ$ . We then obtained  $GNSS_{sar}$  values in LOS, range and azimuth direction. Then, we discretized

301 the GNSS<sub>sar</sub> values into a number of intervals of 0.03 m width. For each interval, we calculated the median and  
302 identified the geographic location of each point in the interval. At those points, we extracted median GNSS<sub>sar</sub> and  
303 SAR values. Then, we plotted GNSS<sub>sar</sub> *versus* SAR for each interval. The results are scatterplots showing GNSS  
304 (LOS) vs InSAR (Figure 6) and GNSS (range; azimuth) vs SAR OT (range, azimuth) in Figure 7.

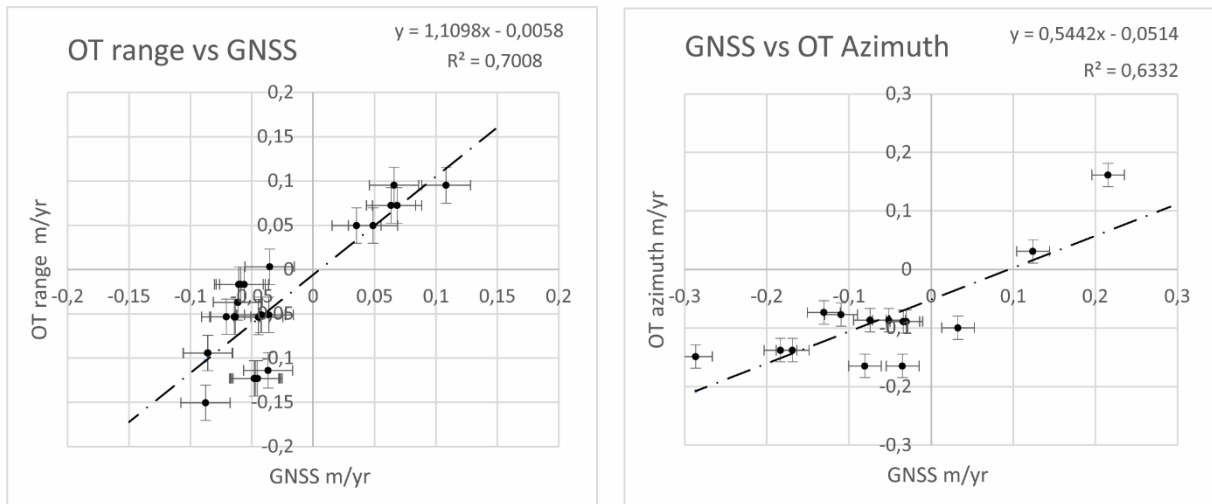
305 From Figure 6, we see that the comparison between InSAR velocities and GNSS<sub>sar</sub> velocities is satisfactory.  
306 However, there was a general underestimation of motion for the InSAR technique (i.e., InSAR=0.8xGNSS). This  
307 may be due to an uncompensated residual ramp in the InSAR velocity map.



308  
309 **Figure 6. InSAR VS GNSS (LOS) data (m/yr). InSAR is not sensitive to velocities higher than 2 cm/yr. Therefore, we**  
310 **mask all values that are related to GNSS values higher than |2| cm per year.**

311  
312 In Figure 7, we show the comparison between GNSS<sub>sar</sub> and OT velocities in range and azimuth directions. We see  
313 that the comparison between SAR and GNSS<sub>sar</sub> velocities is good. There is a general underestimation of motion  
314 by the OT technique in the azimuth direction (i.e., OT<sub>azimuth</sub>=0.5xGNSS<sub>sar</sub>). This may be due to an  
315 uncompensated residual ramp in the OTs velocity maps.

316



317

318

319 **Figure 7. Left. GNSS<sub>sar</sub> vs OT in the range direction (m/yr). Right: GNSS<sub>sar</sub> vs OT in the azimuth direction (m/yr).**  
 320 **Masked GNSS values between ±3 cm per year**

321

322 **5. Discussion, conclusions, and perspectives**

323 In this study, we applied Sentinel 1 SAR analysis, both InSAR and OT, to the measurement of ground motion on  
 324 Cirque de Salazie, Reunion Island, France. Thanks to the high repetition frequency of Sentinel 1, the C-band  
 325 InSAR signal is coherent in this region, in contrast with past C-band studies on the study area. This result allows  
 326 us to produce interpretable velocity maps, both with InSAR and OT techniques. The InSAR velocity map provided  
 327 spatially detailed ground velocities in the LOS of the satellite, with precision reaching a fraction of the SAR  
 328 wavelength. The comparison between InSAR and GNSS velocities is satisfactory. The Sentinel 1 MLIs OT  
 329 technique provided useful measurements. Nevertheless, the comparison between OT and GNSS velocities  
 330 highlighted several biases that require a more detailed investigation. The biases may be due to a residual orbital  
 331 ramp in the OT velocities but also the fact that OT precision is a function of the MLI pixel size. Because the InSAR  
 332 and OT techniques provide “relative” measurements, the biases with respect to GNSS suggested that absolute  
 333 calibration of SAR maps is needed to compare SAR and GNSS results.

334 Within the InSAR and OT detection limits and the period of SAR measurements (October 2017–November 2018)  
 335 this study shows the ground motion and internal kinematics on HB landslide, the N-NW section of IV landslide,  
 336 and CP landslide. Moreover, we point out an unexpected pattern of ground motion S-SE of HB and South of IV,  
 337 consistent with the geomorphology of the area but situated in a non-instrumented, uninhabited area on the ground.  
 338 We suggest that it might correspond to an area that was considered stabilized or dormant, called Crete de Salaze.  
 339 Motion in this area might have been reactivated as a consequence of heavy rainfall and thus represents a post  
 340 cyclonic burst of ground motion.

341 Three GNSS sites on the South-Western part of IV landslides indicates ground motion in this sector of CdS.  
 342 Therefore, this noticeable signal requires further consideration and investigation.

343 We need precise time series of this ground motion, localized on those three specific areas, to discriminate whether  
344 we can highlight rheological changes due to the post-cyclonic activity.

345 There are rooms for methodological improvement:

346 Even though the Sentinel 1 ascending mode is less adapted in CdS due to shadow and layover effects depending  
347 on the look angle, it may be possible to exploit the few coherent pixels to extract the vertical and east-west  
348 components of ground displacement, by a combination of Sentinel 1 InSAR in ascending and descending modes.  
349 The exploitation of both InSAR and OT from Sentinel 1 and other SAR missions (e. g. ALOS 2, TerraSAR X)  
350 would improve data coverage, spatially and temporally. OT with Sentinel 1 data revealed precious to measure  
351 large ground motion in CdS. In this study, we calculated OT on MLIs 3-2; we could run an experiment to determine  
352 whether OT from MLIs 2-1 or even MLIs 1-1 could lead to more accurate results.

353 In conclusion, Sentinel 1 InSAR and OT present high potential for routine monitoring on CdS, as a complement  
354 to *in situ* techniques (i e., Rault et al., 2022). This study presented a solid premise for the future exploitation of the  
355 European Ground Motion Service (EGMS) of the European Union Copernicus program, based on Sentinel 1  
356 InSAR, in CdS.

357

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